

Kernelization Complexity of Solution Discovery Problems

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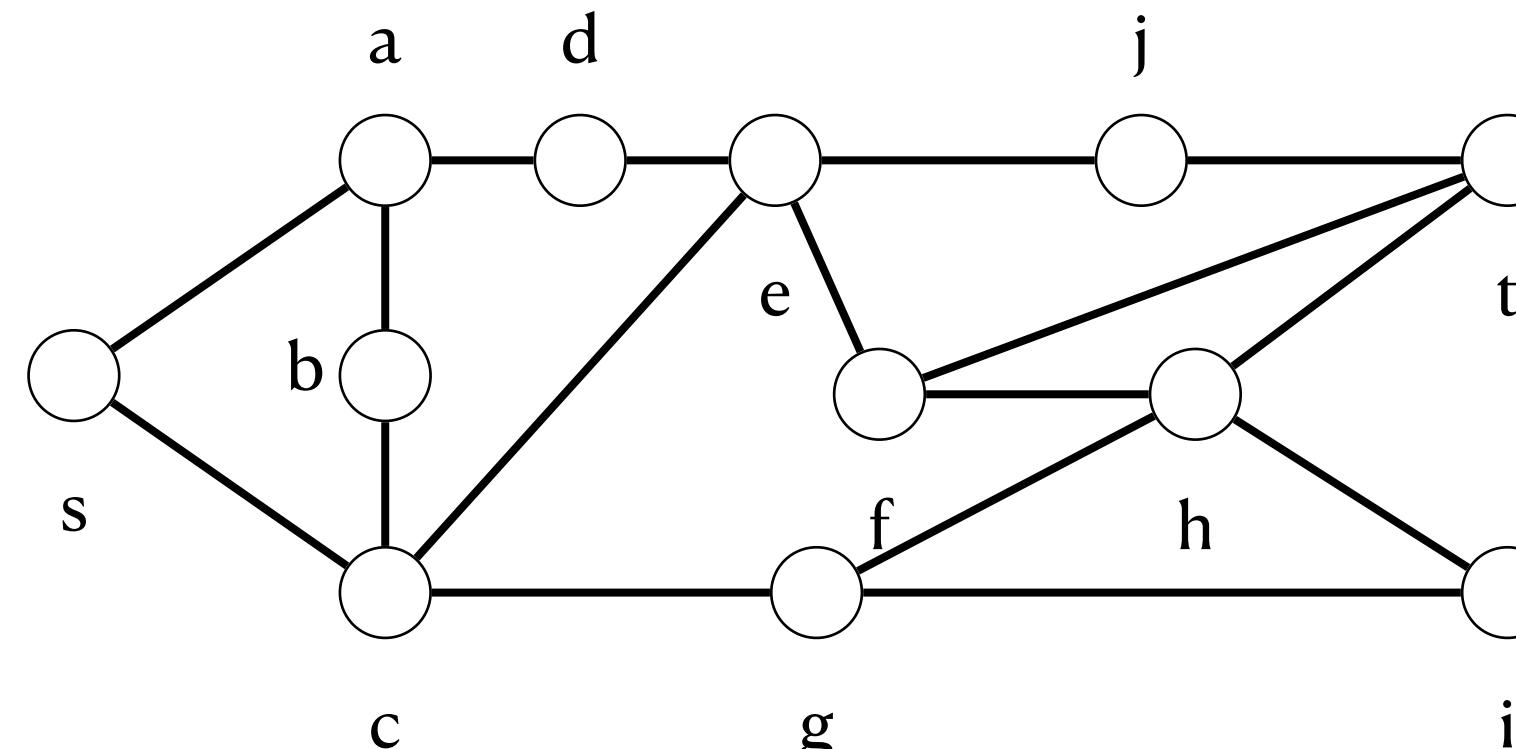
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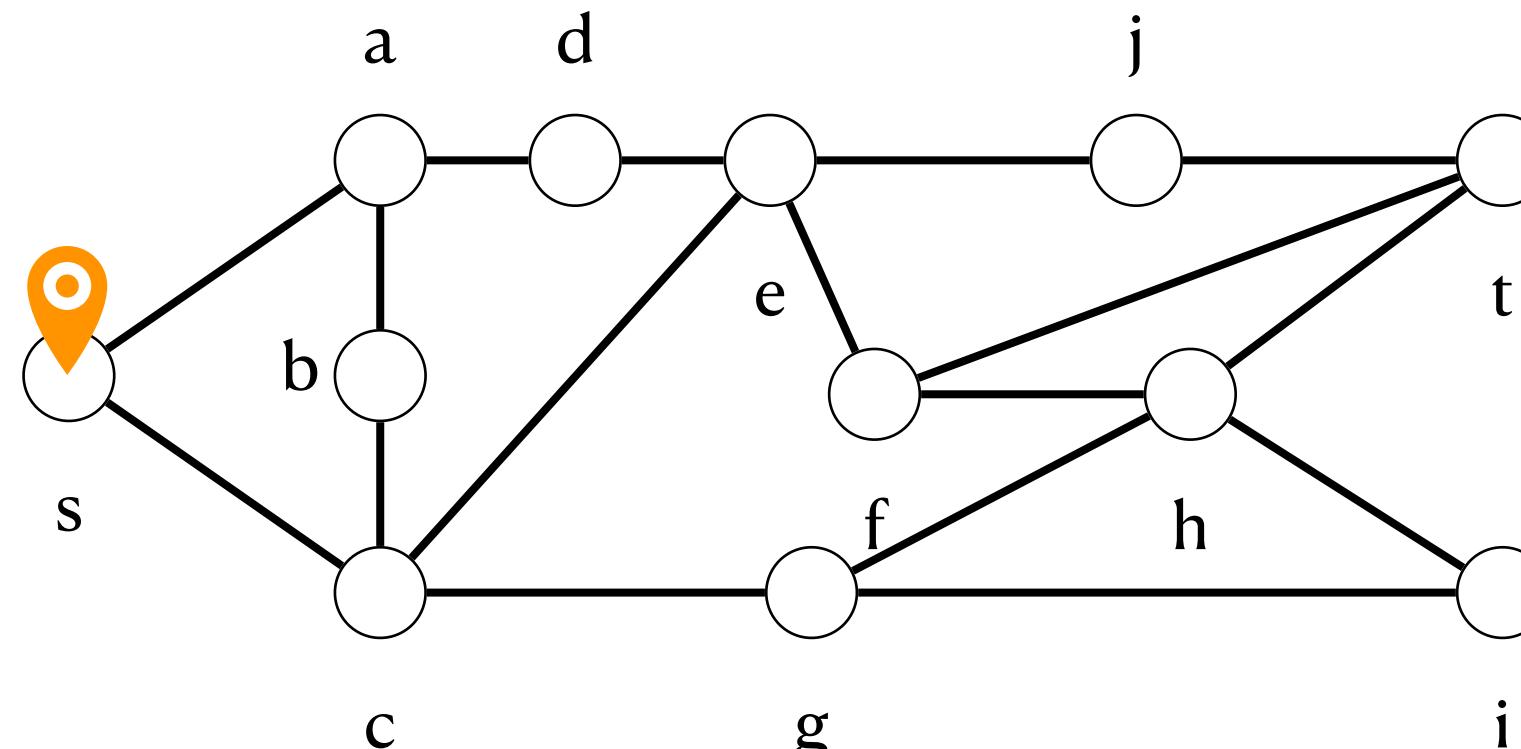
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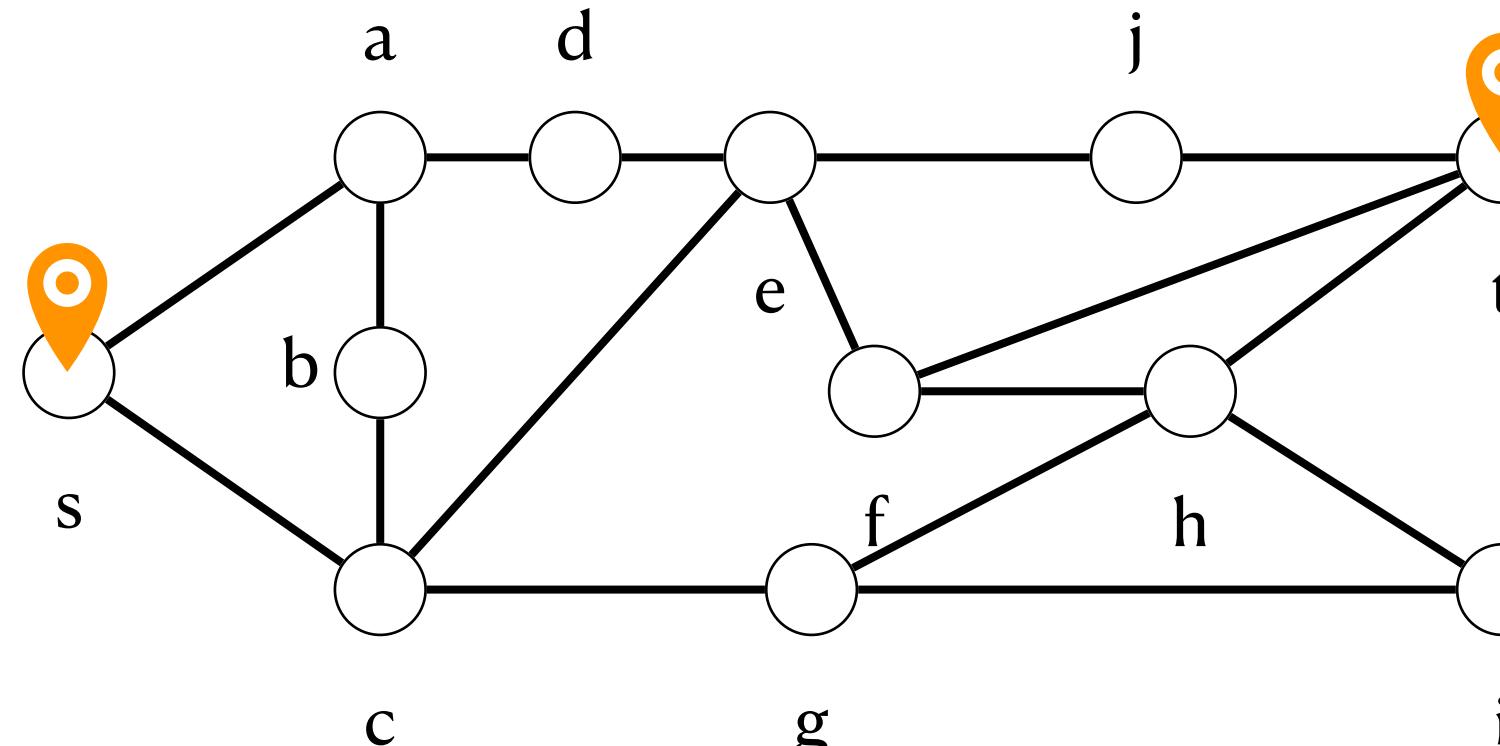
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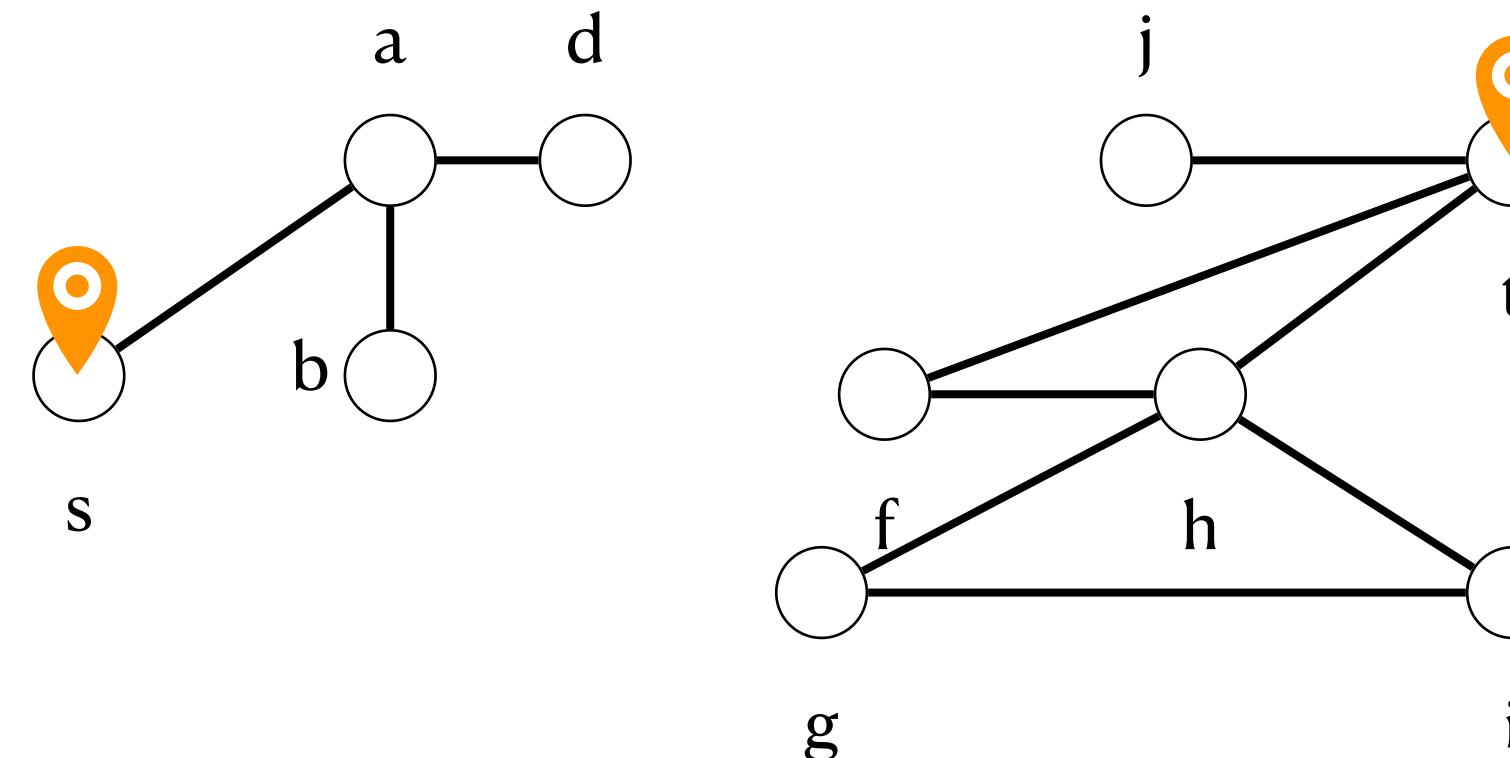
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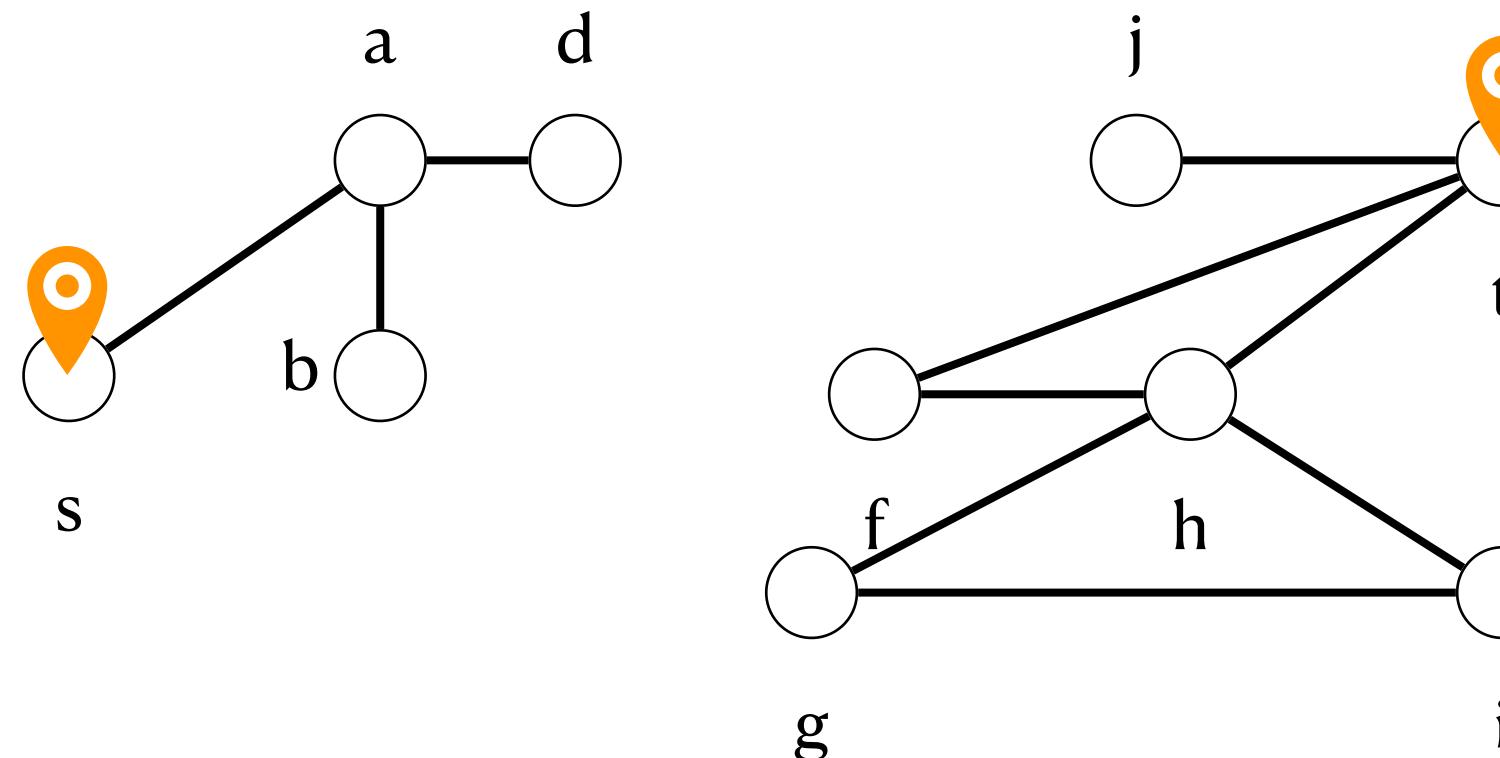
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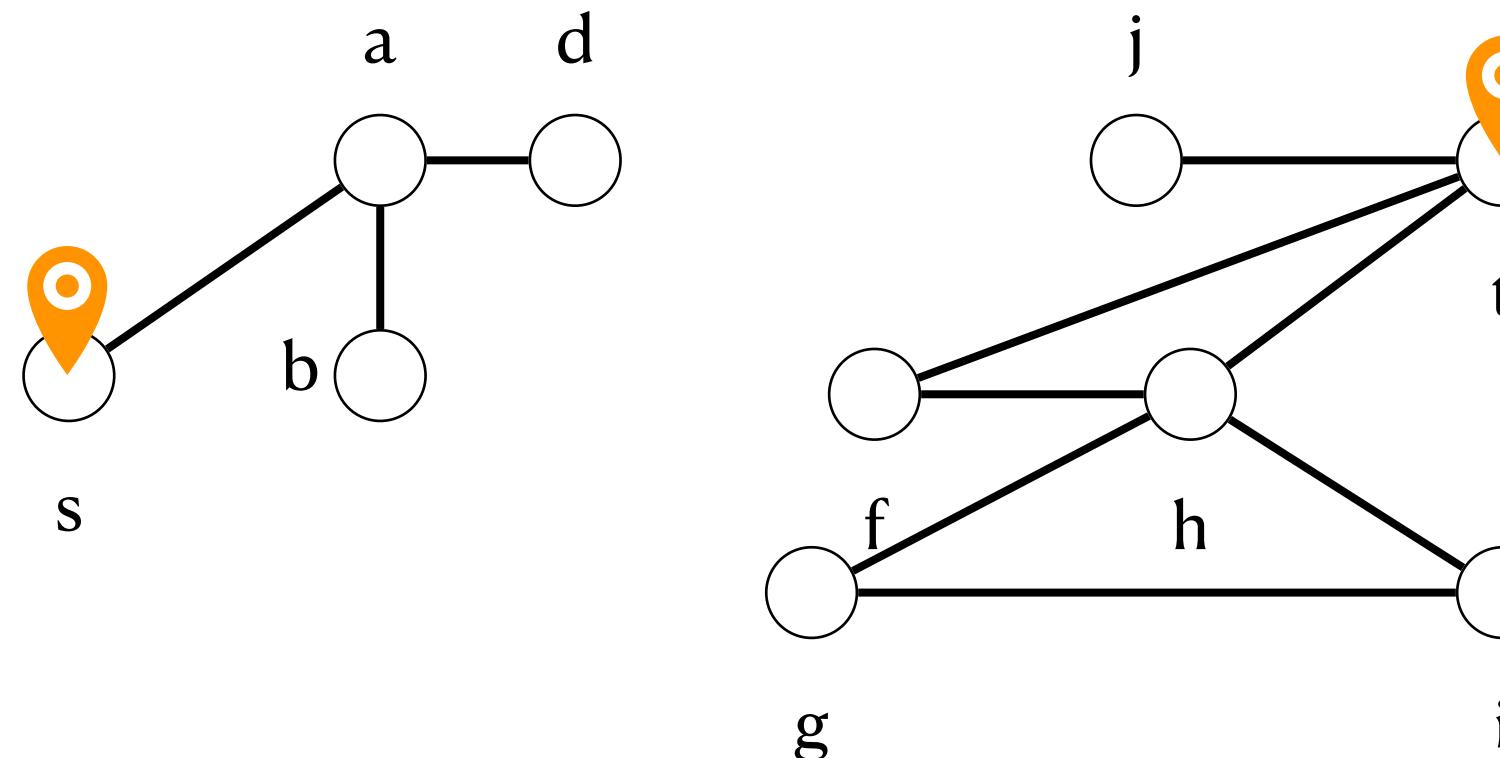
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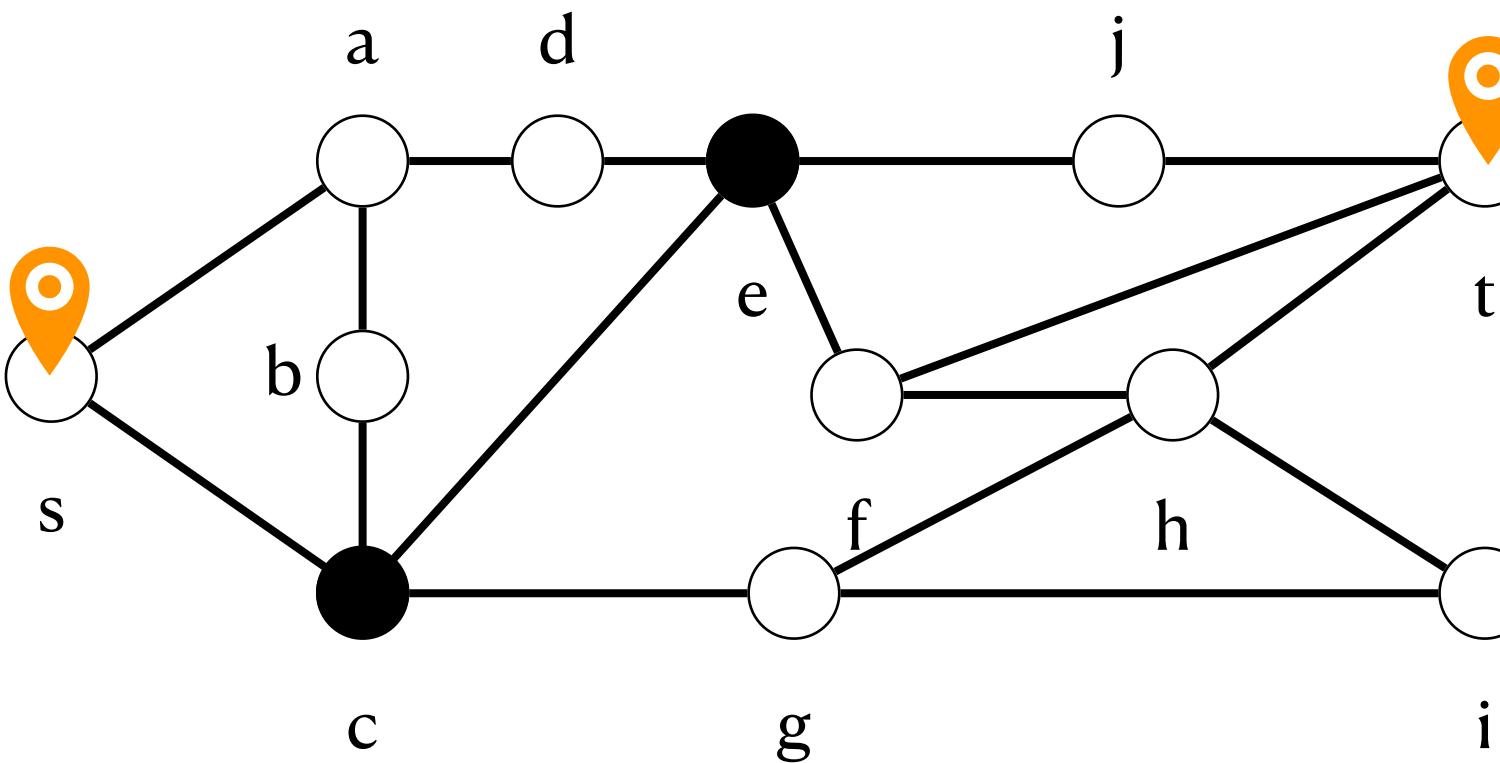


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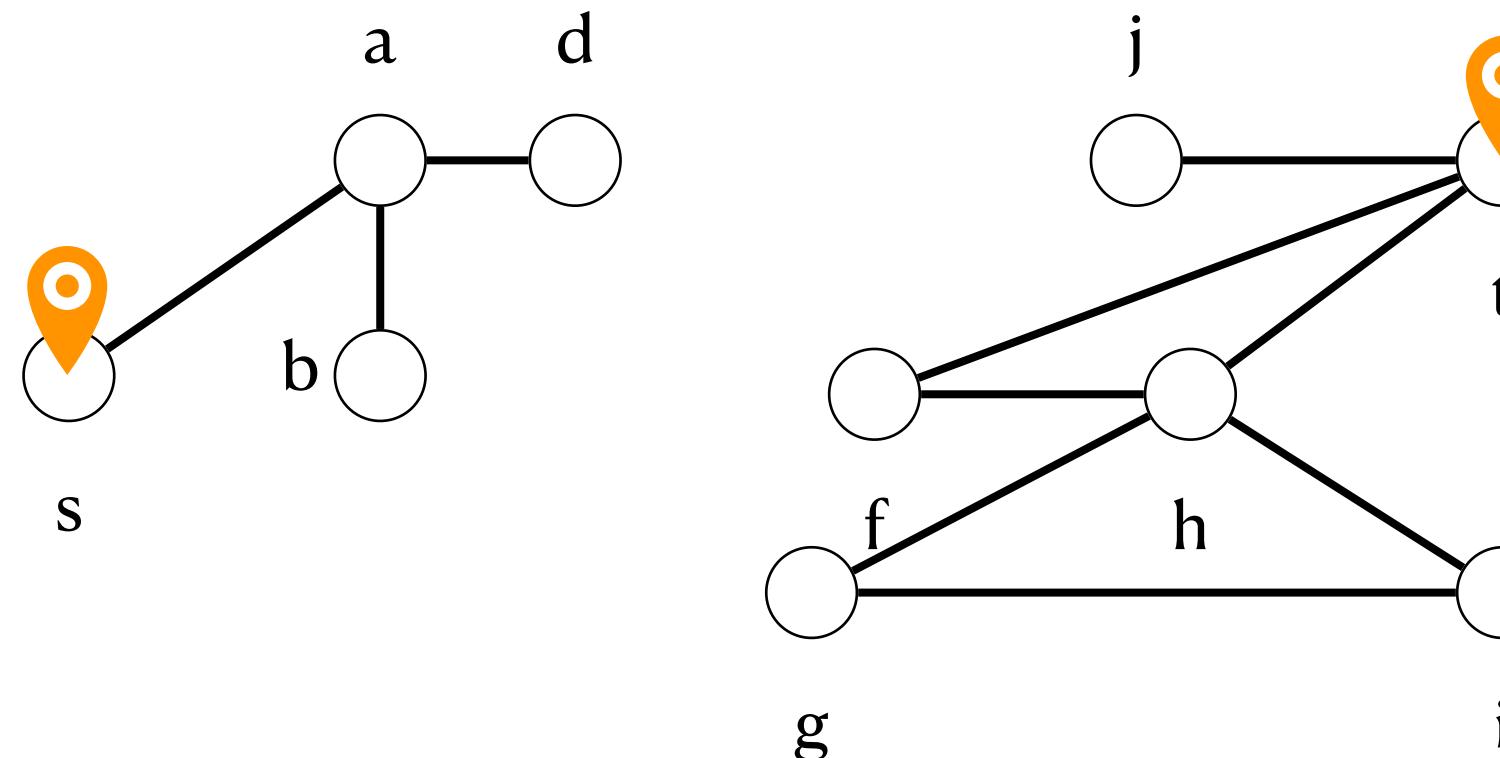
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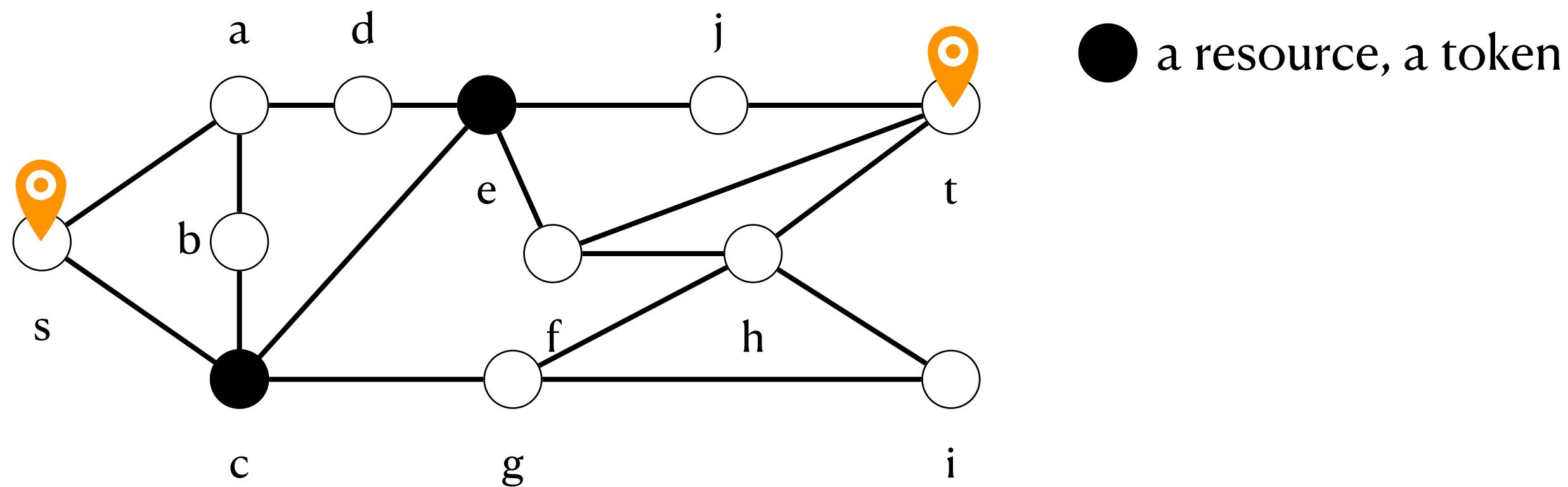
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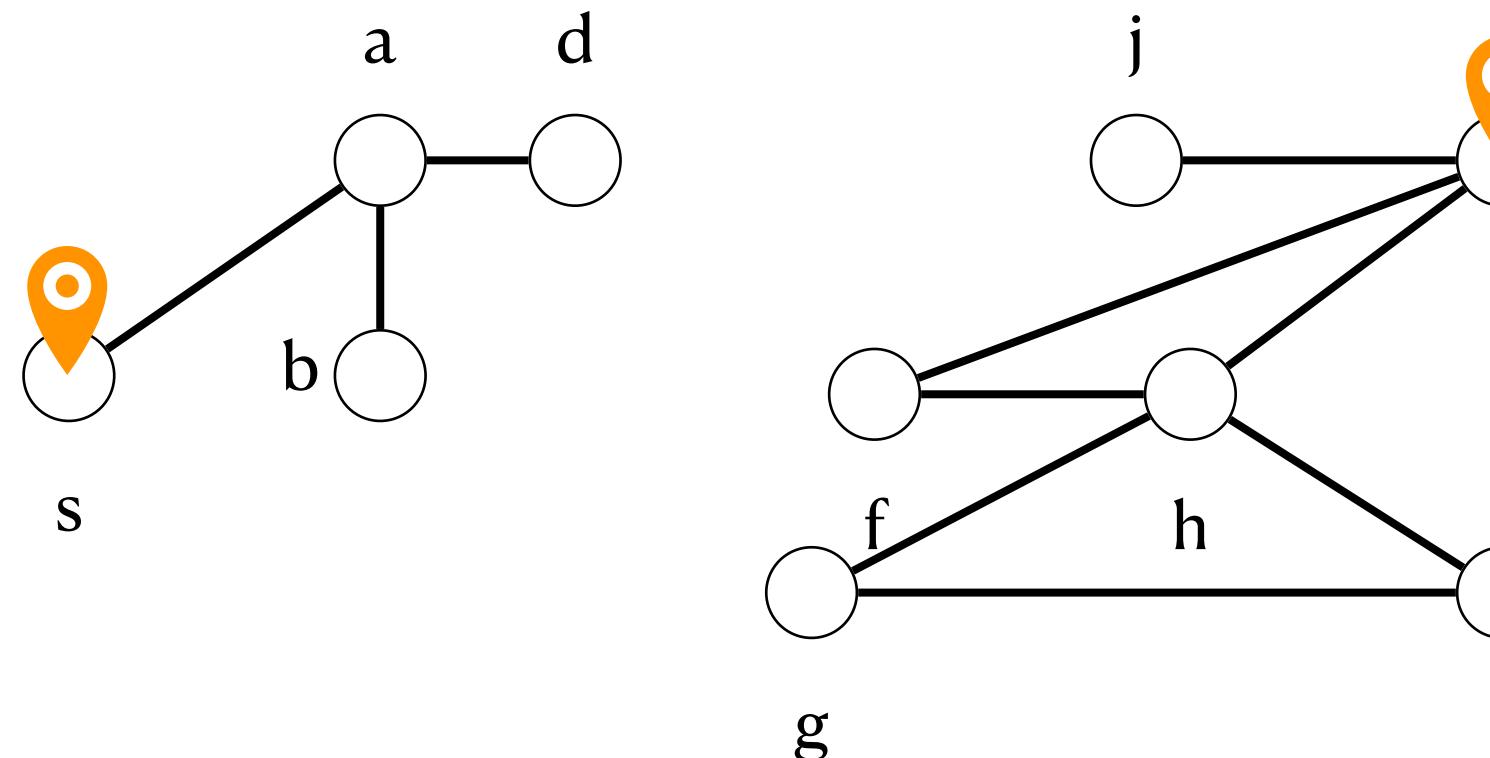
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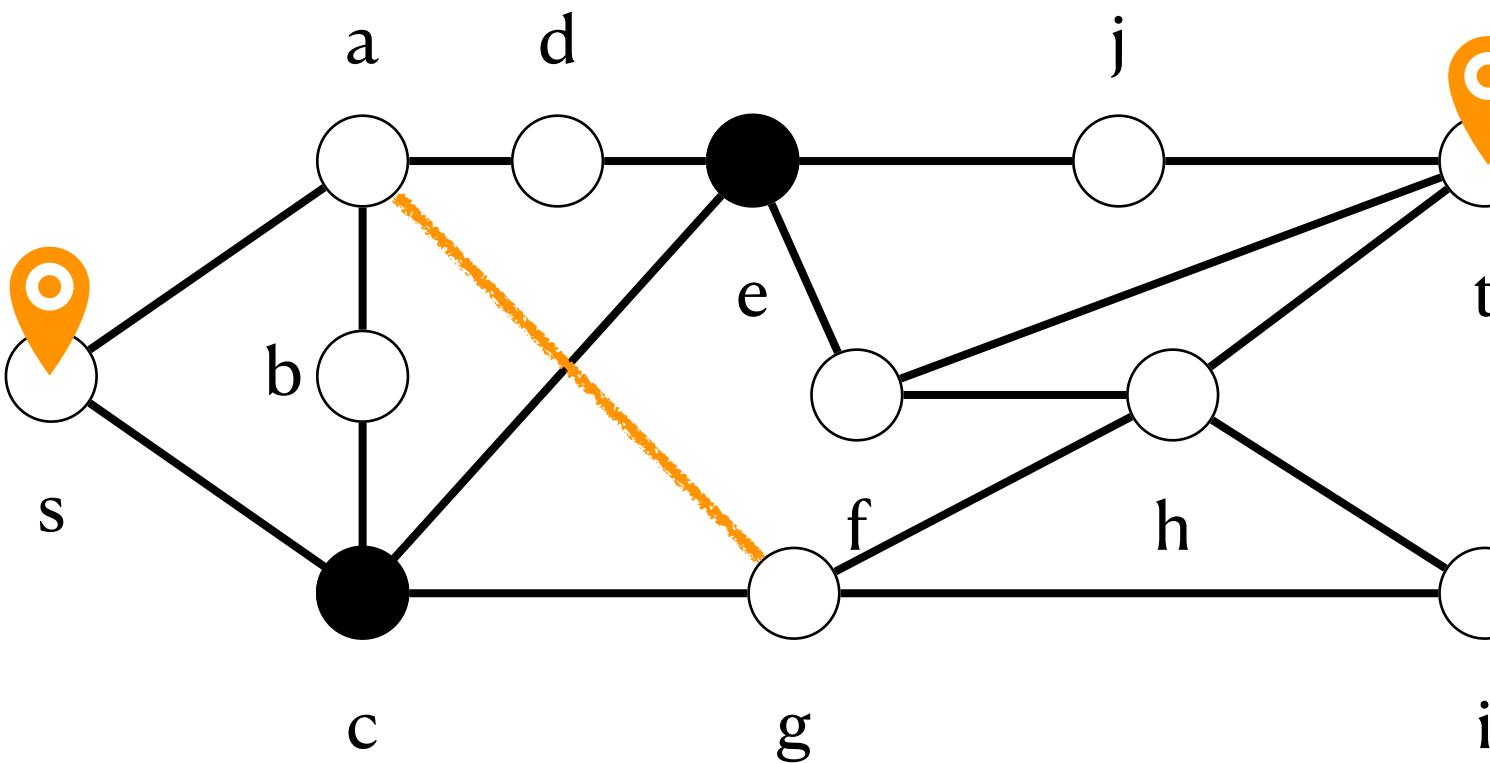
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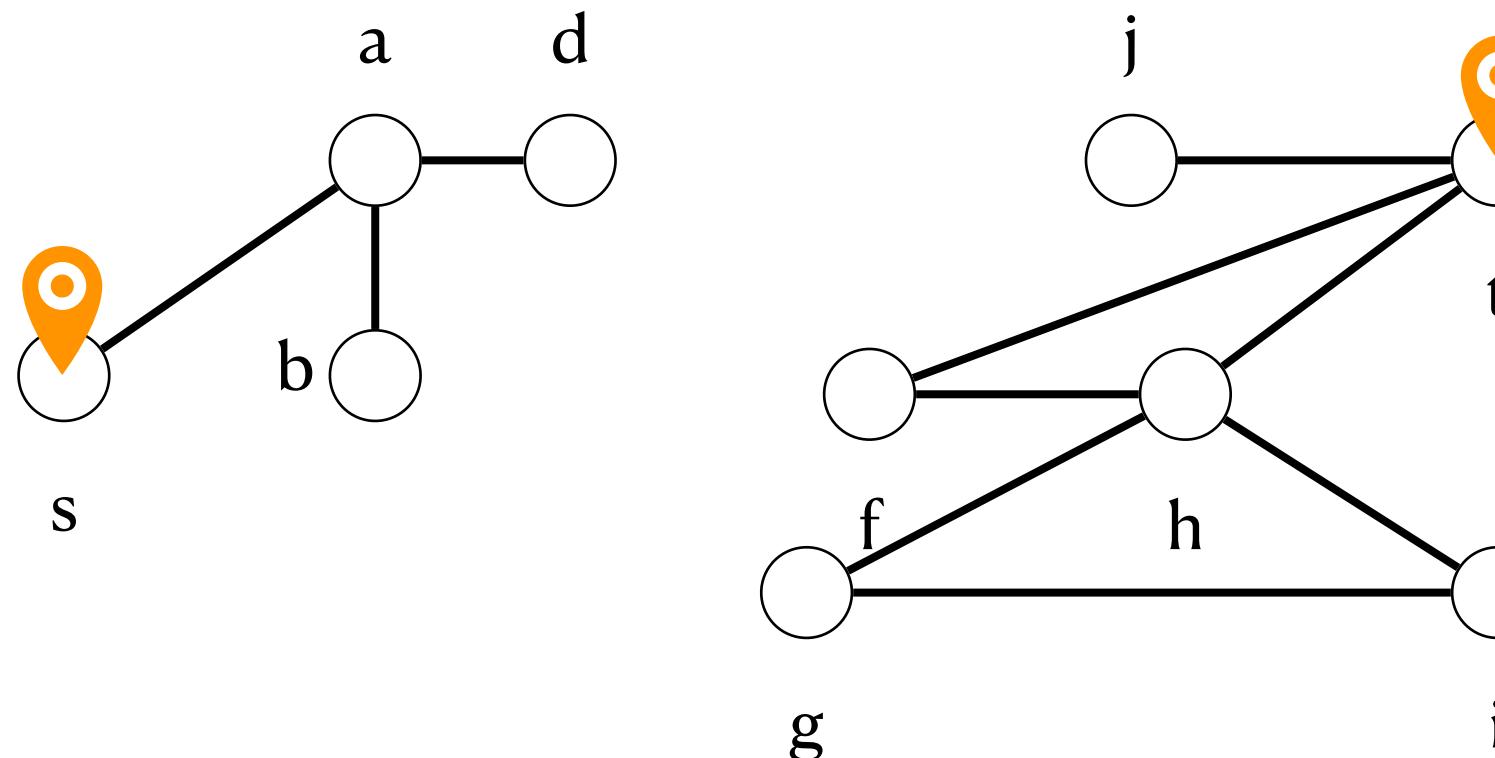


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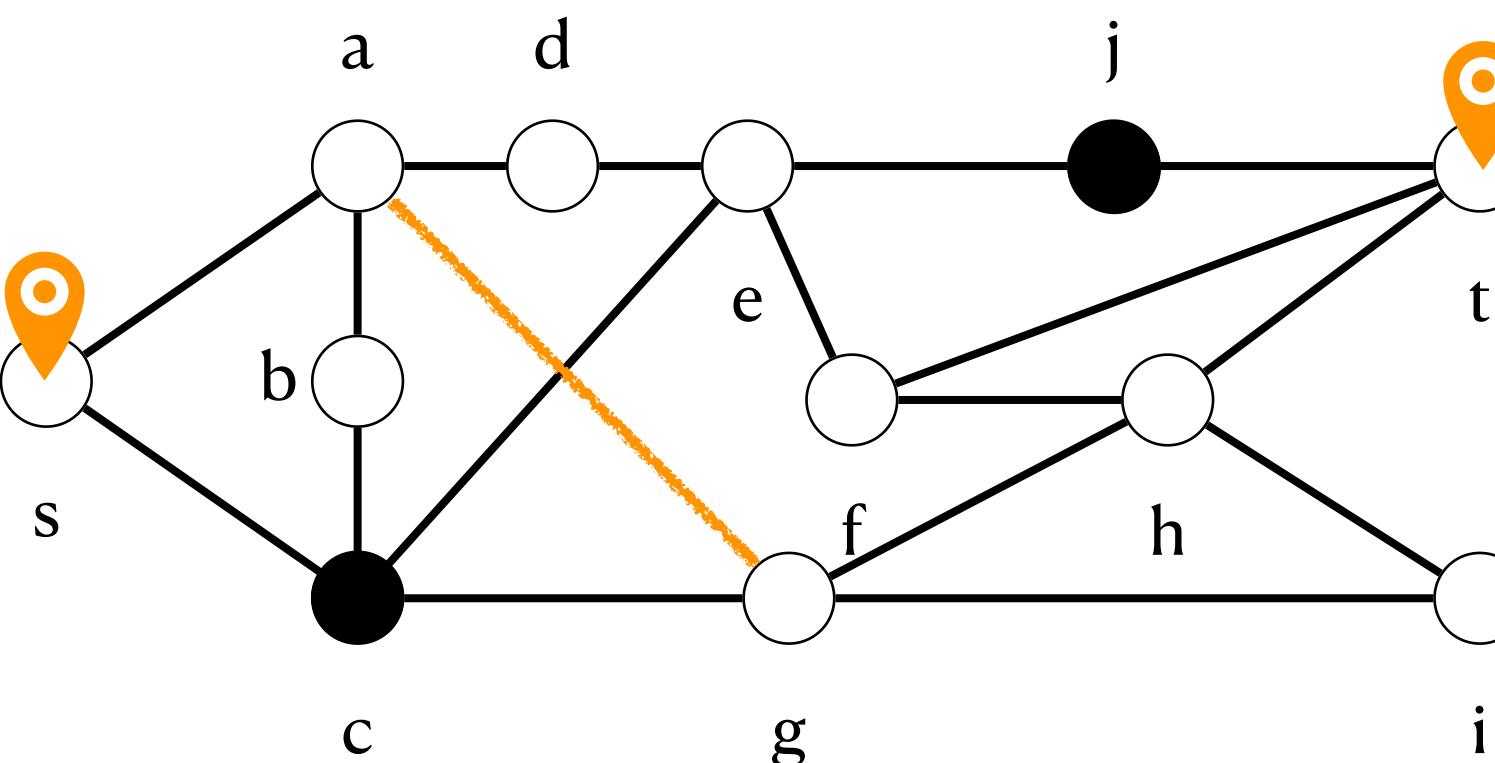


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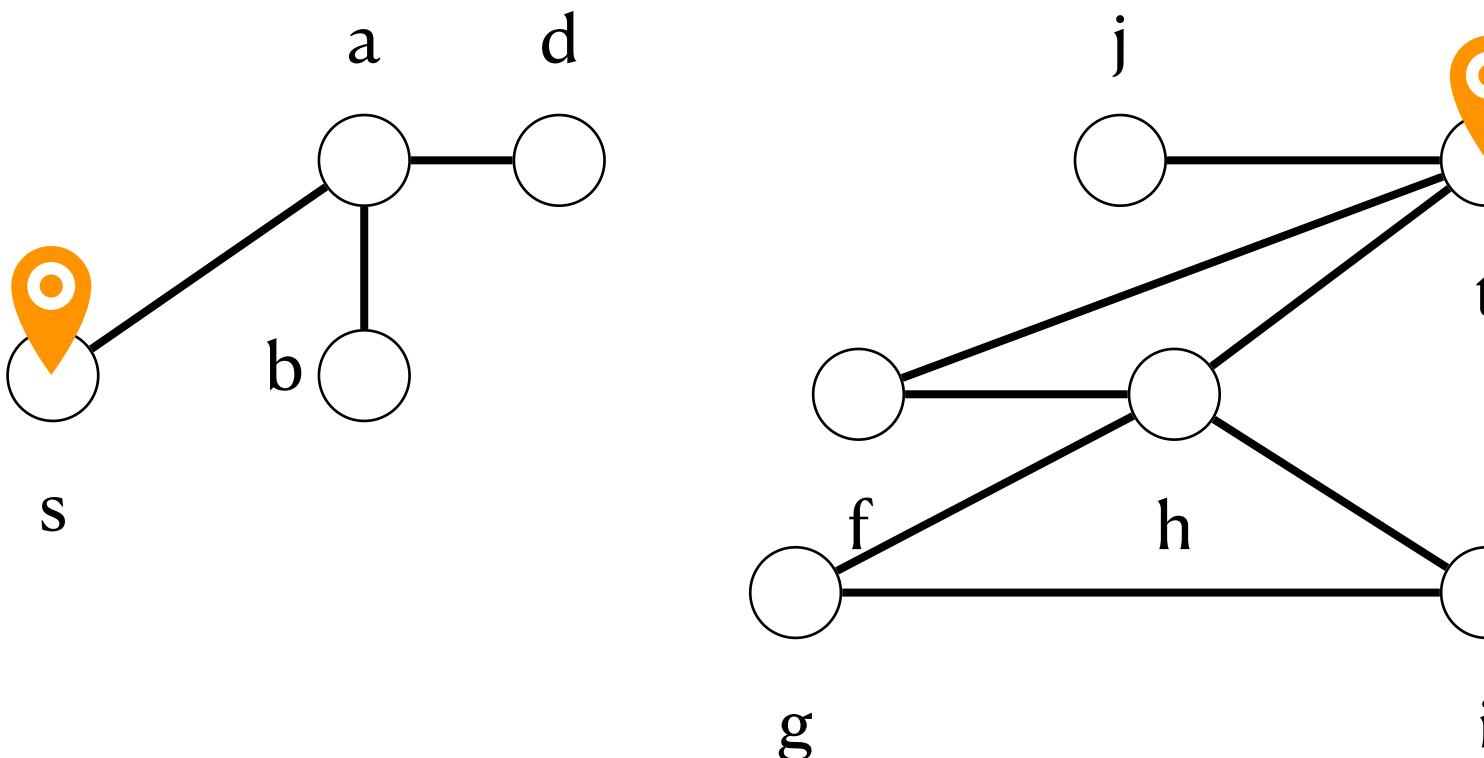
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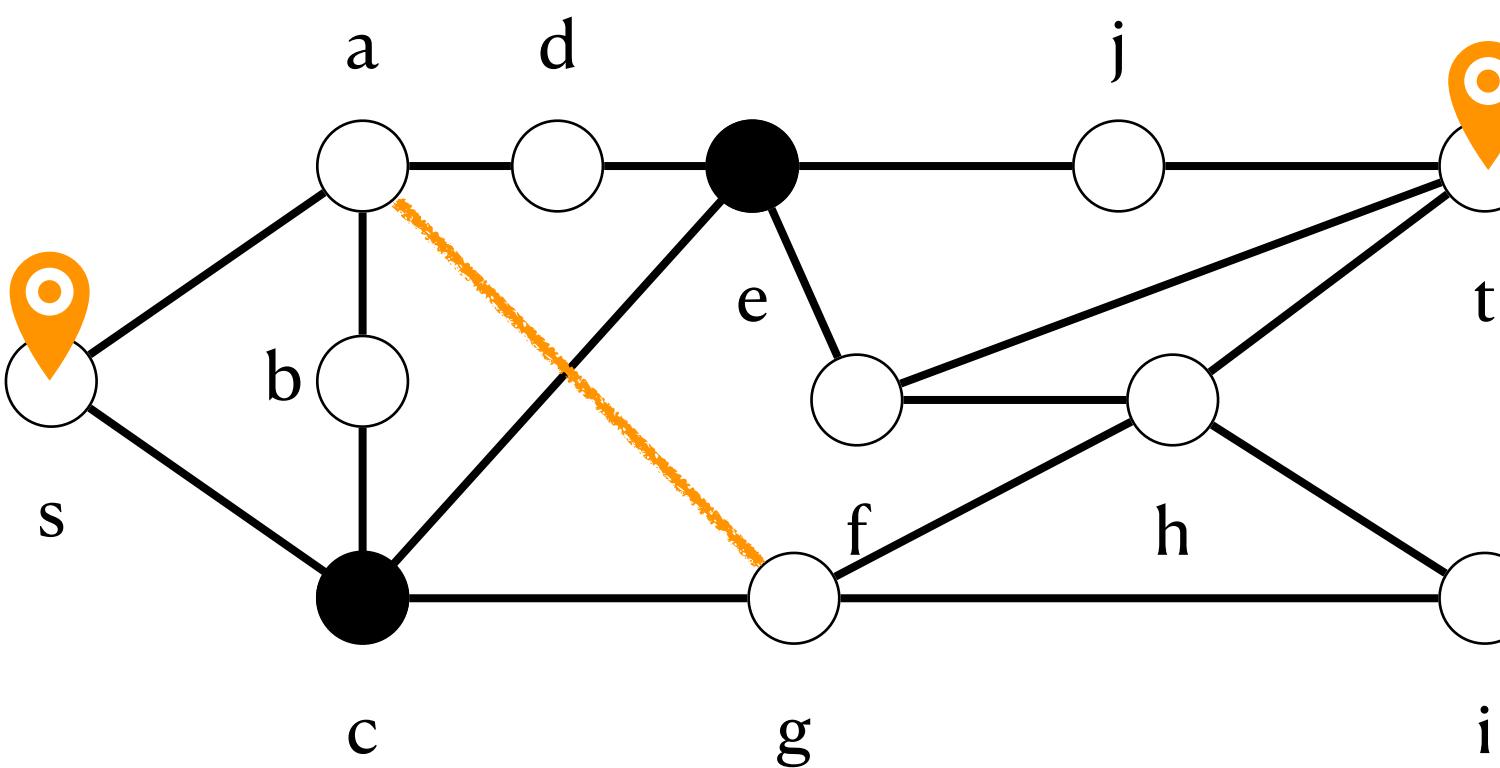
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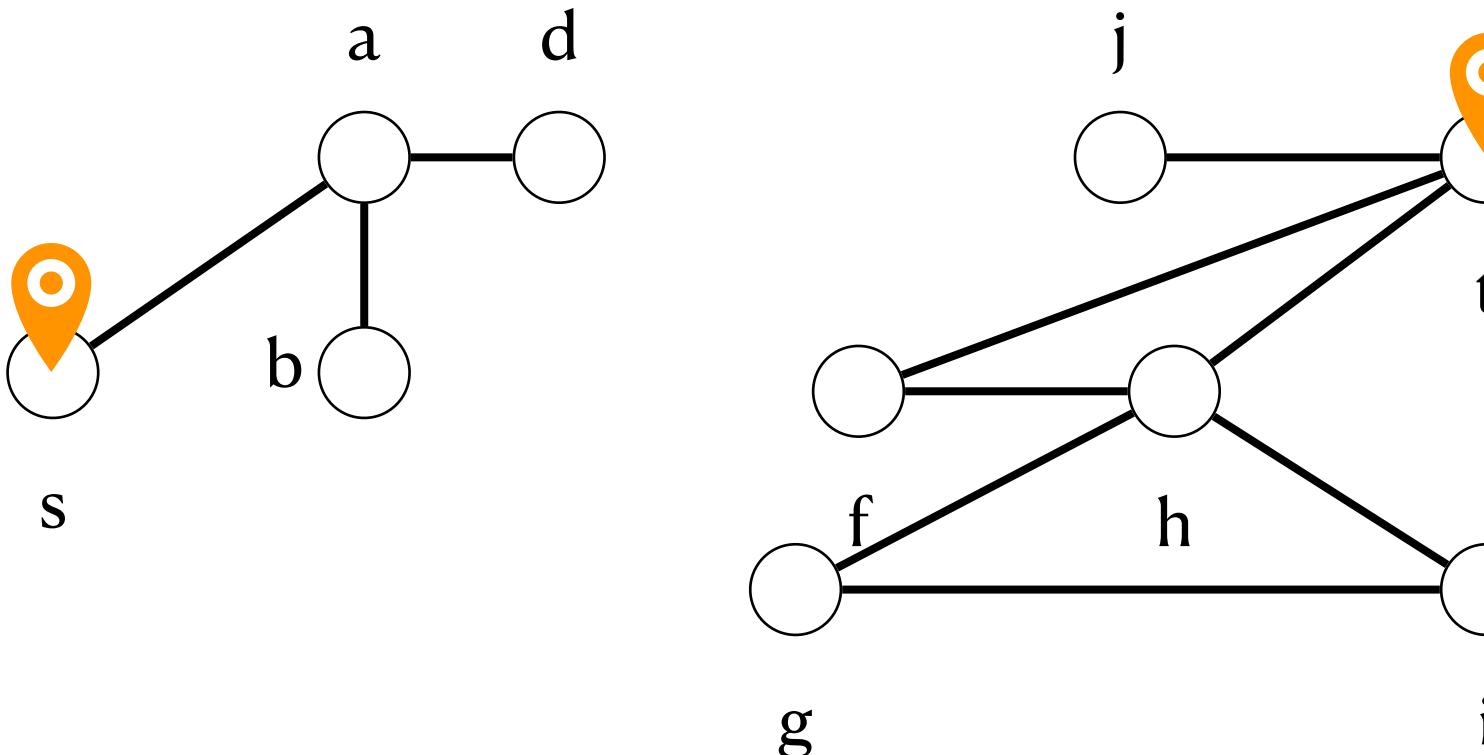


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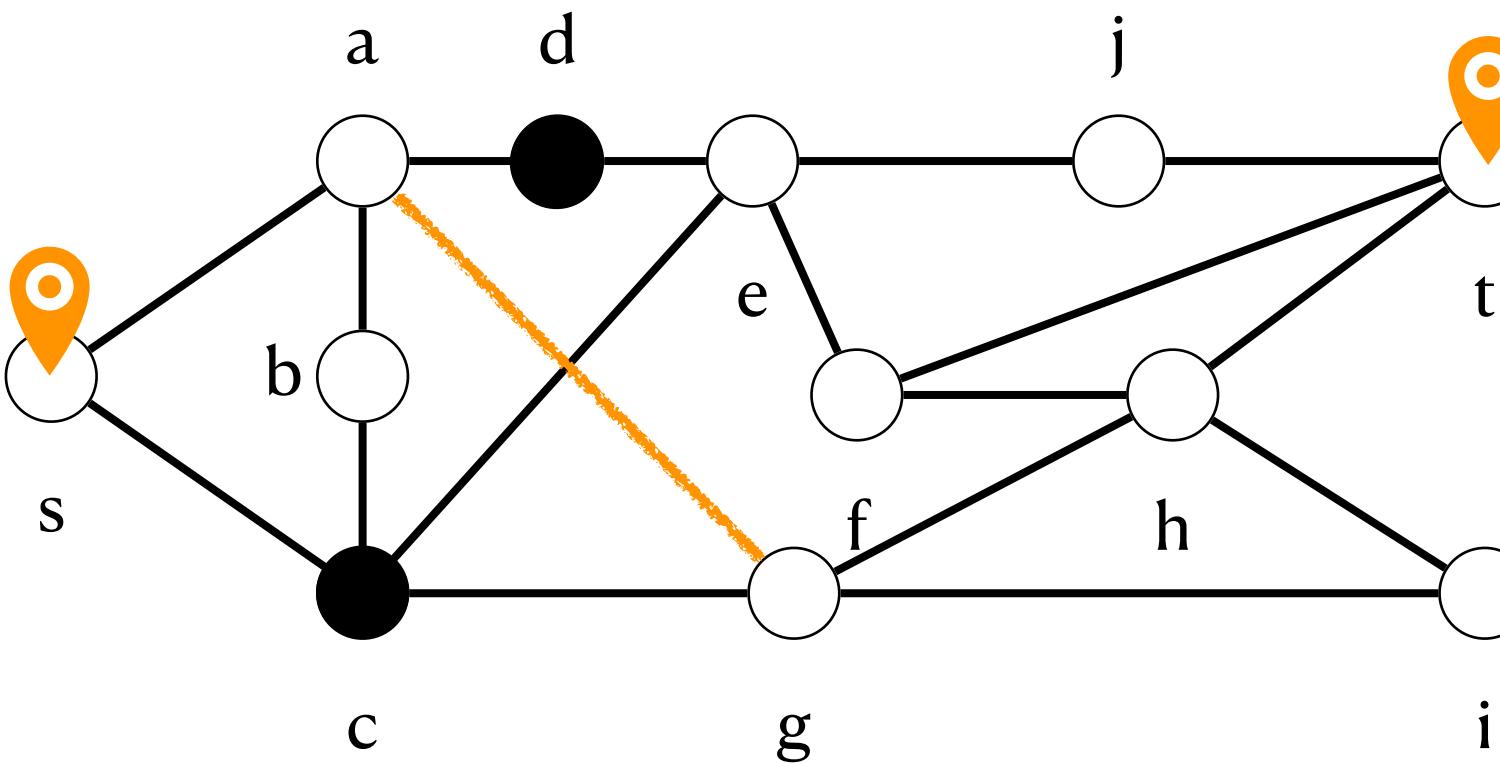


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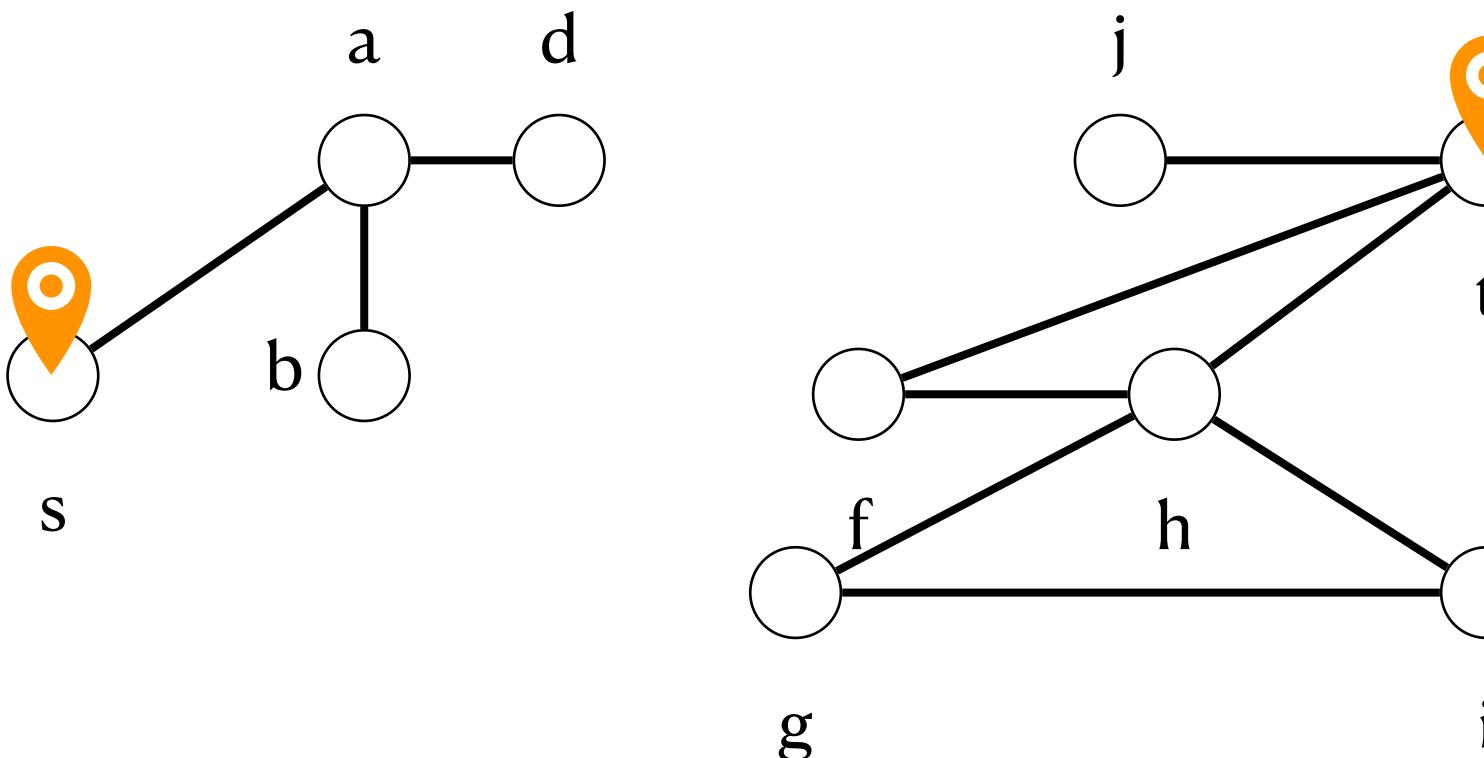


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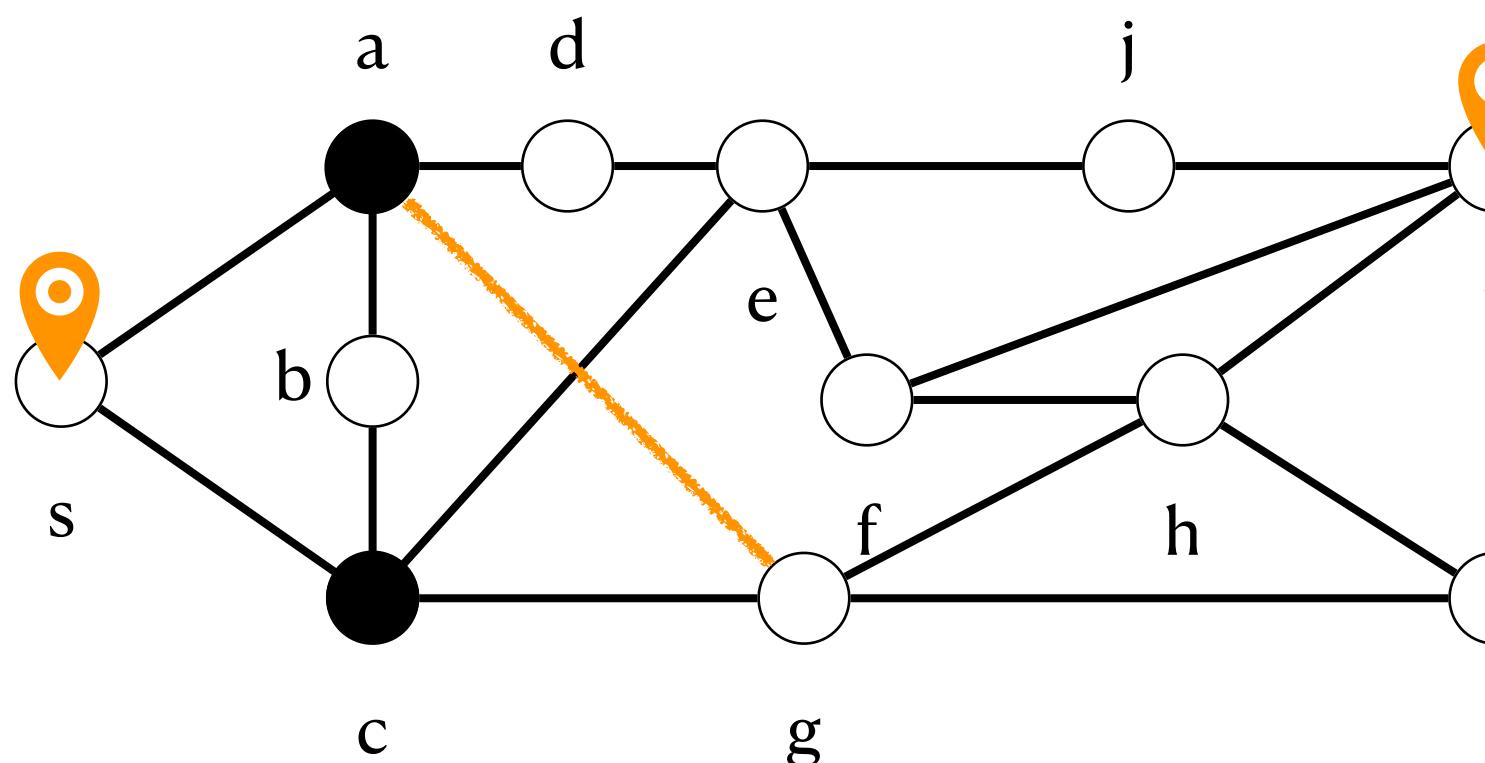


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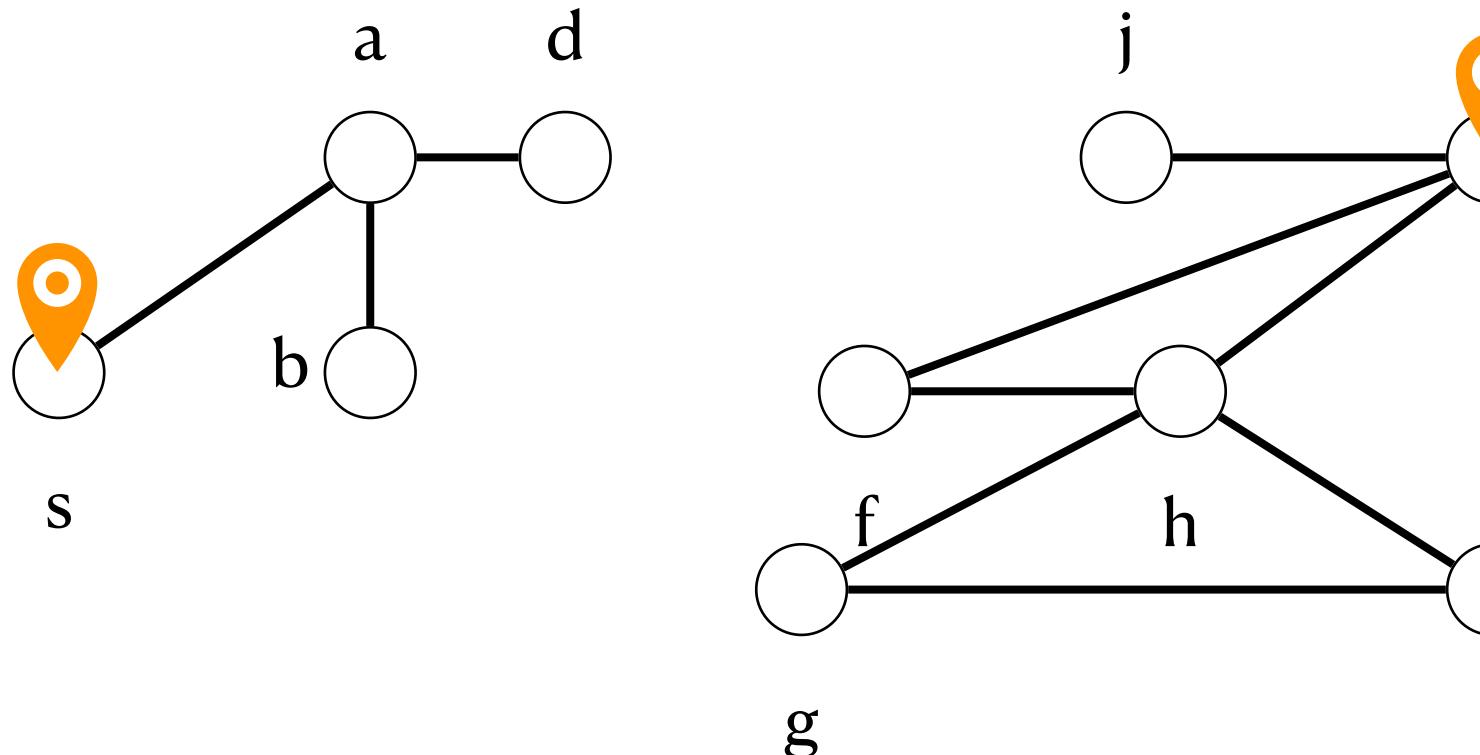
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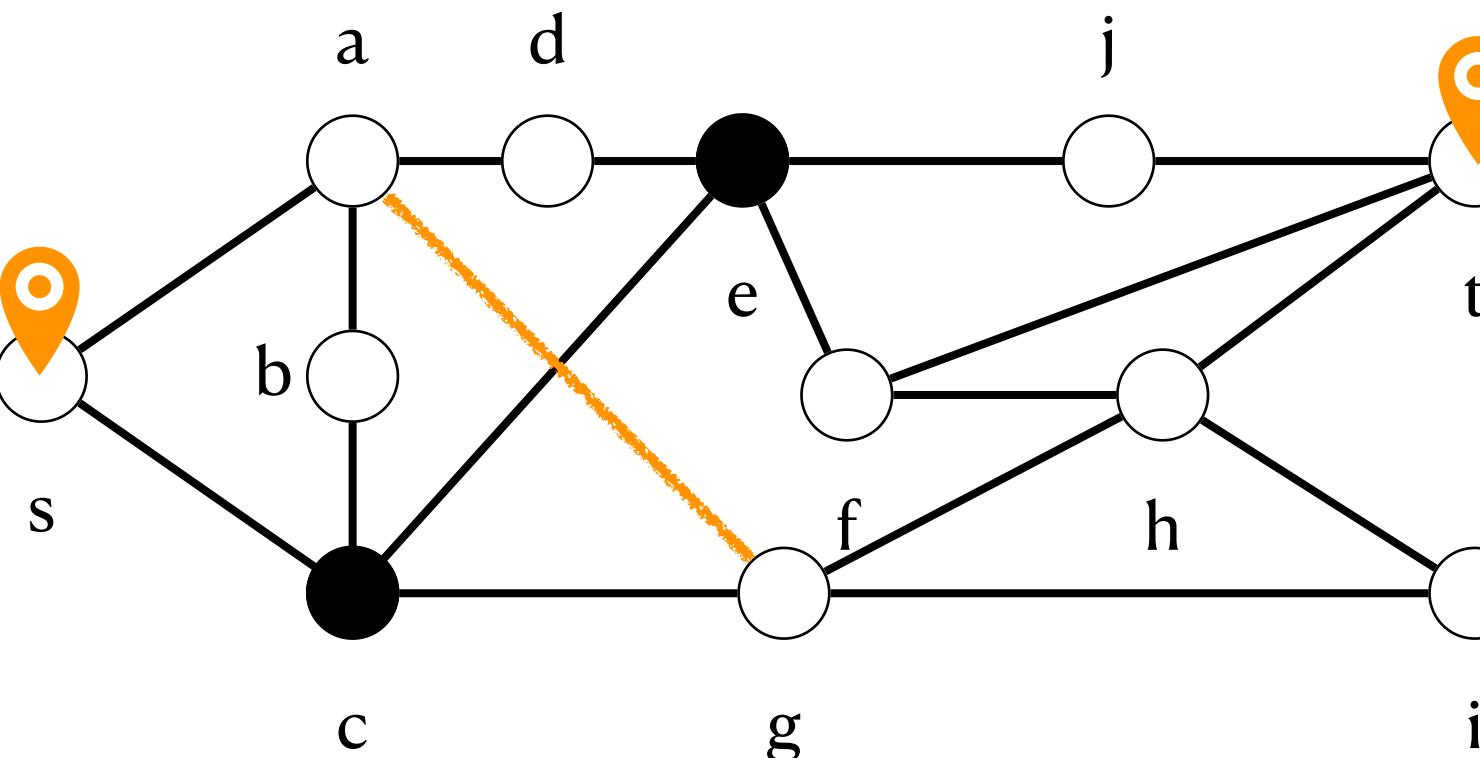
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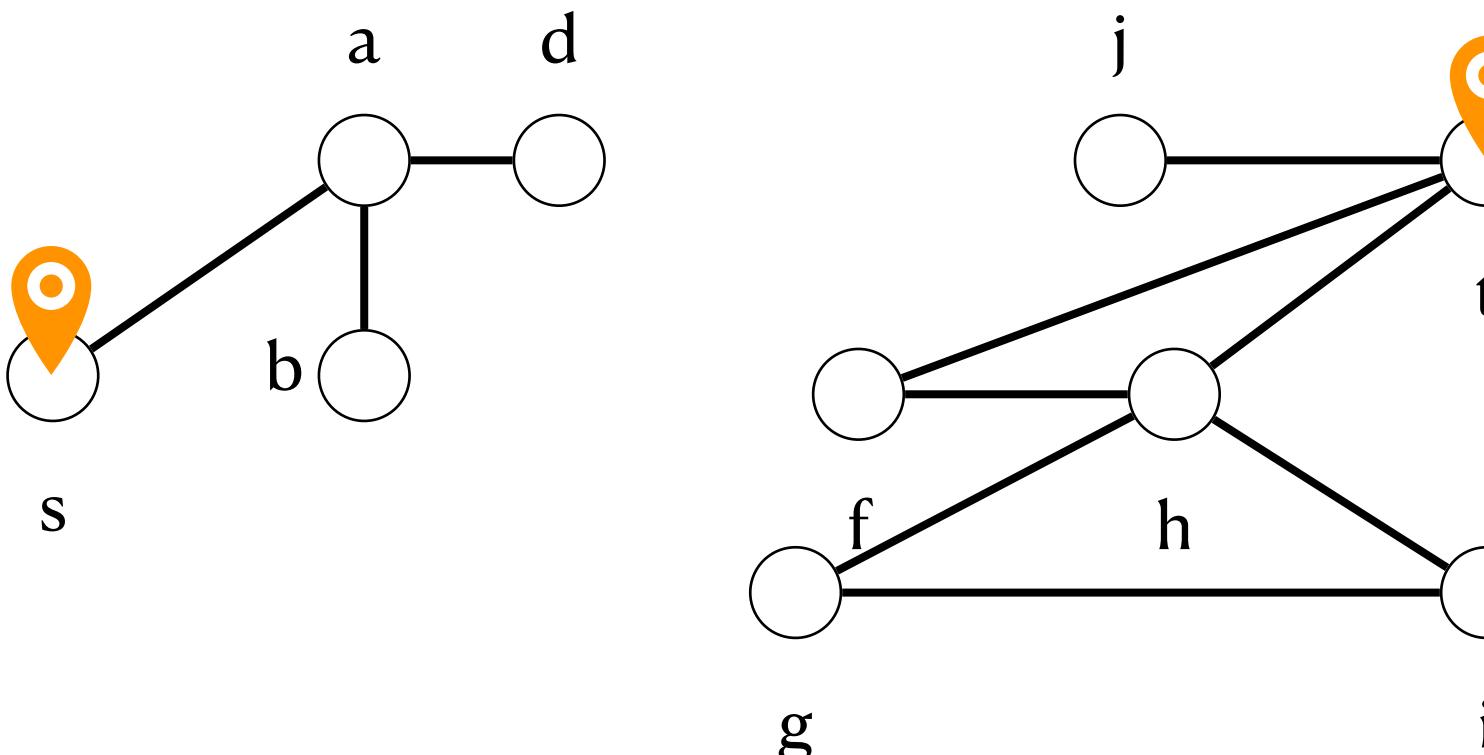


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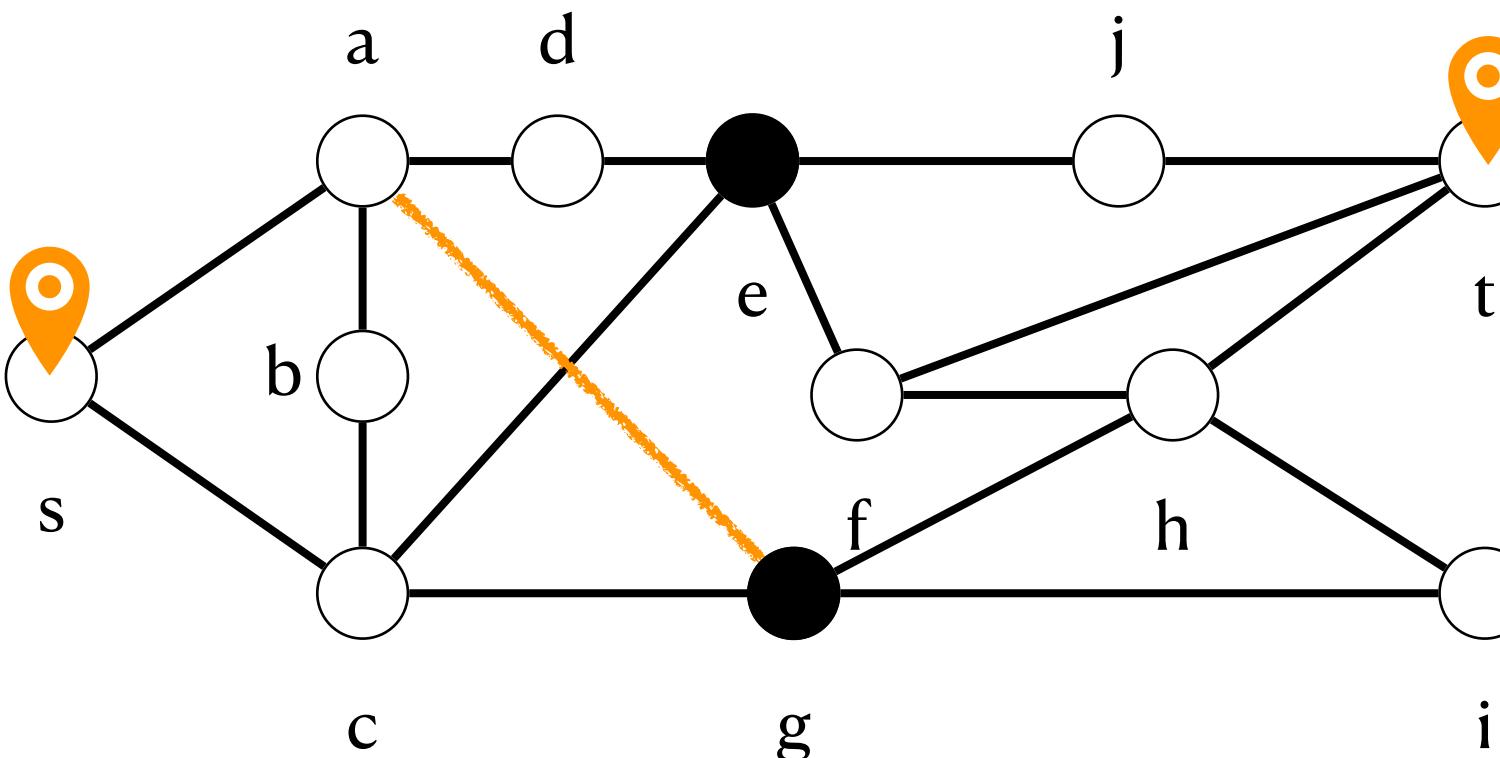


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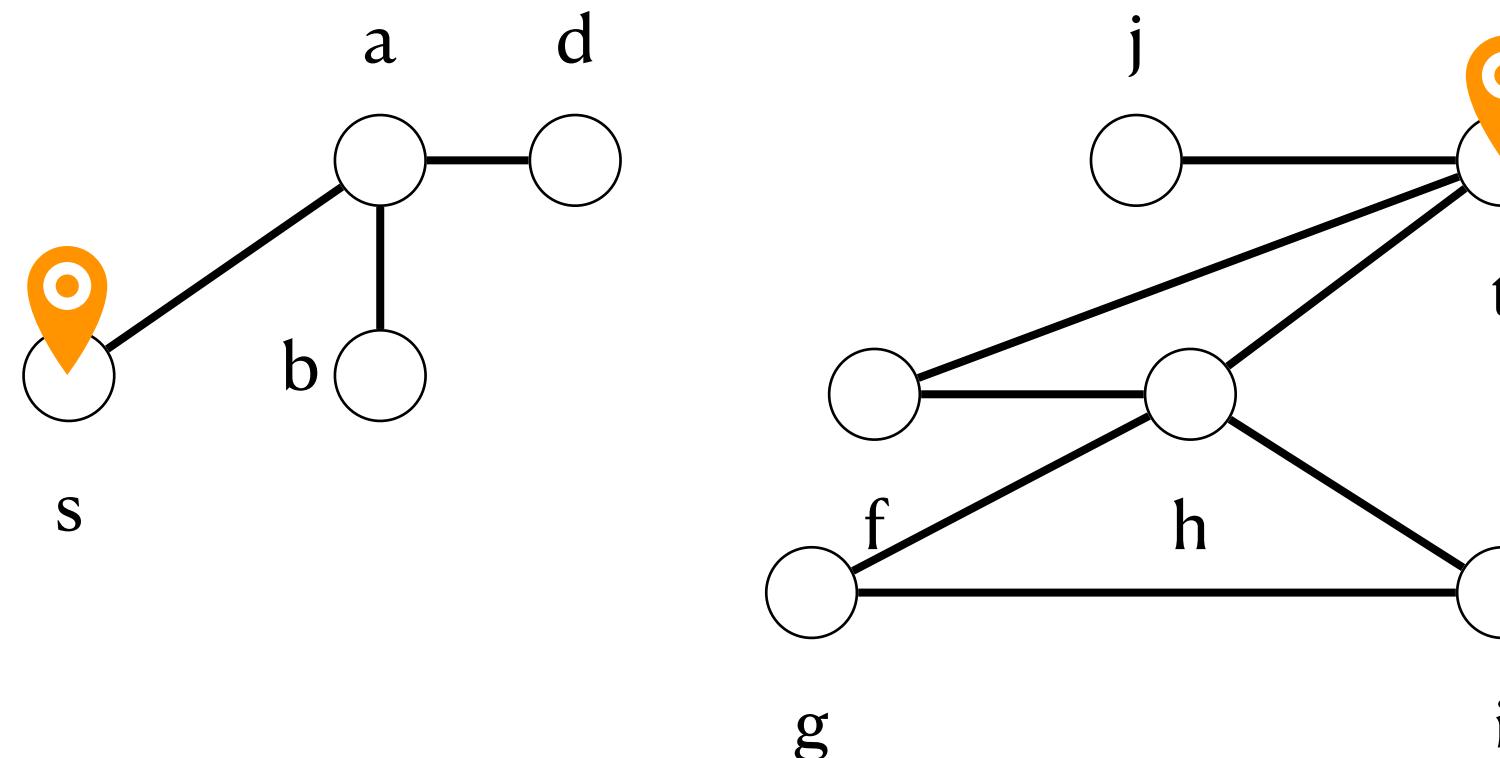


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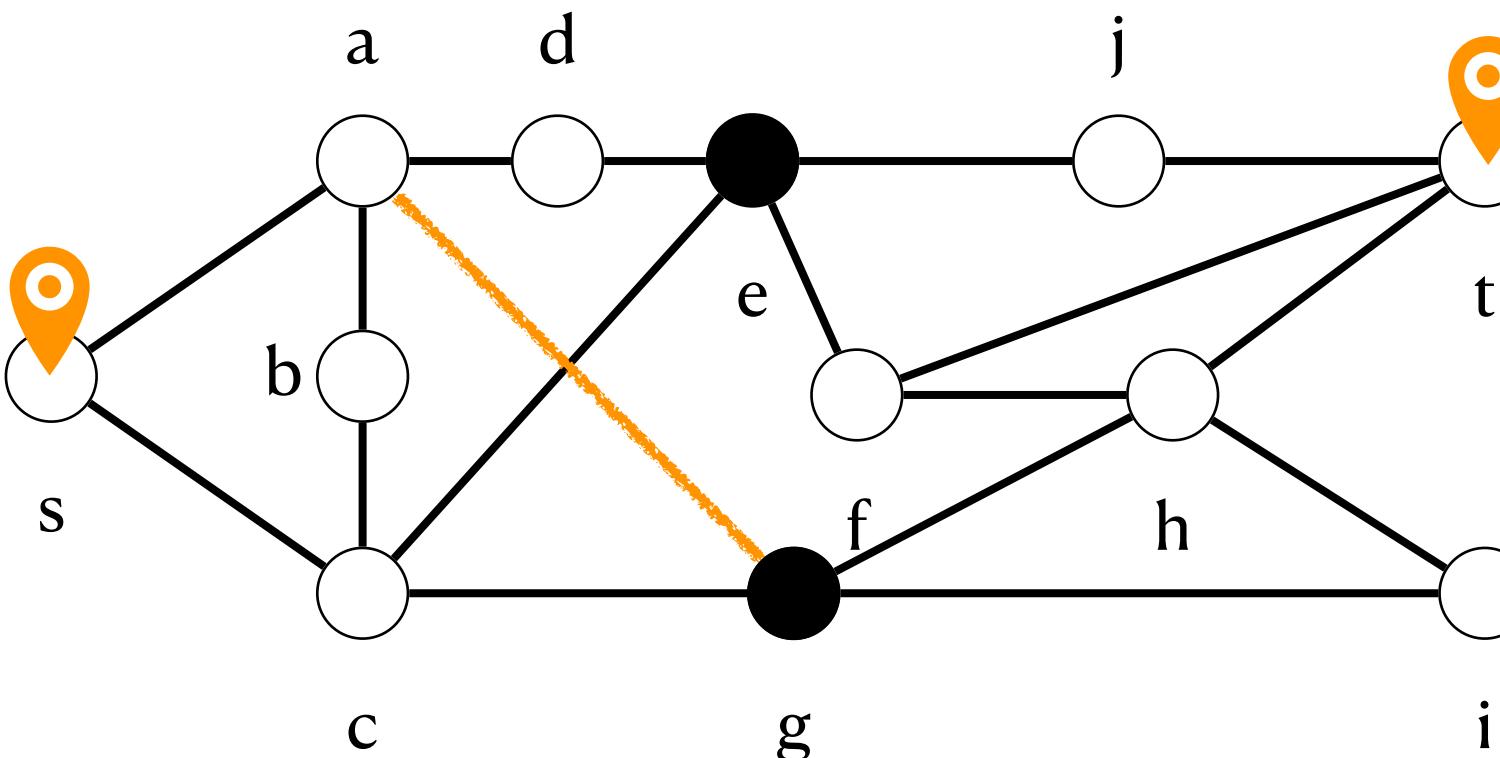


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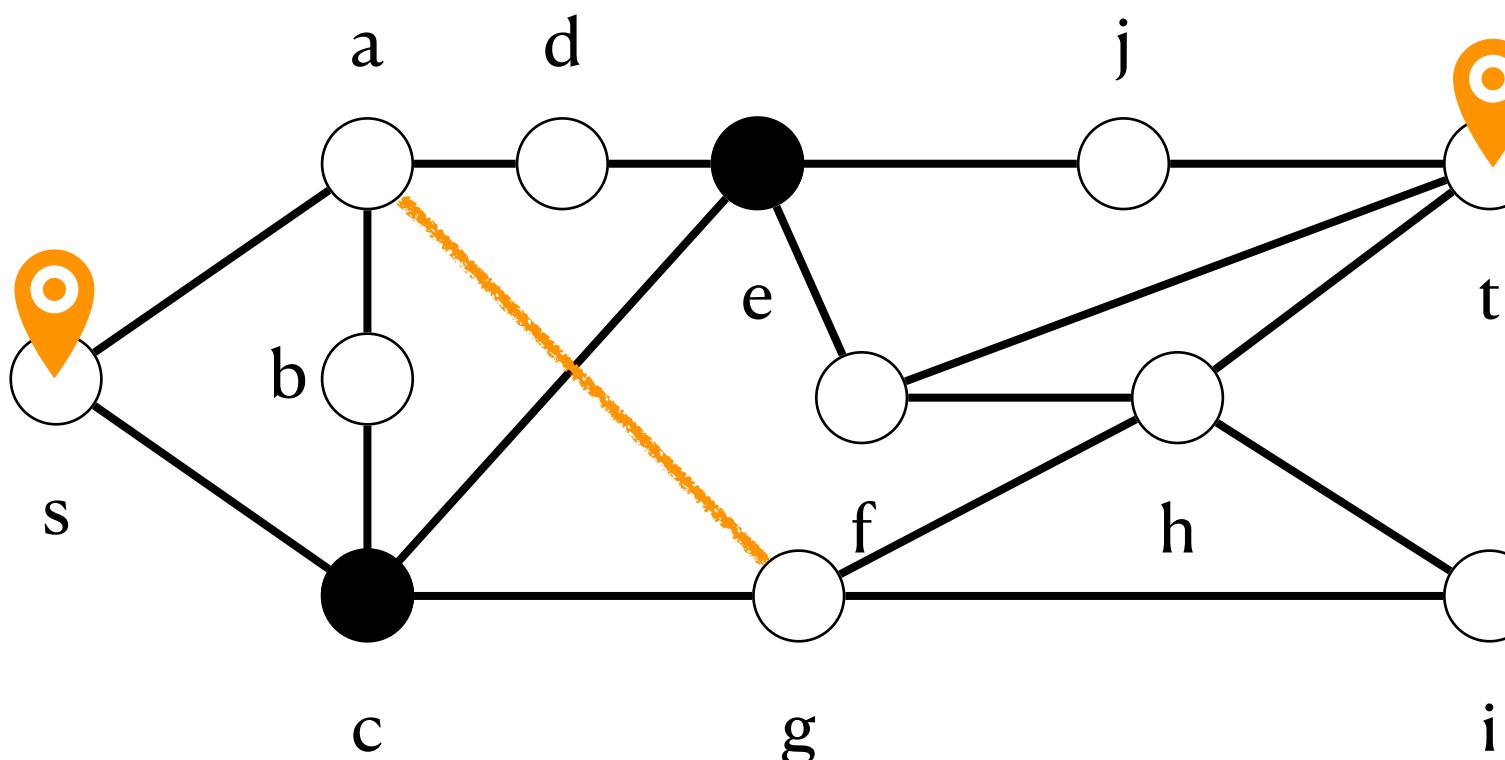
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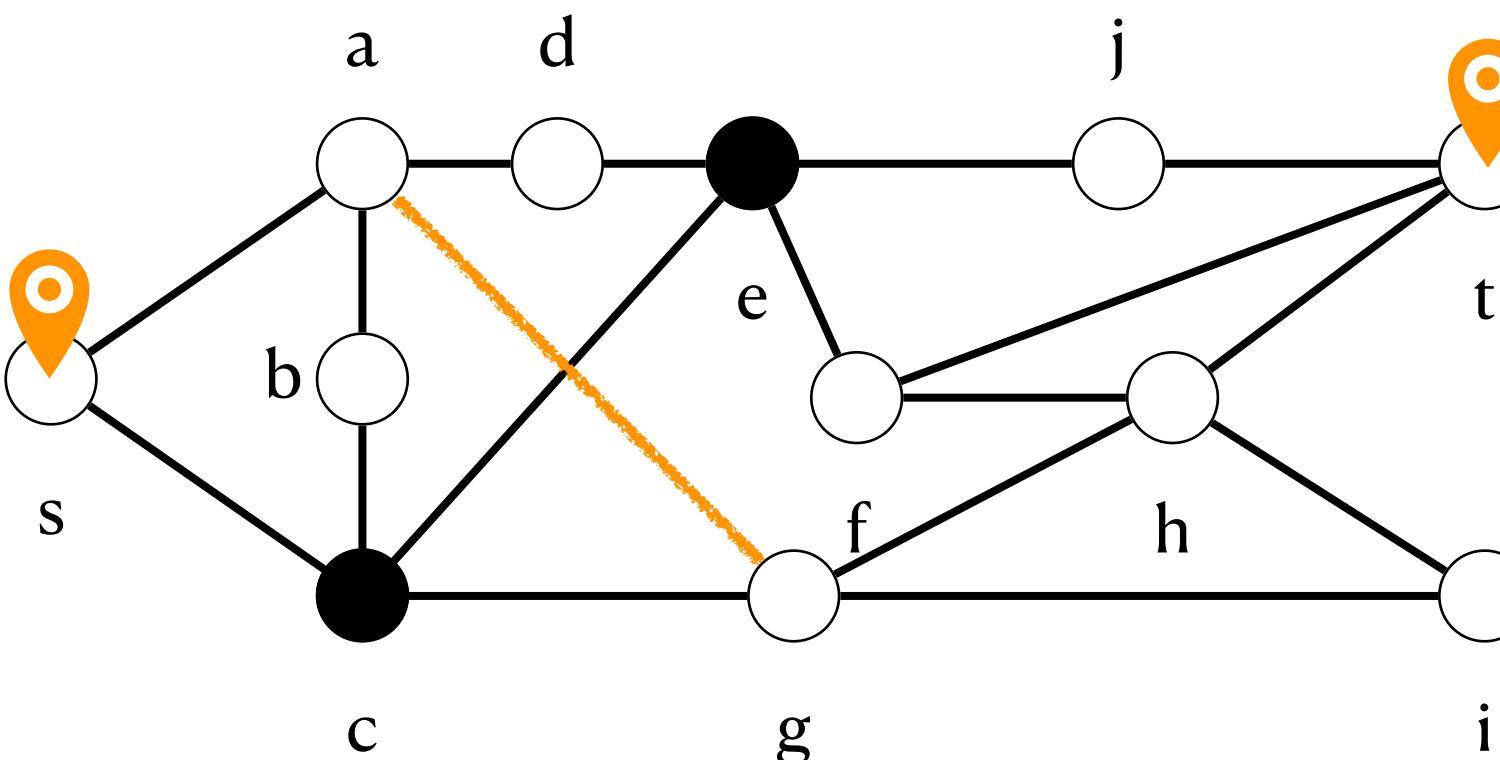
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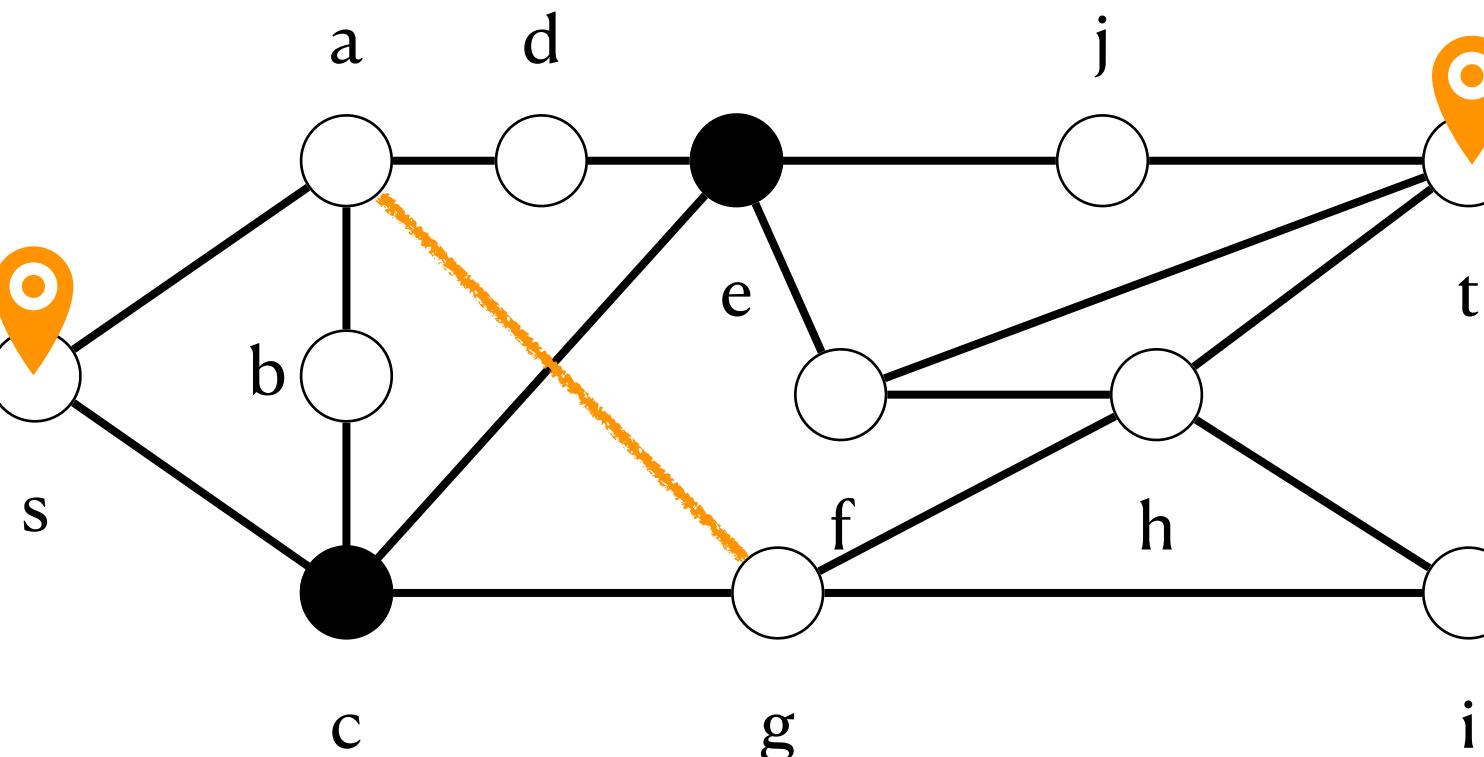
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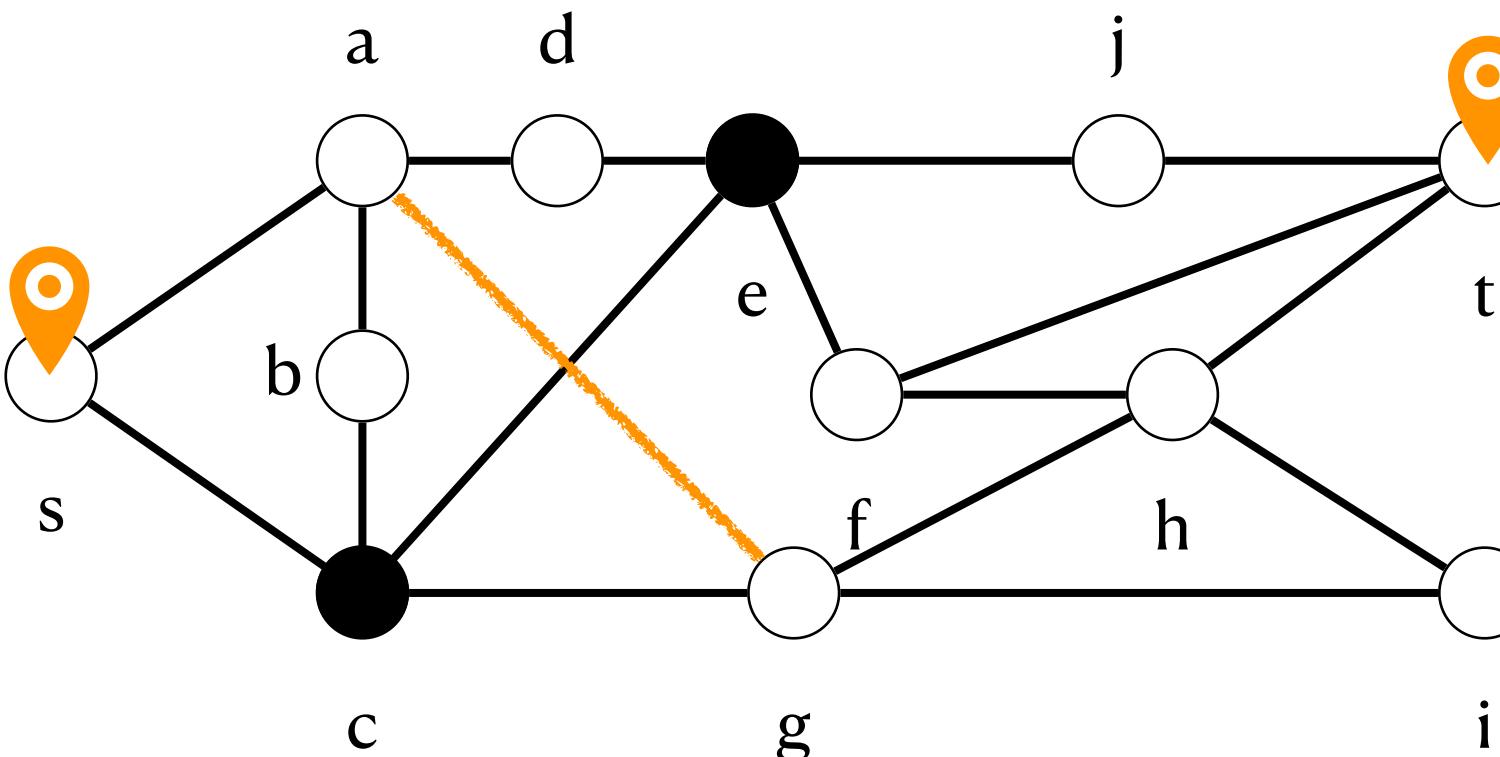
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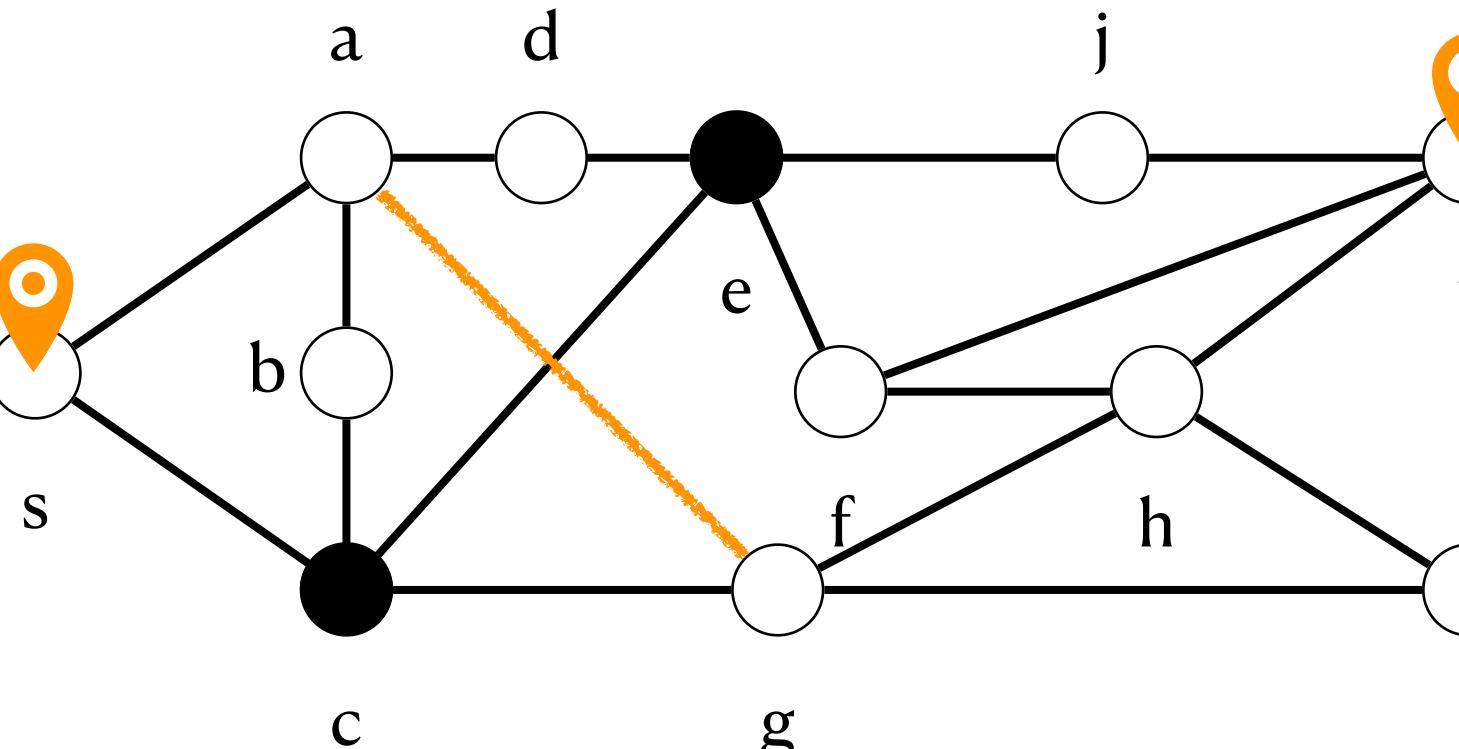
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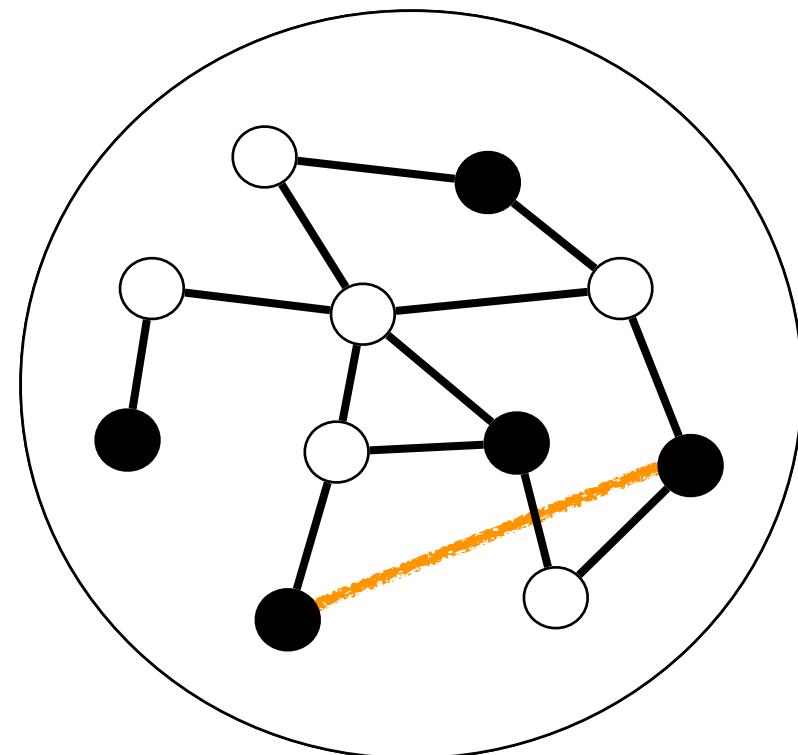
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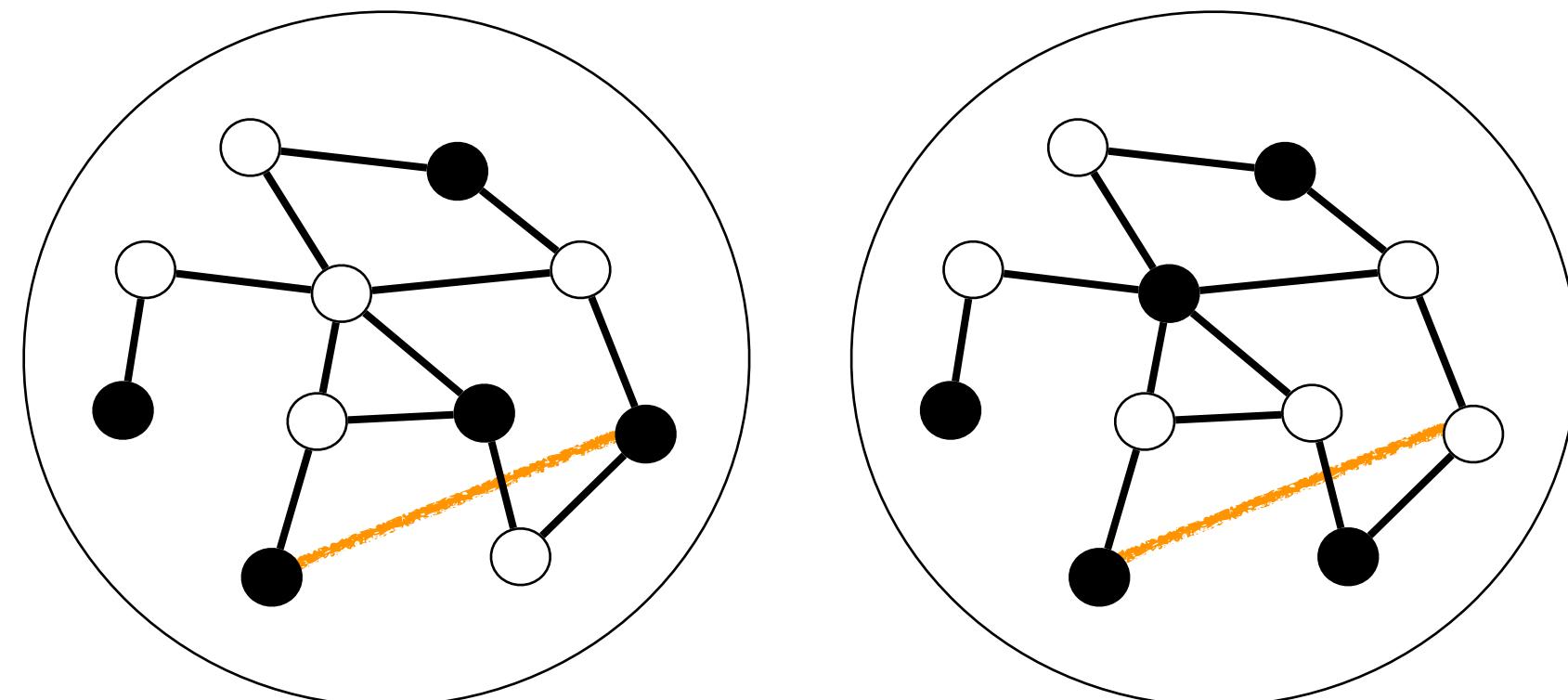
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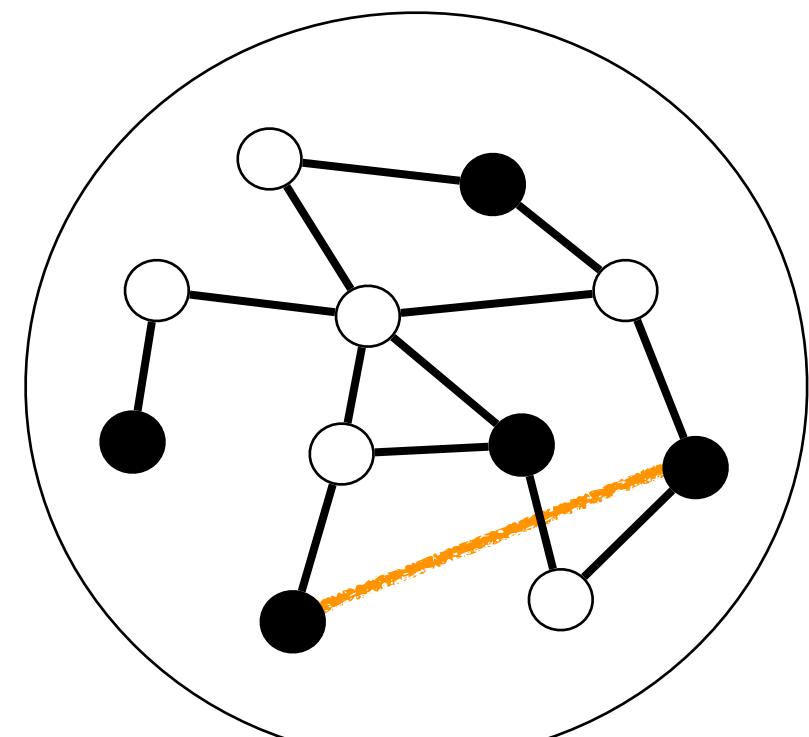
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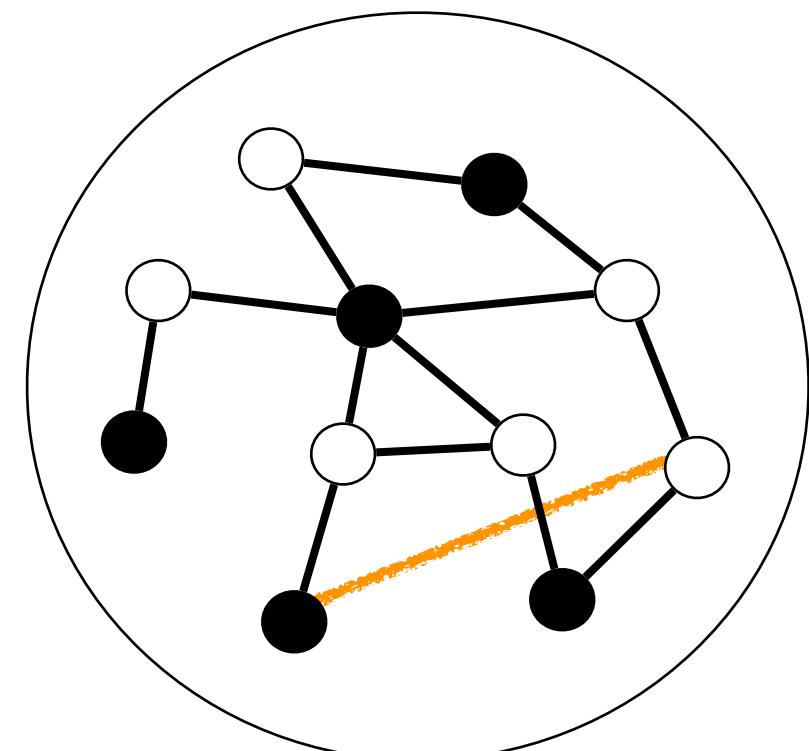
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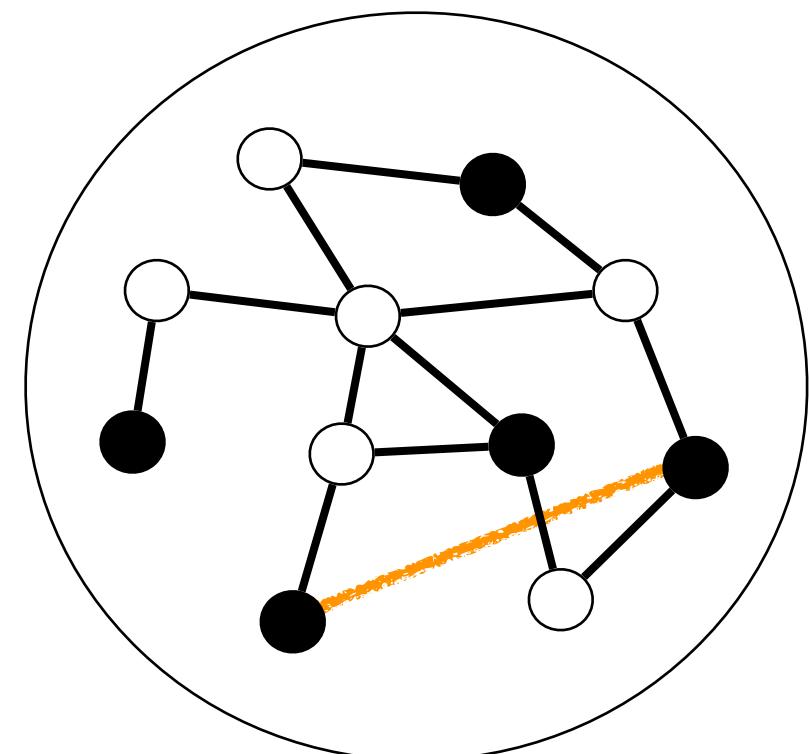
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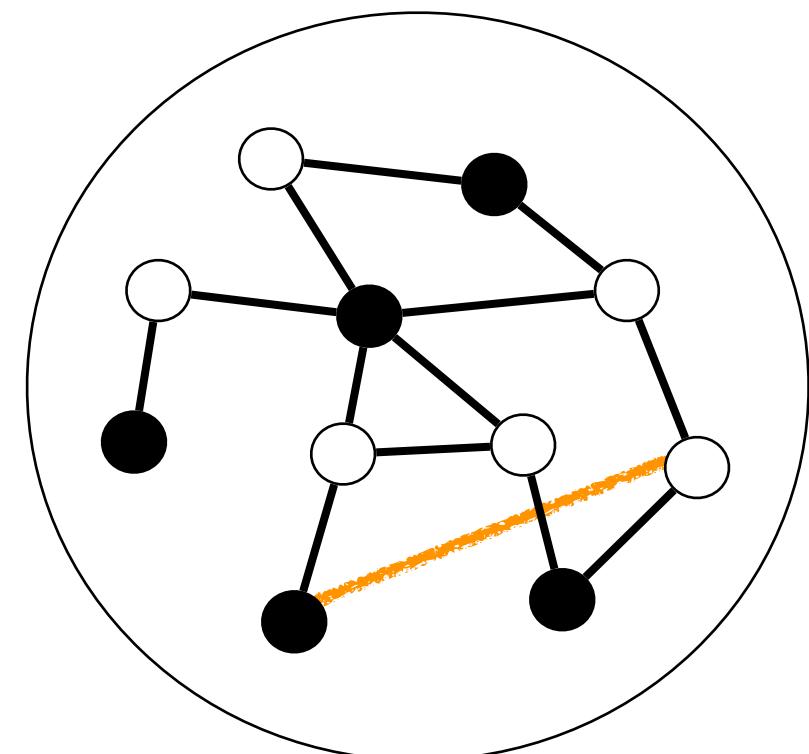
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Solution Discovery Algorithms **are also different** from..

I. Dynamic Graph Algorithms

III. Local Search Algorithms

II. Combinatorial Reconfiguration Algorithms

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- ➊ [Fellows et al, 2023], [Grobler et al. 2024] show **NP-hardness** for all these solution discovery problems.

Parameterized and Kernelization Complexities

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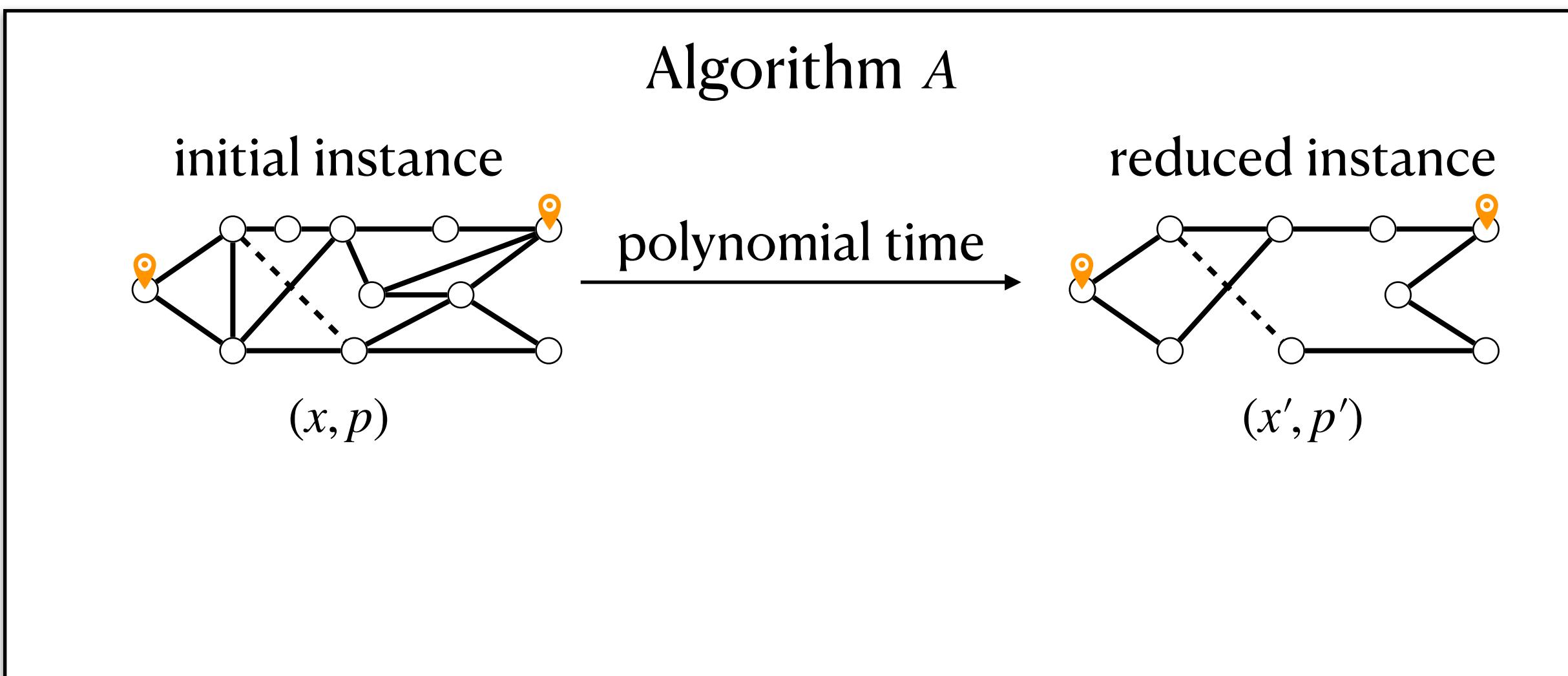
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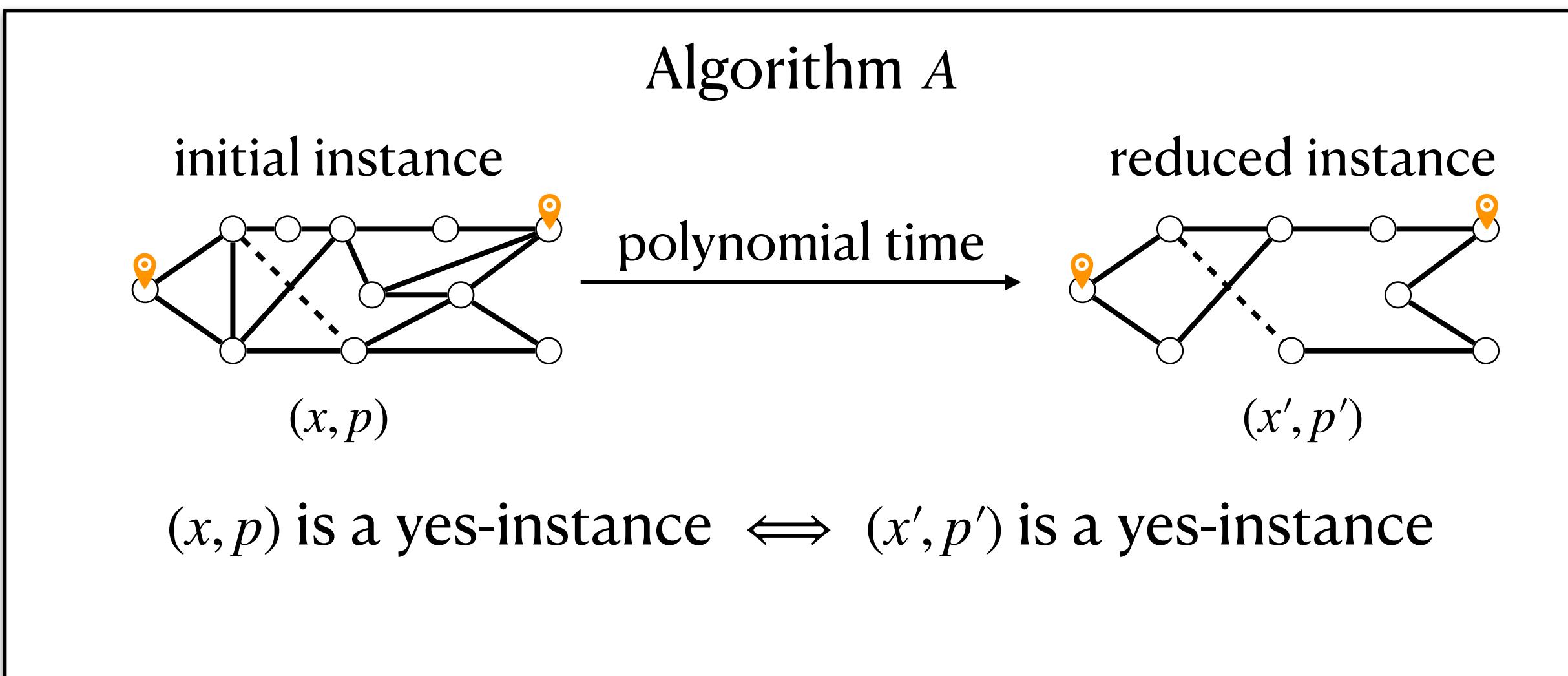


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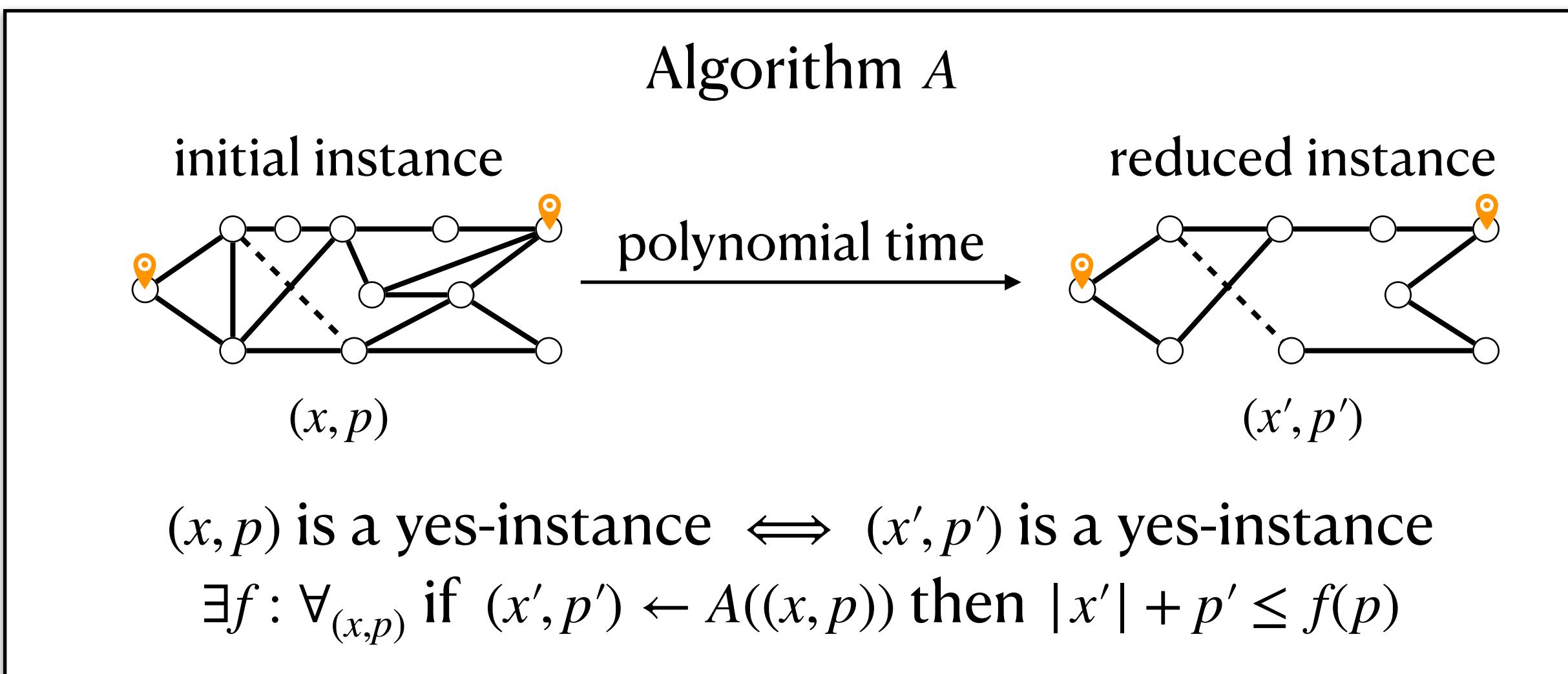


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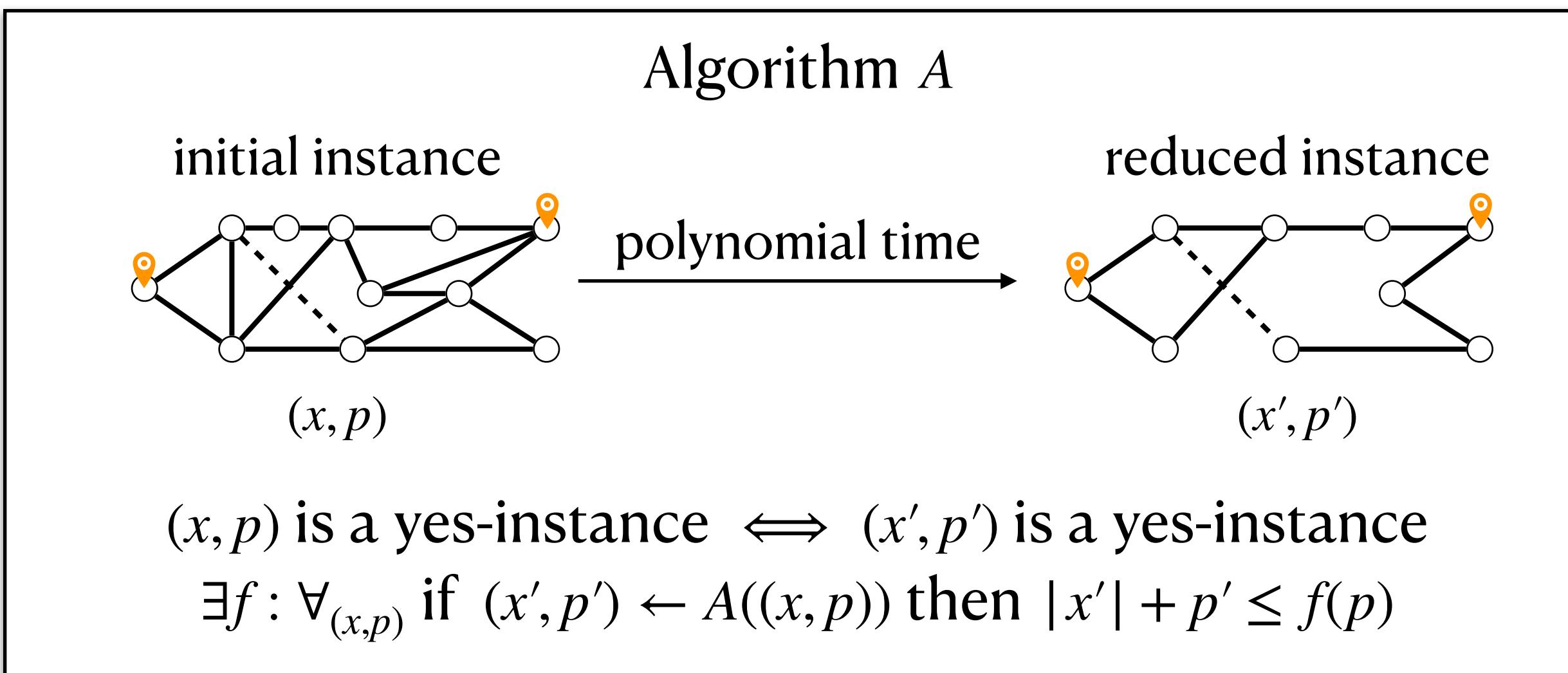


p : parameter

x : instance for classical problem

Parameterized and Kernelization Complexities

- A *parameterized problem* with an algorithm that runs in $g(p) \cdot |x|^c$ time, where g is a function, is in FPT.
- $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots \subseteq \text{XNLP}$
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- Every parameterized problem in FPT has a kernel; not all are polynomial.

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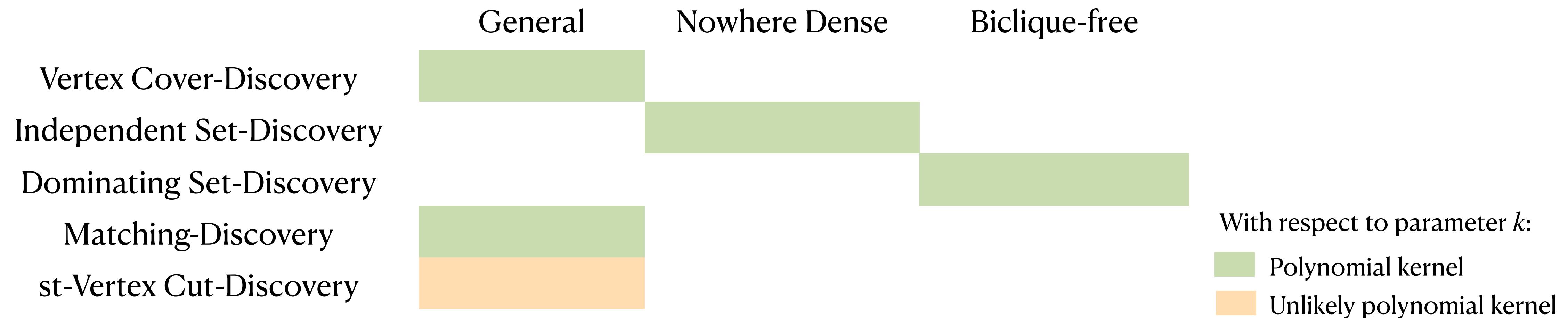
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- We studied the kernelization of the considered problems, unlike [Fellows et al, 2023] and [Grobler et al. 2024].

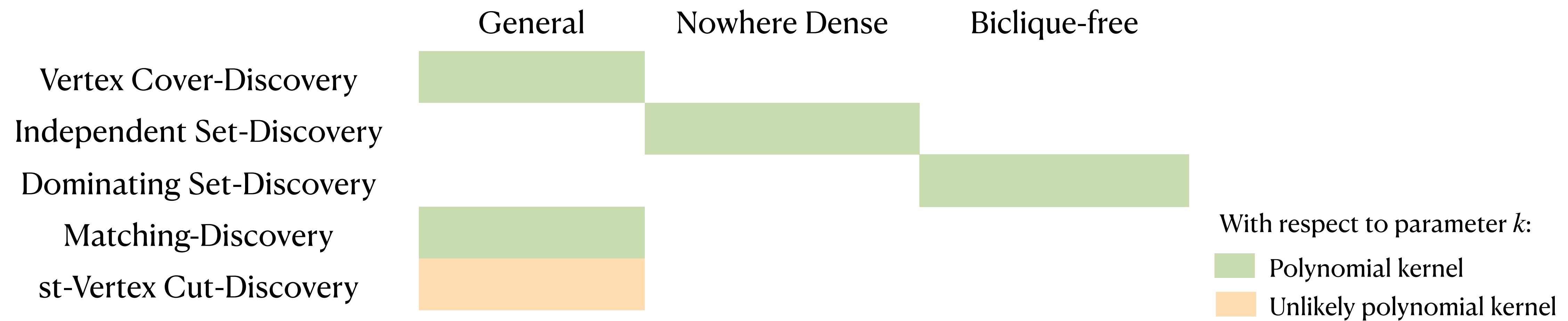
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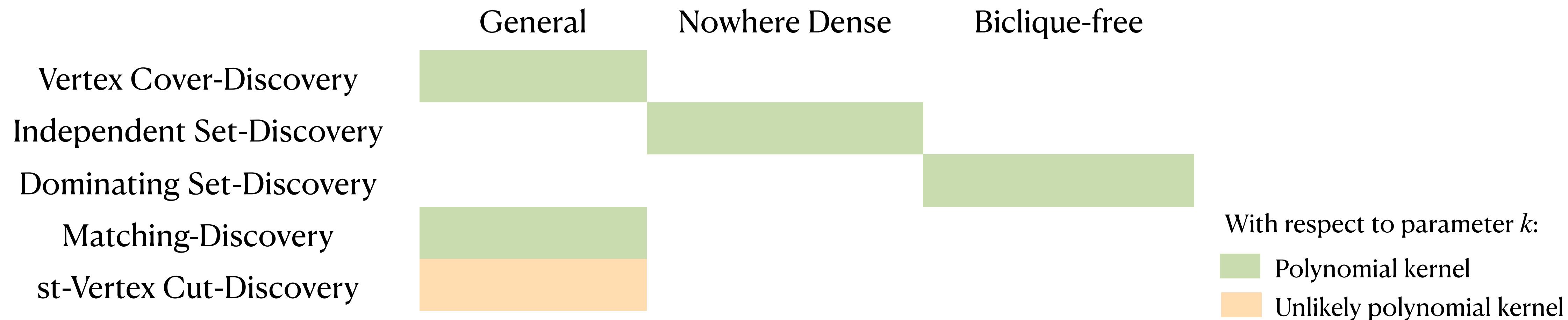
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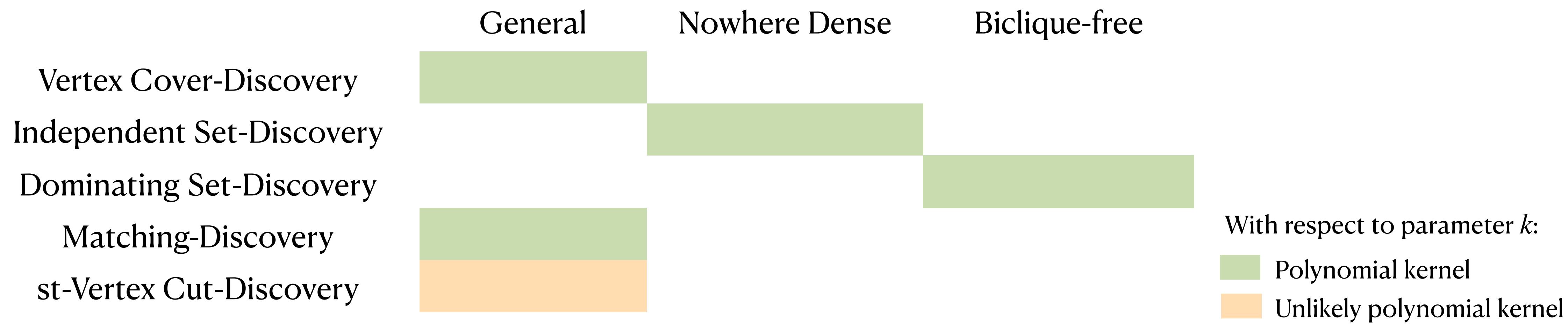
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st-Vertex Cut Discovery with Respect to Parameter k

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- If an *or-cross-composition* from a classical NP-hard problem A into a parameterized problem B exists \Rightarrow no polynomial kernel for B unless $NP \subseteq coNP \setminus poly$ [Bodlaender et al. 2014].

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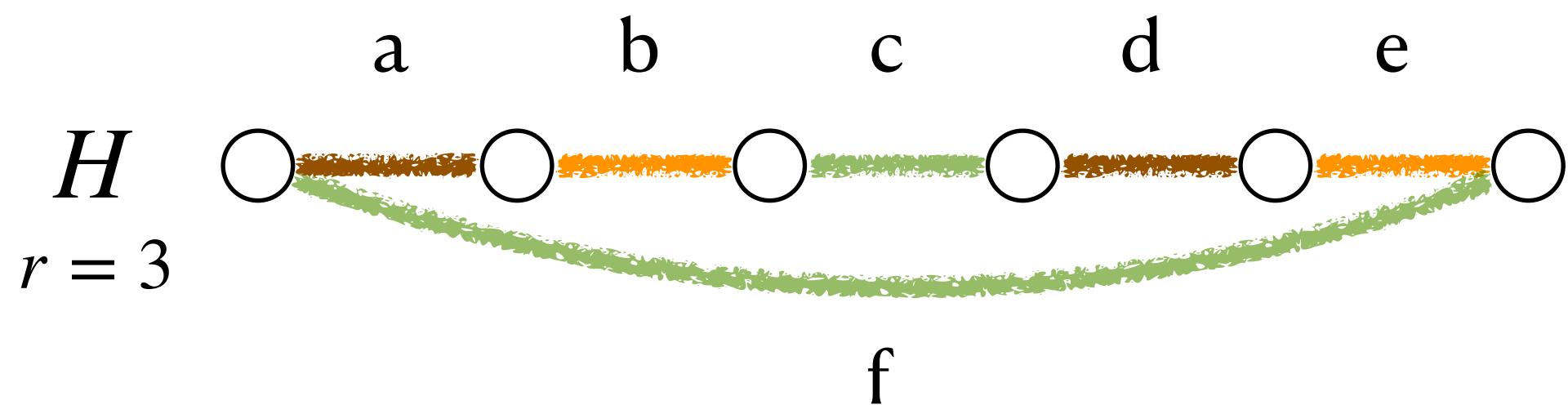
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Input:

- 2-regular graph H ,
- edge coloring s.t. adjacent edges have different colors AND each color is used exactly twice,
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Output: If it exists, a *rainbow matching* (i.e. a matching whose edges have distinct colors) of size r .

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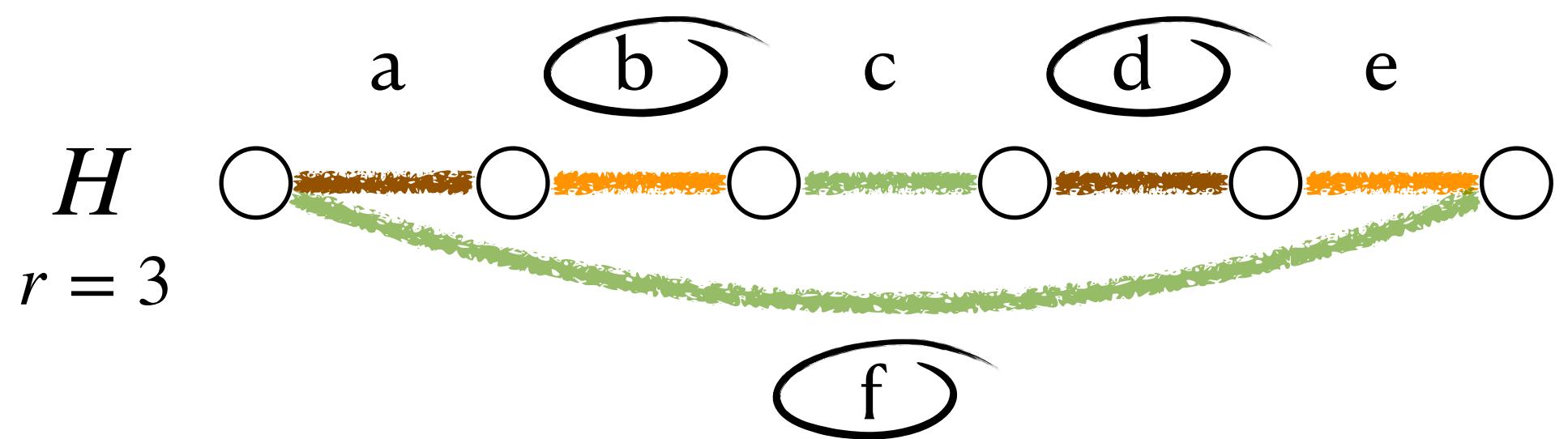
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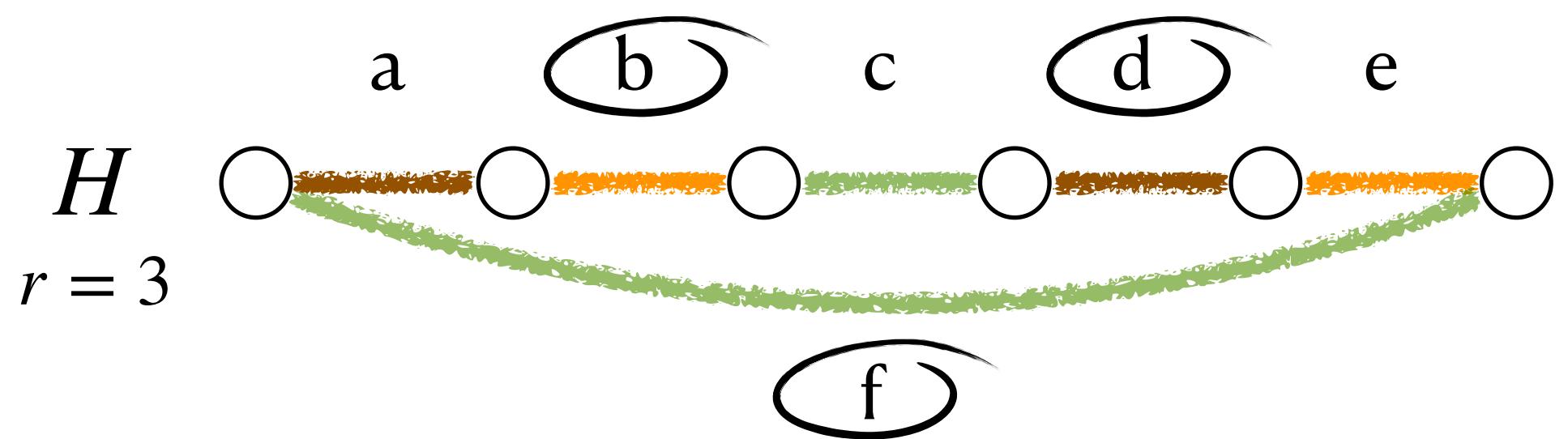
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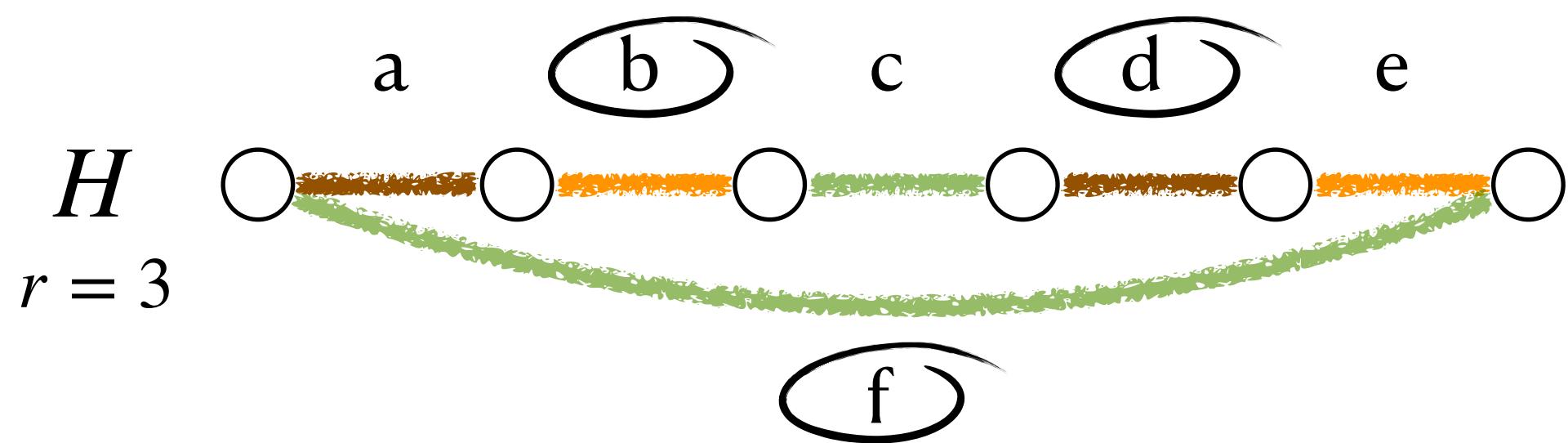
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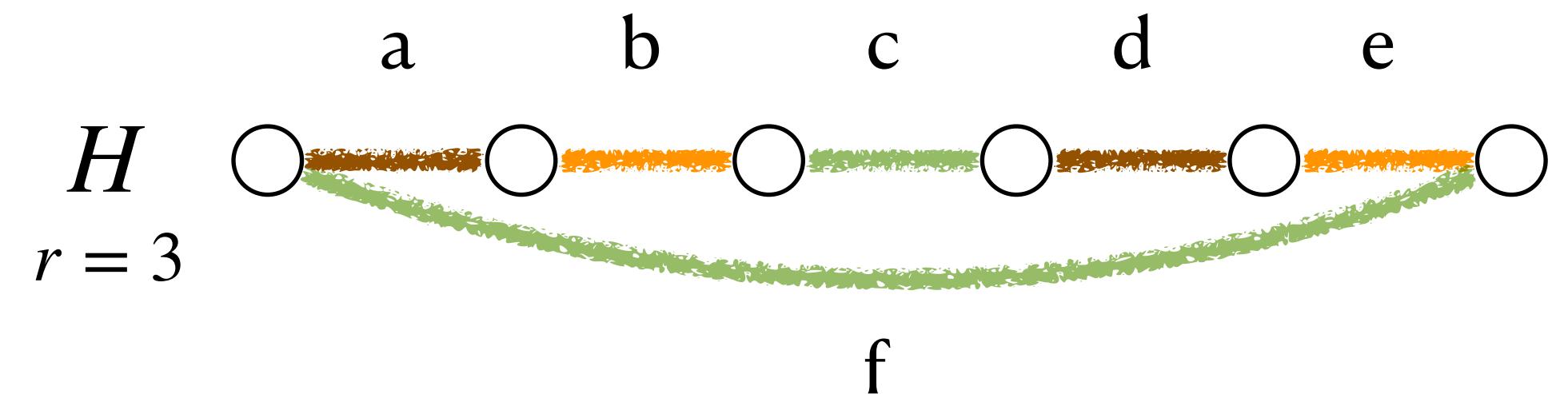
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Reduction from Rainbow Matching to st-Vertex Cut Discovery



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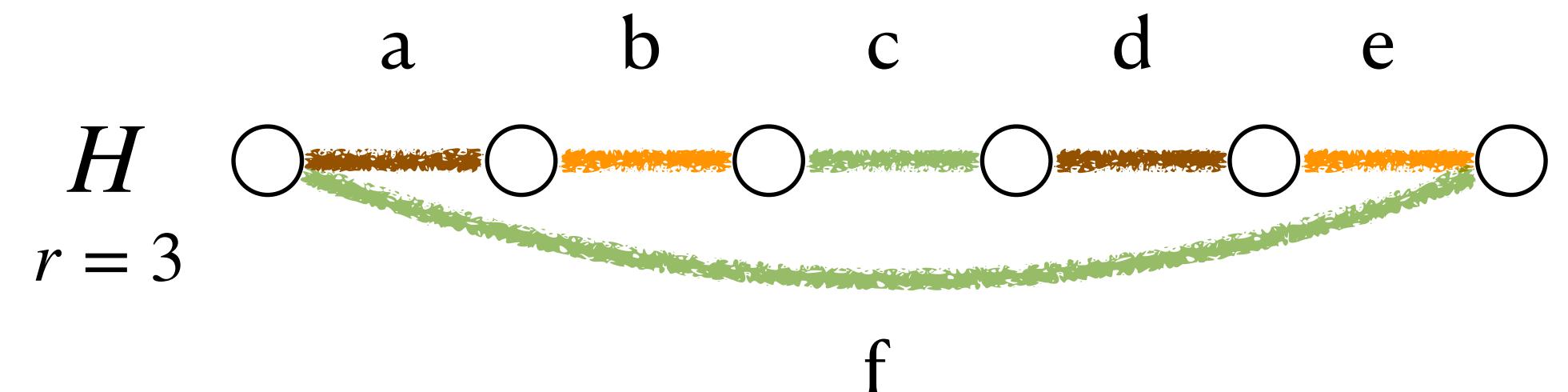
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Reduction from Rainbow Matching to st-Vertex Cut Discovery

G



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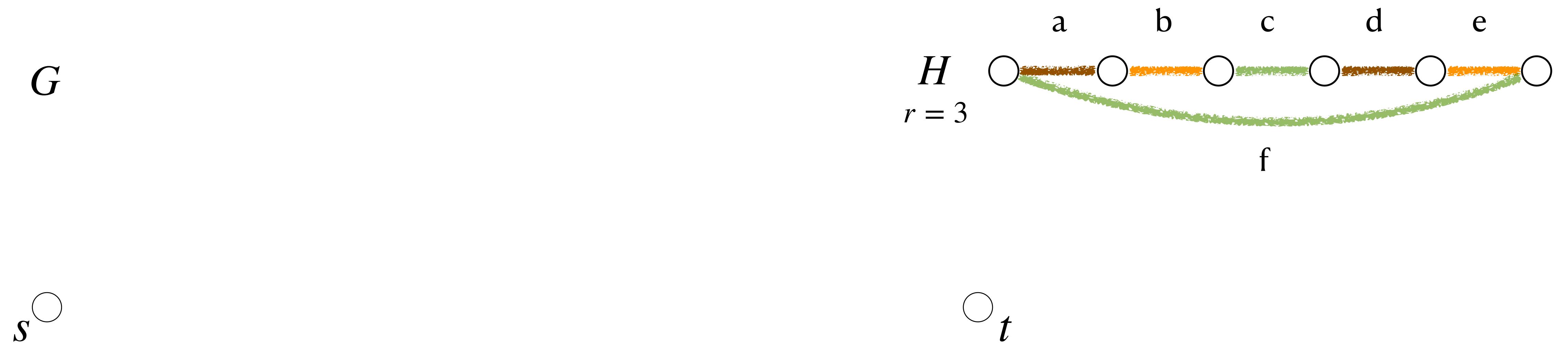
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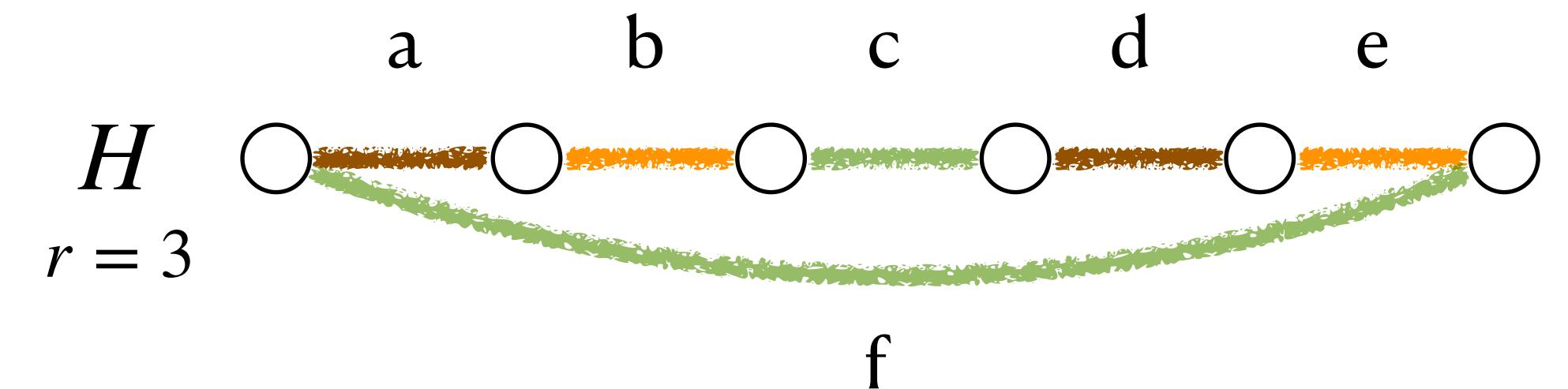
Reduction from Rainbow Matching to st-Vertex Cut Discovery

G

s_1 ○

s ○

s_2 ○



○ t

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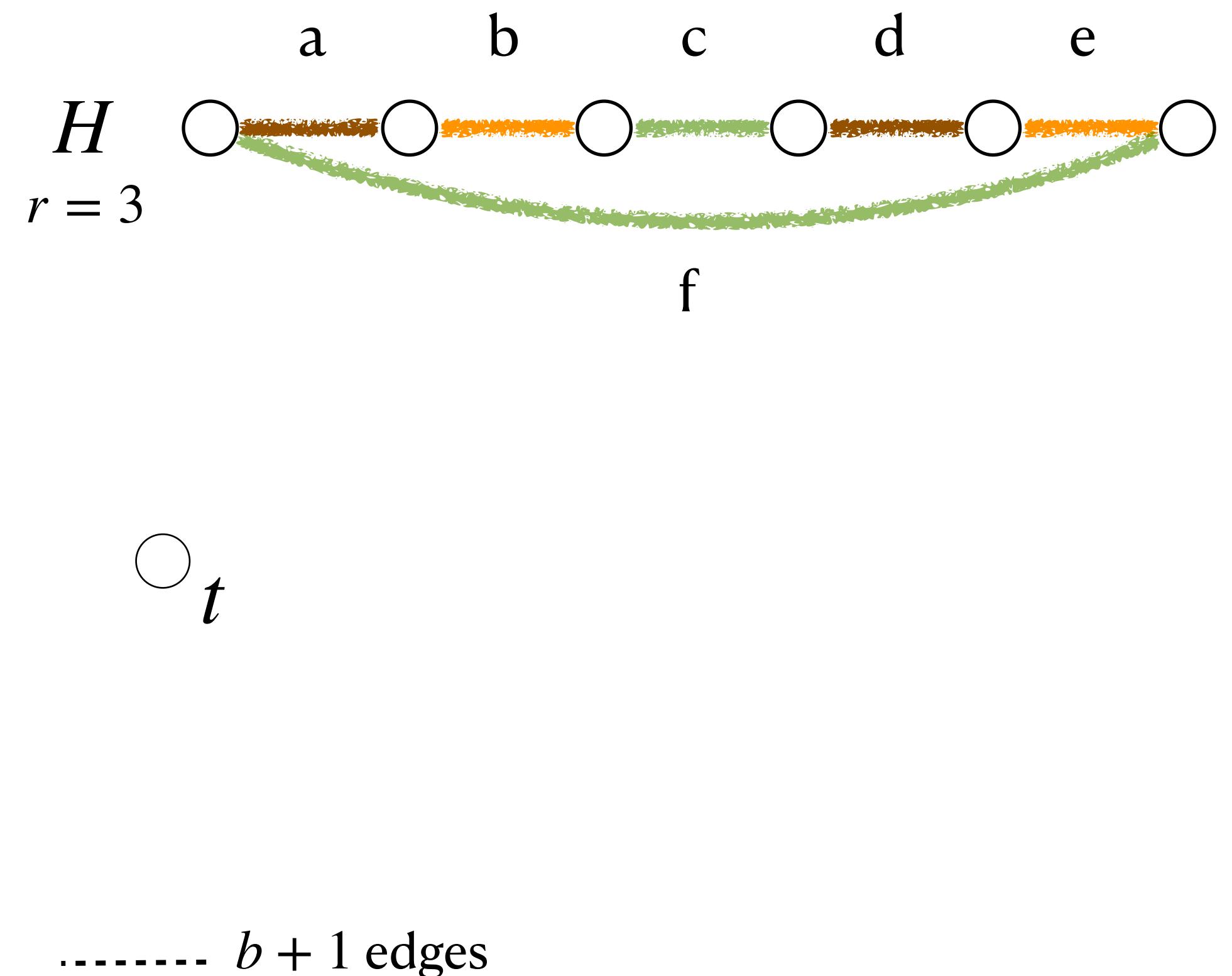
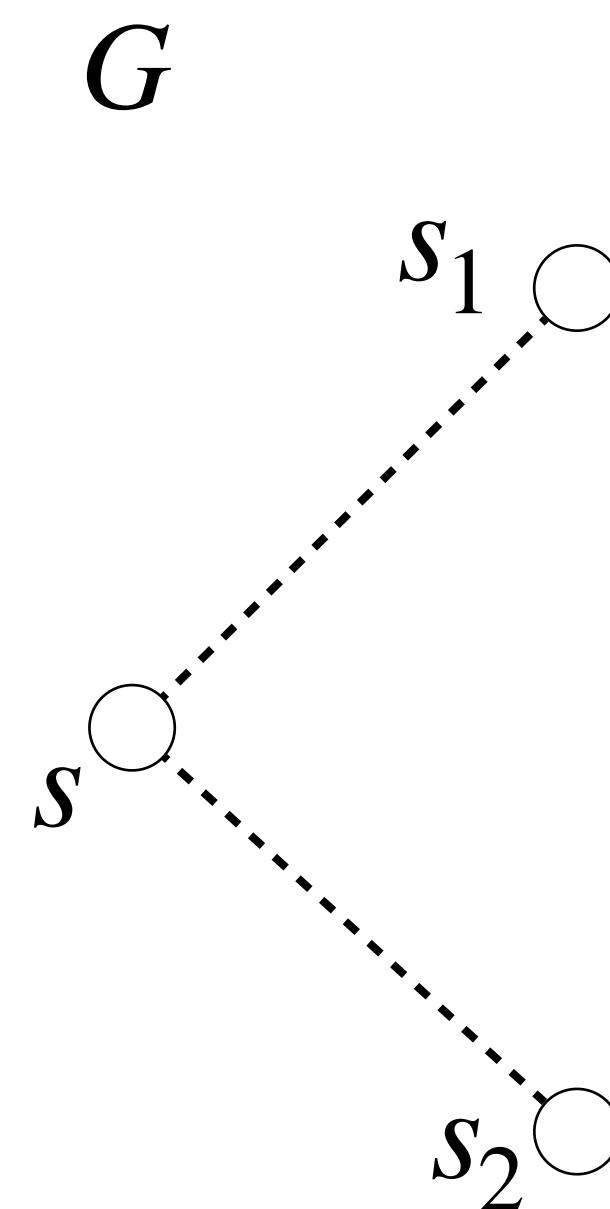
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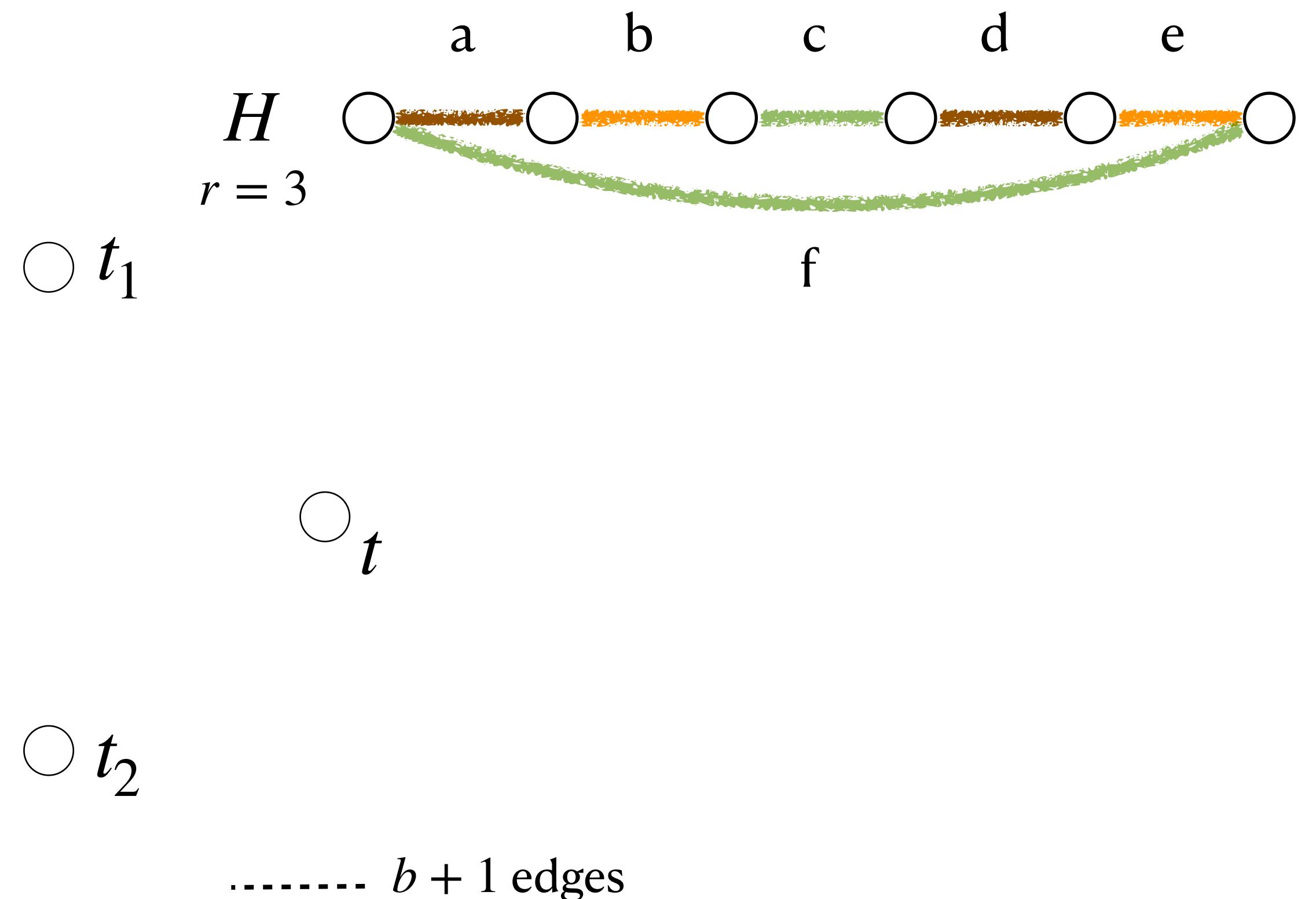
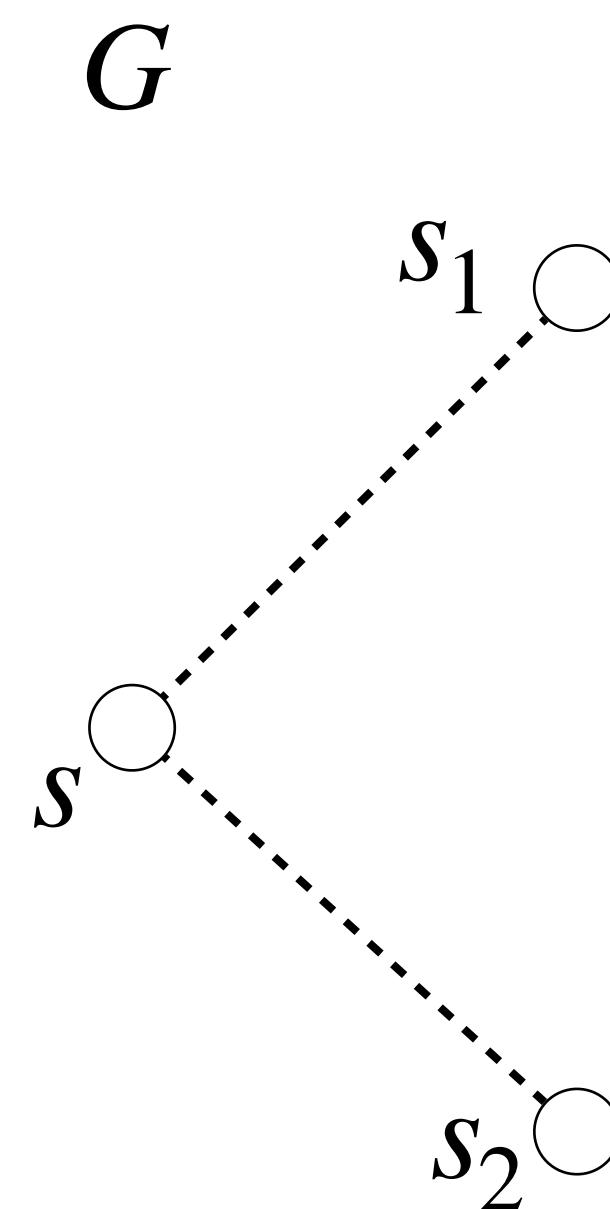
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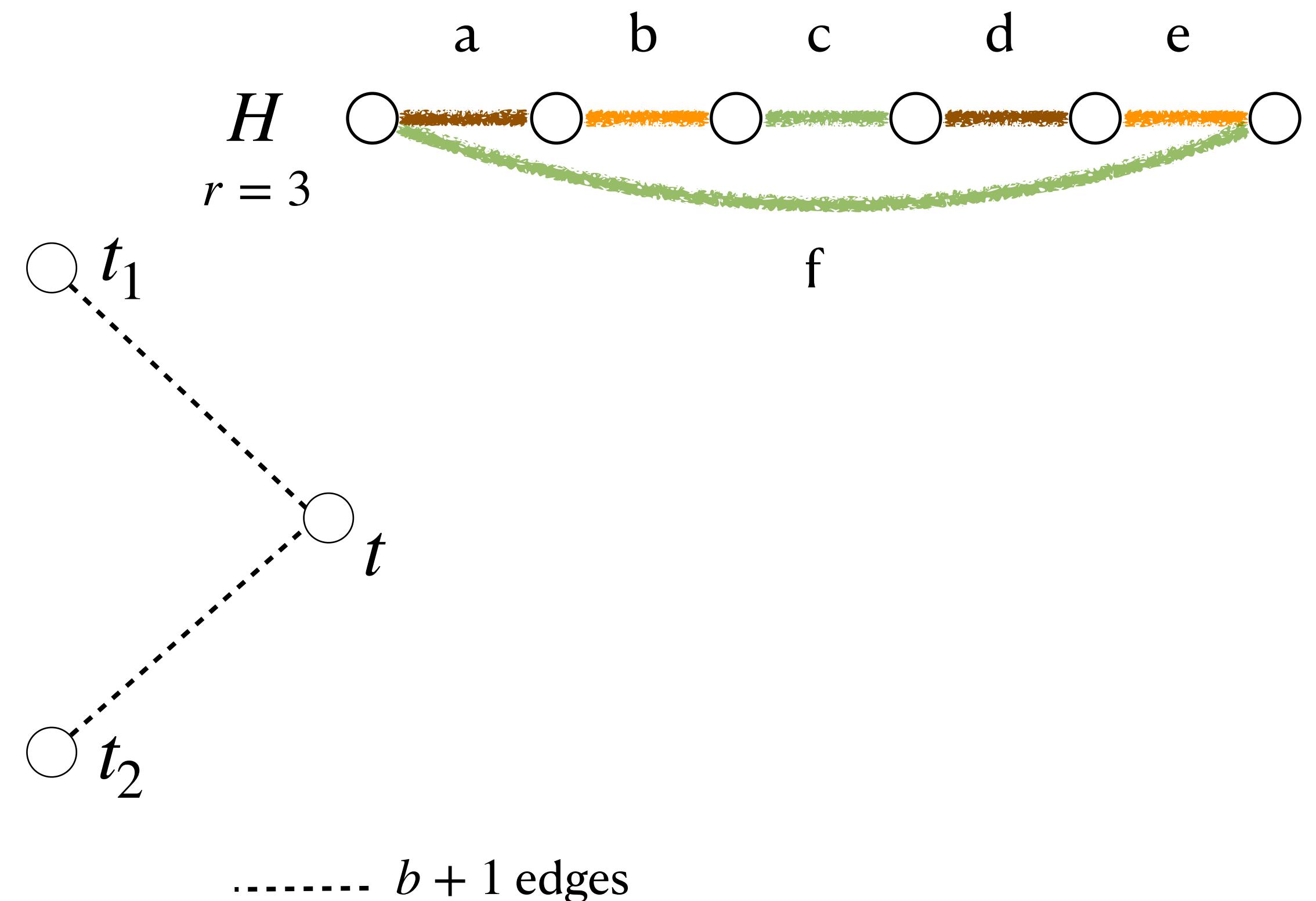
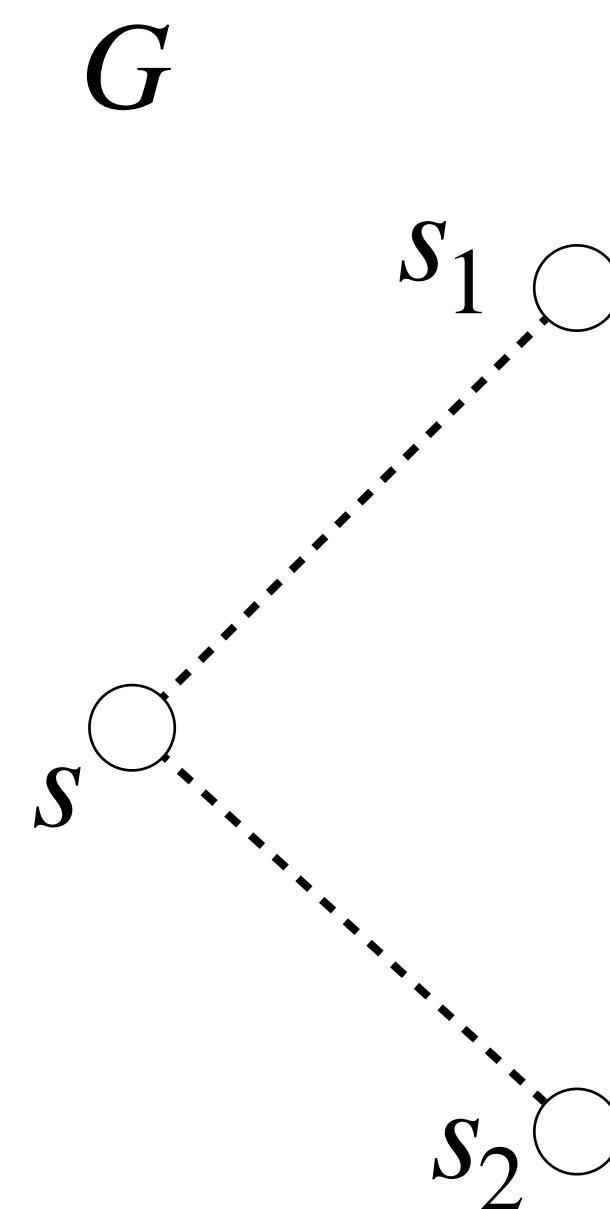
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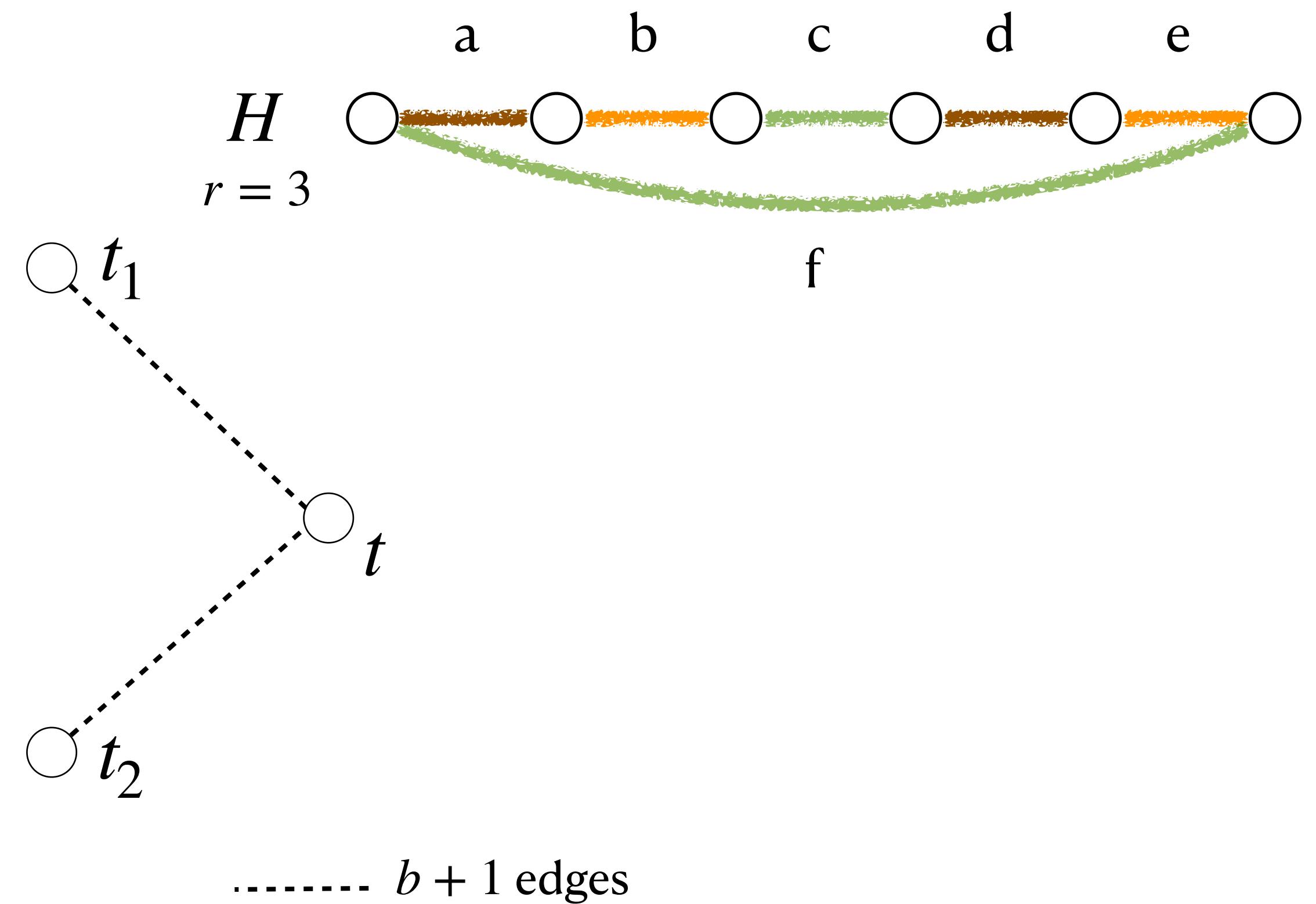
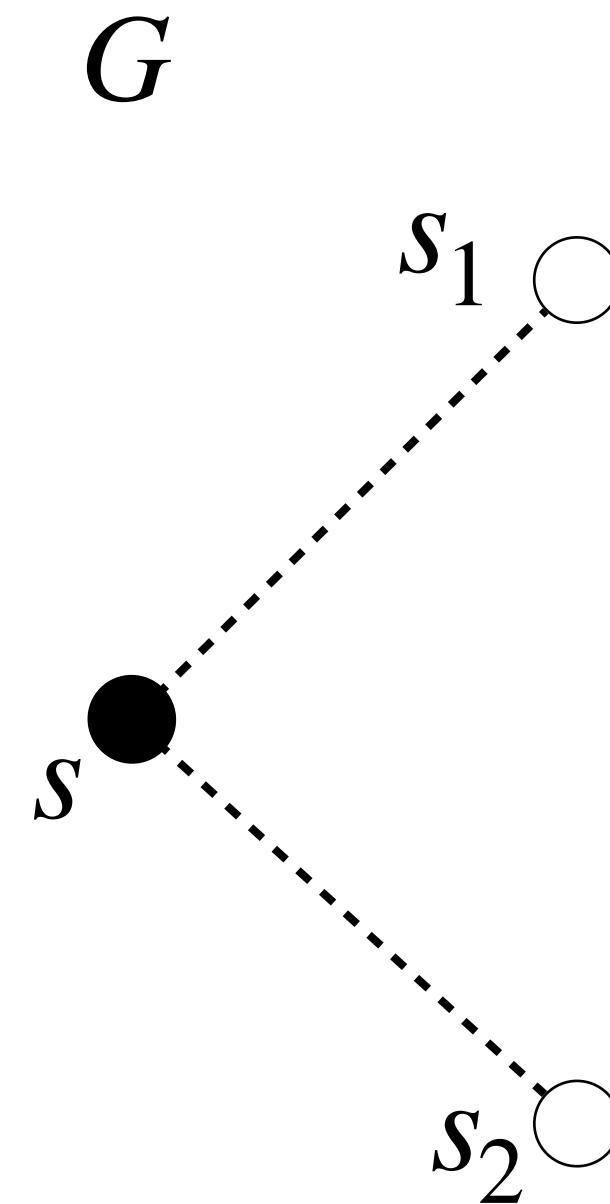
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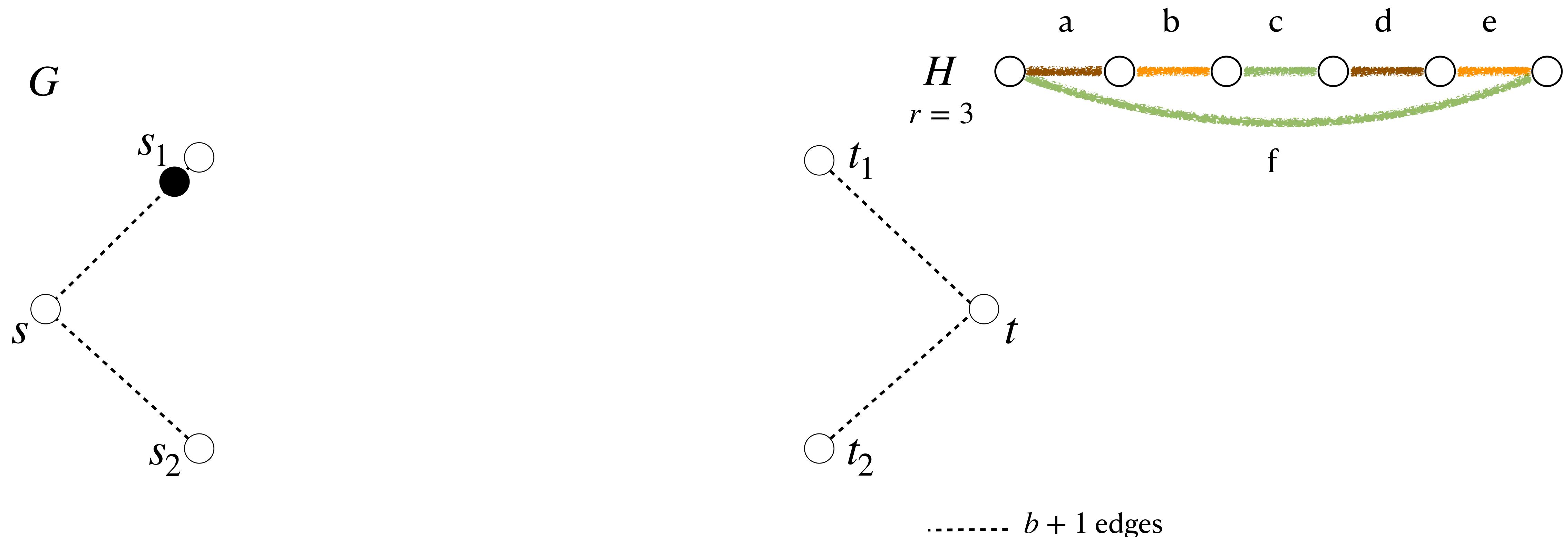
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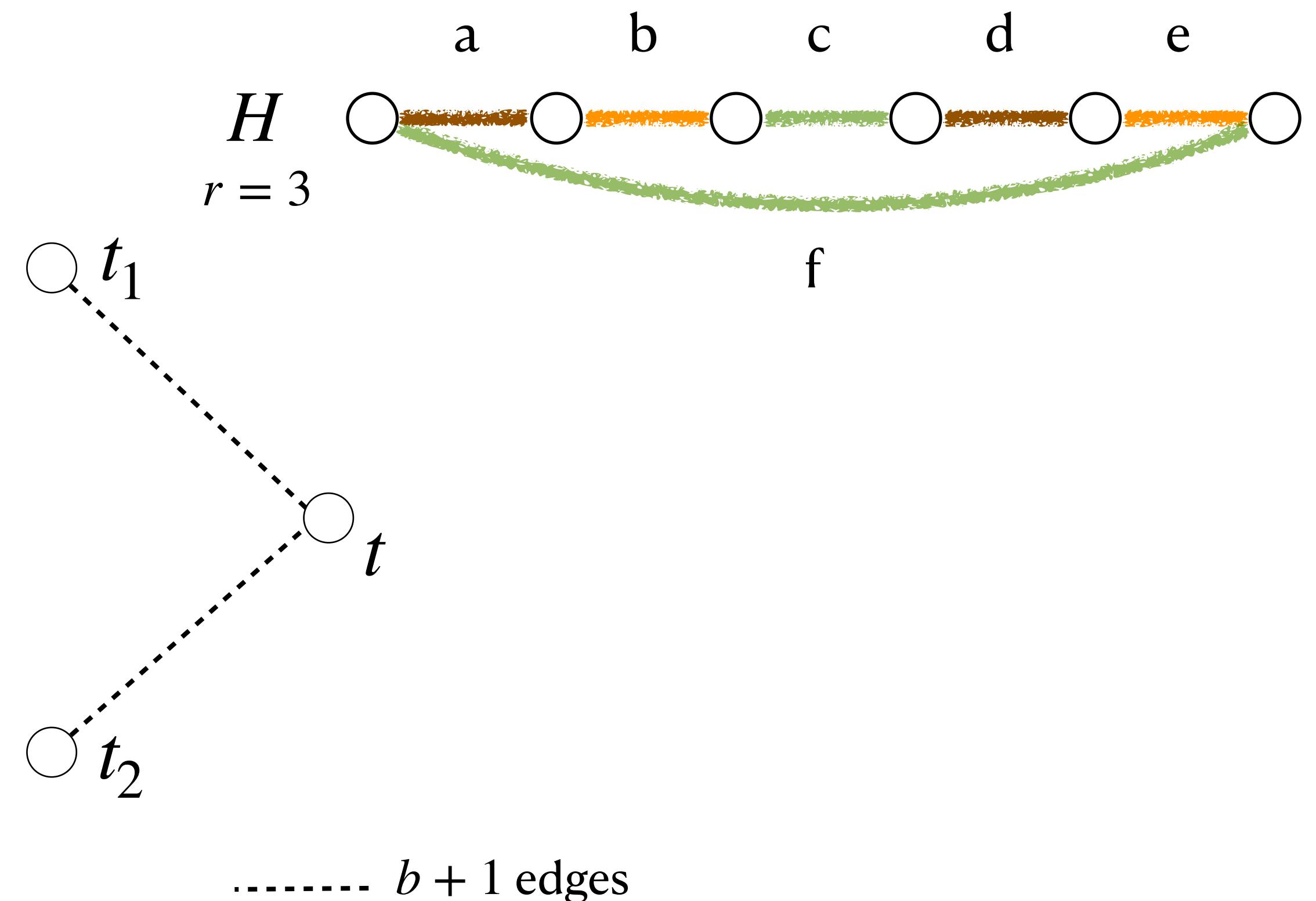
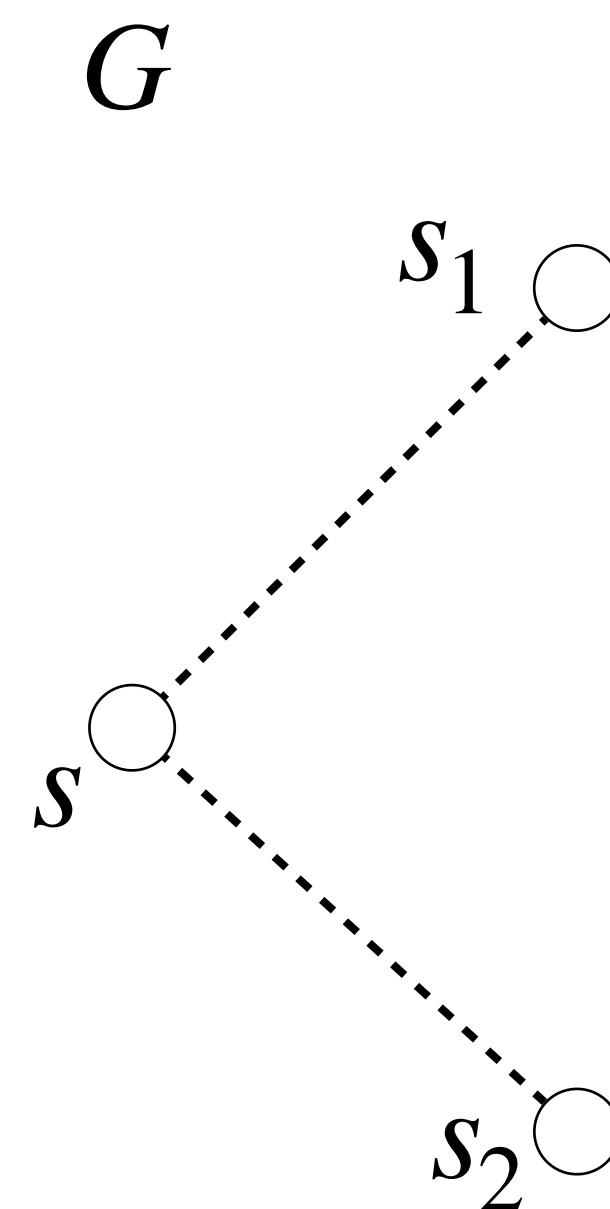
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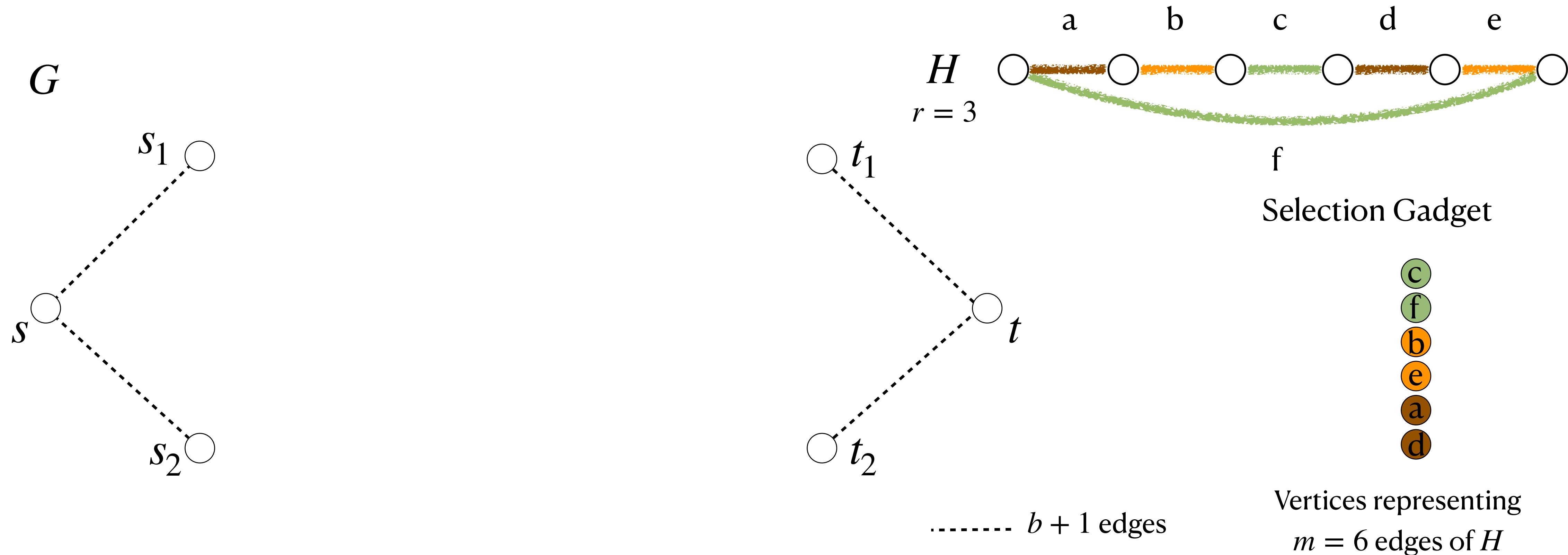
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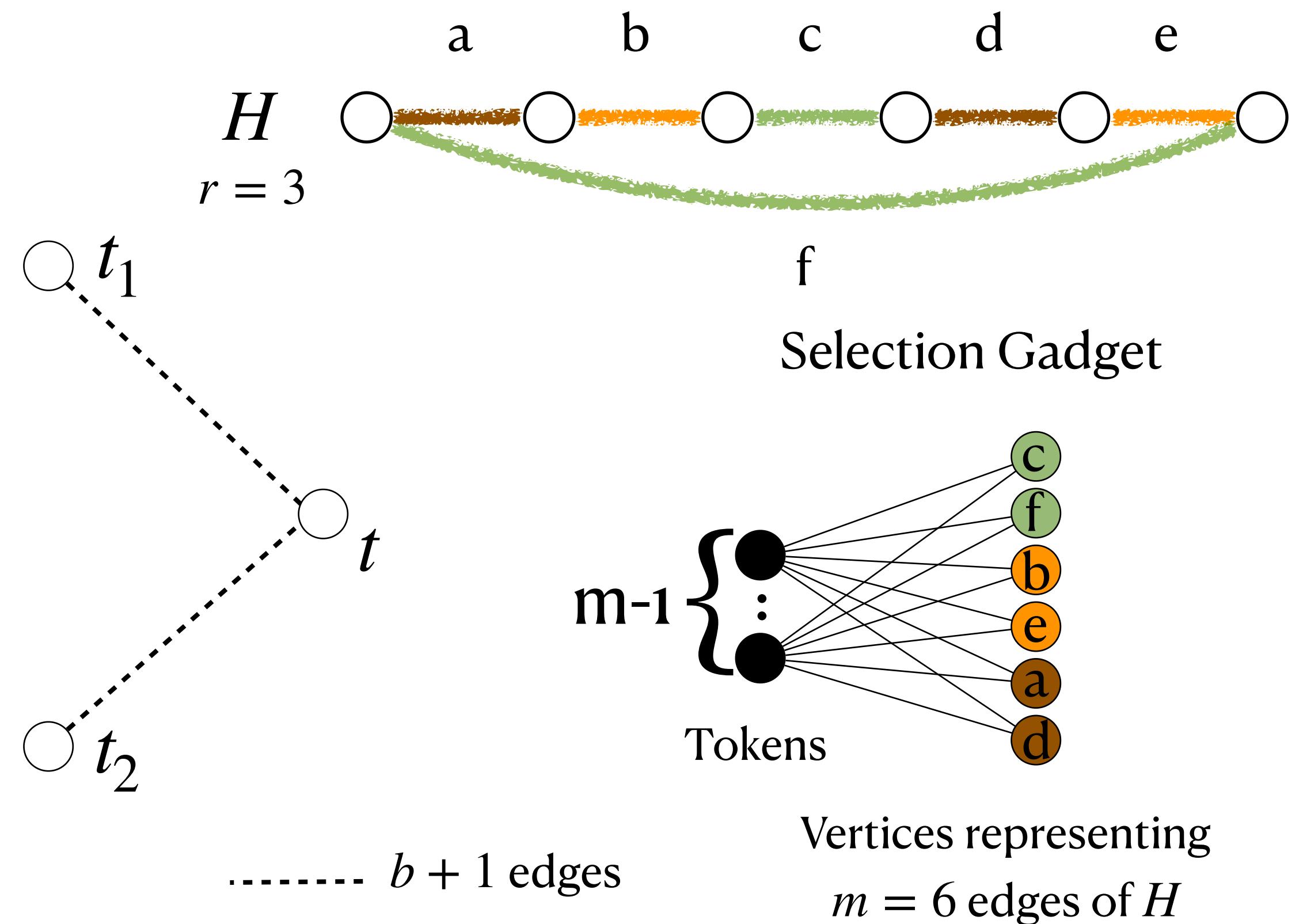
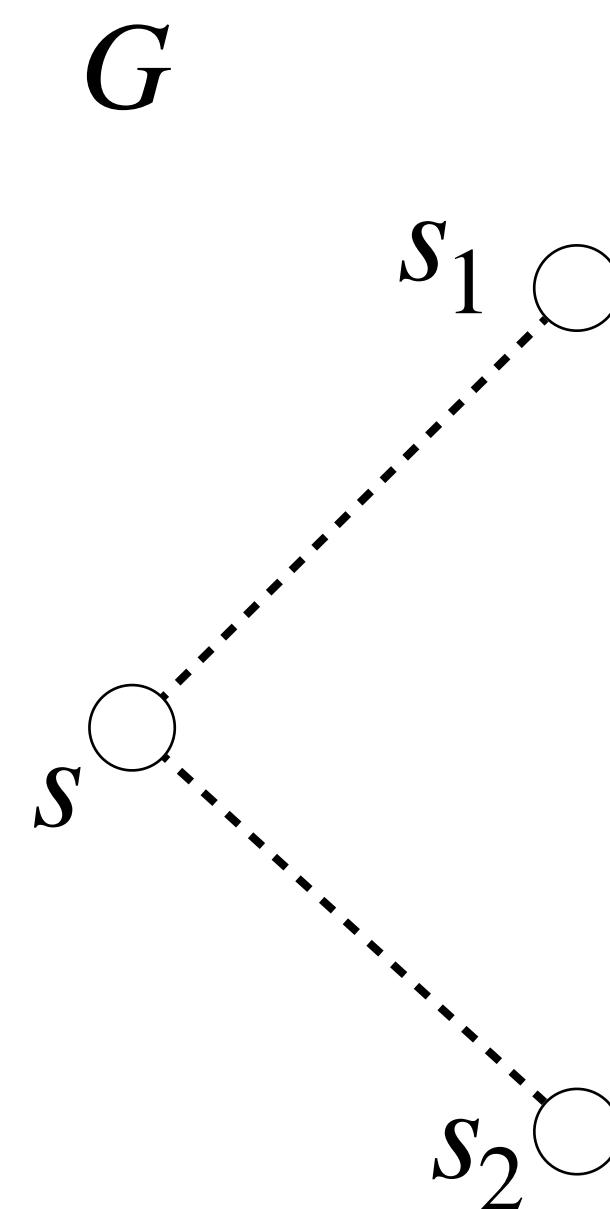
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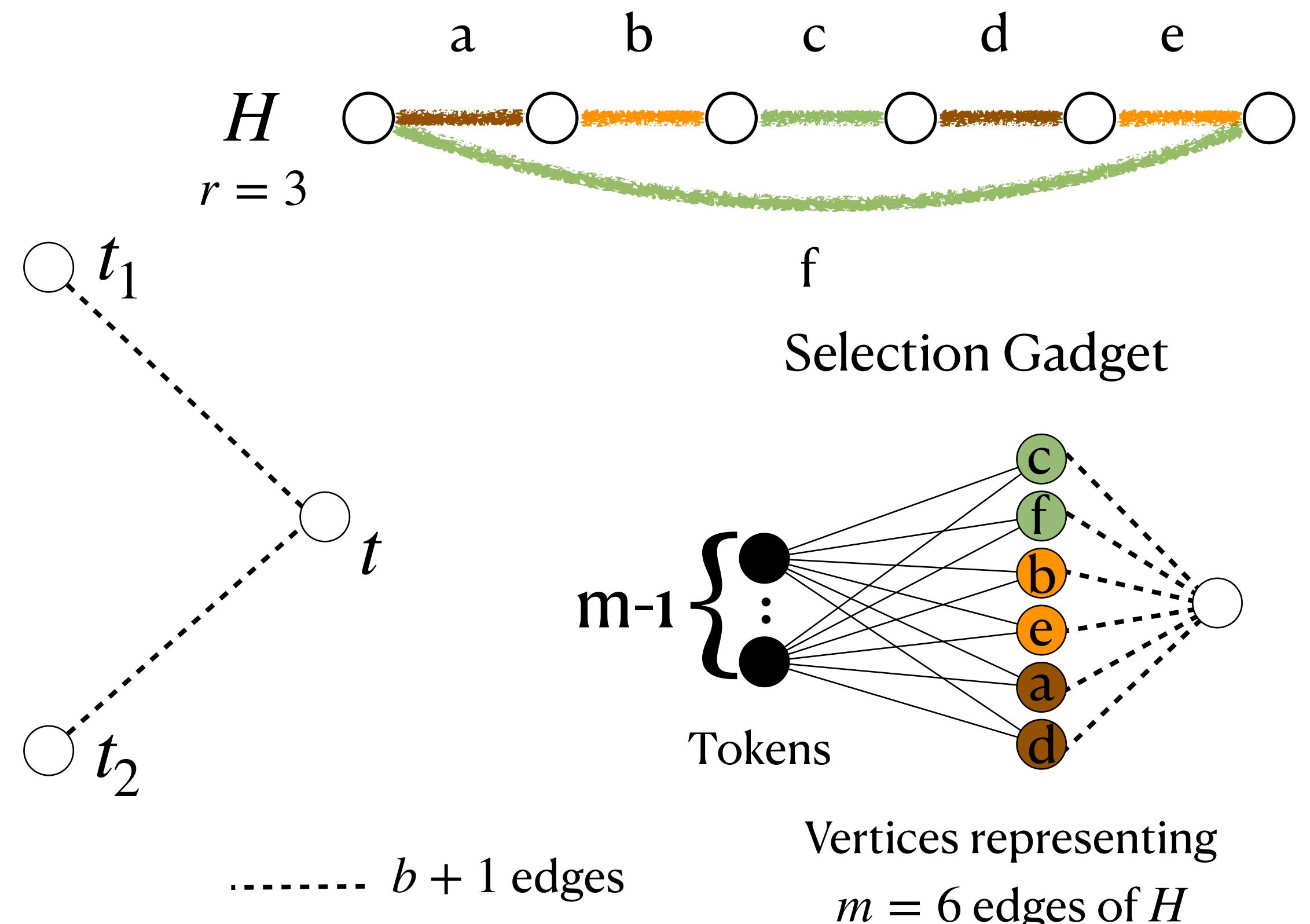
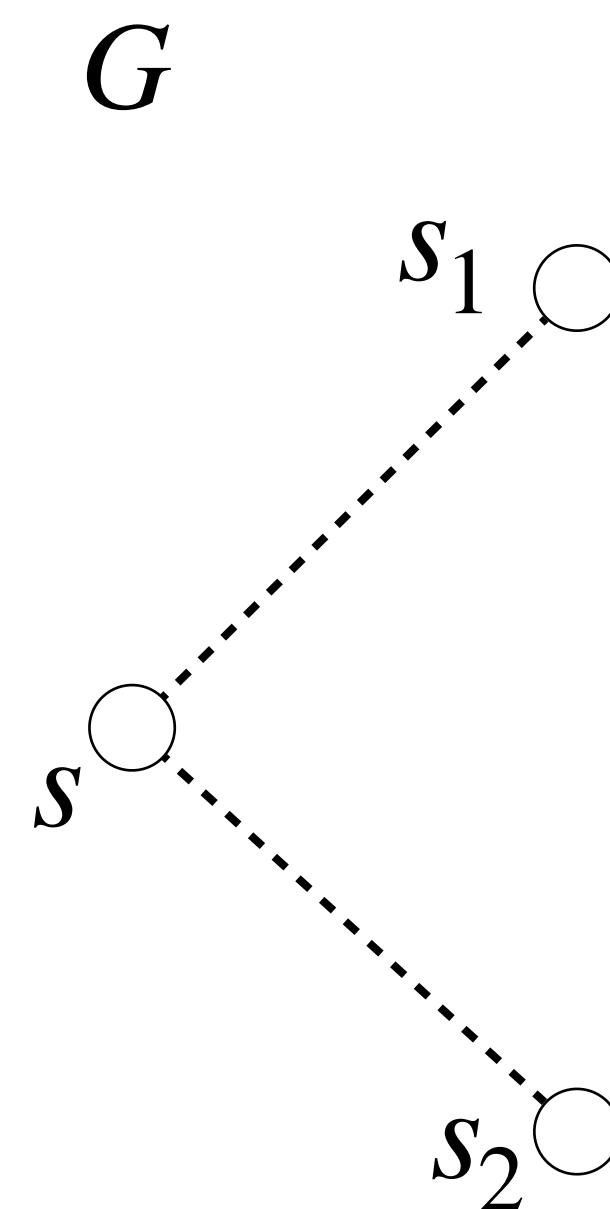
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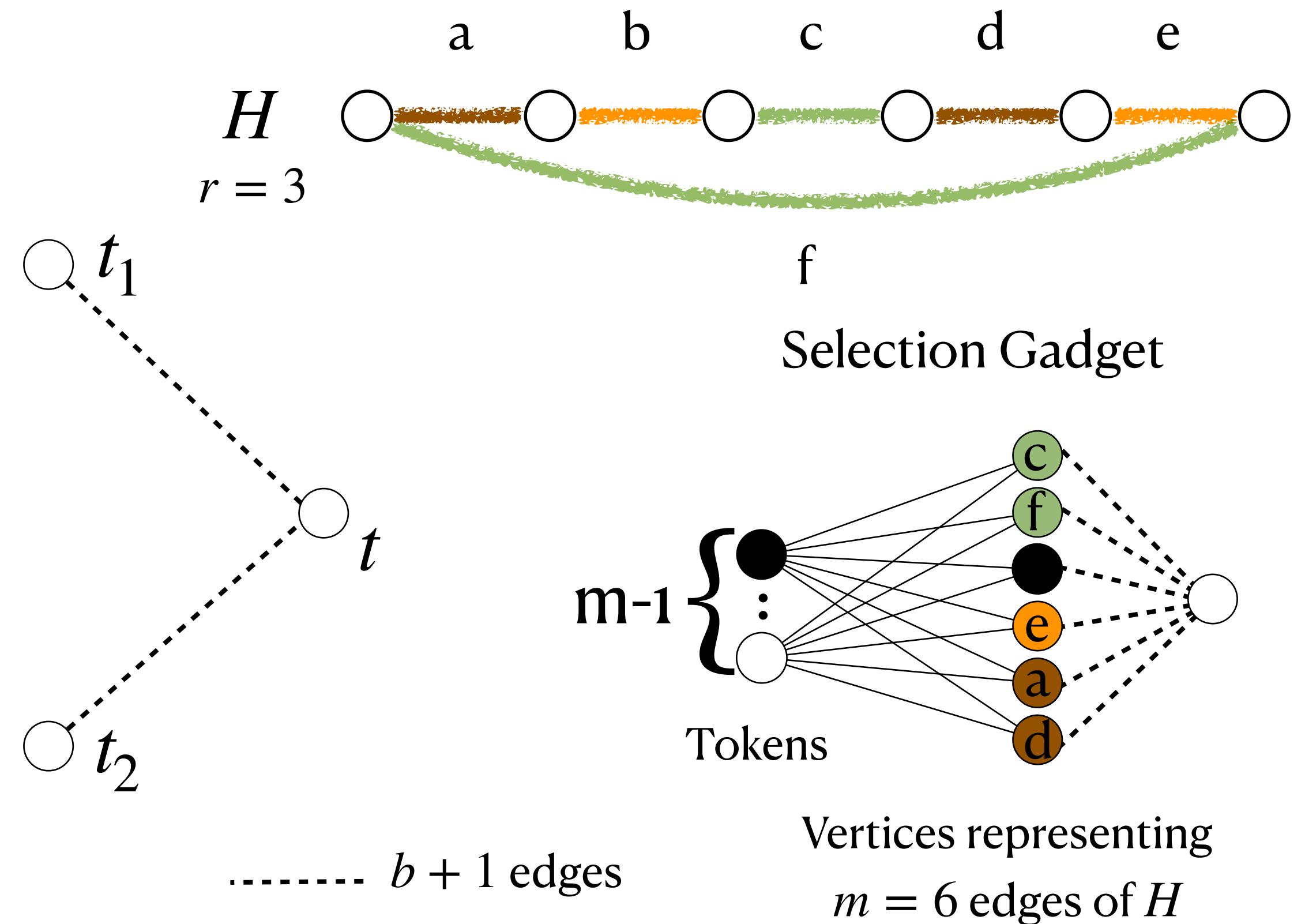
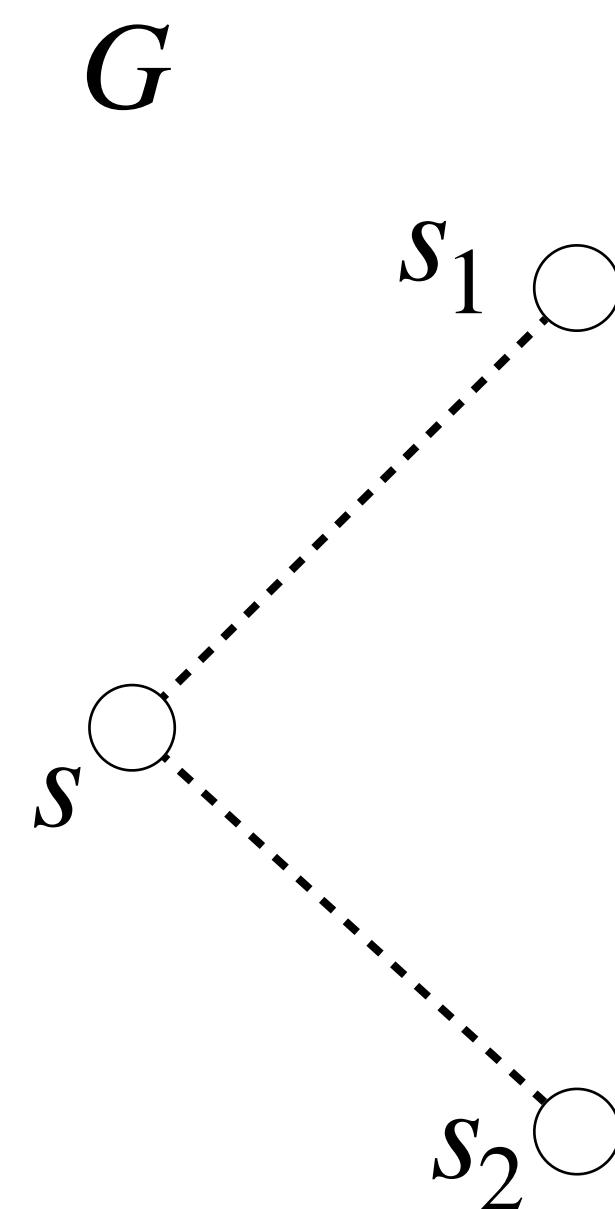
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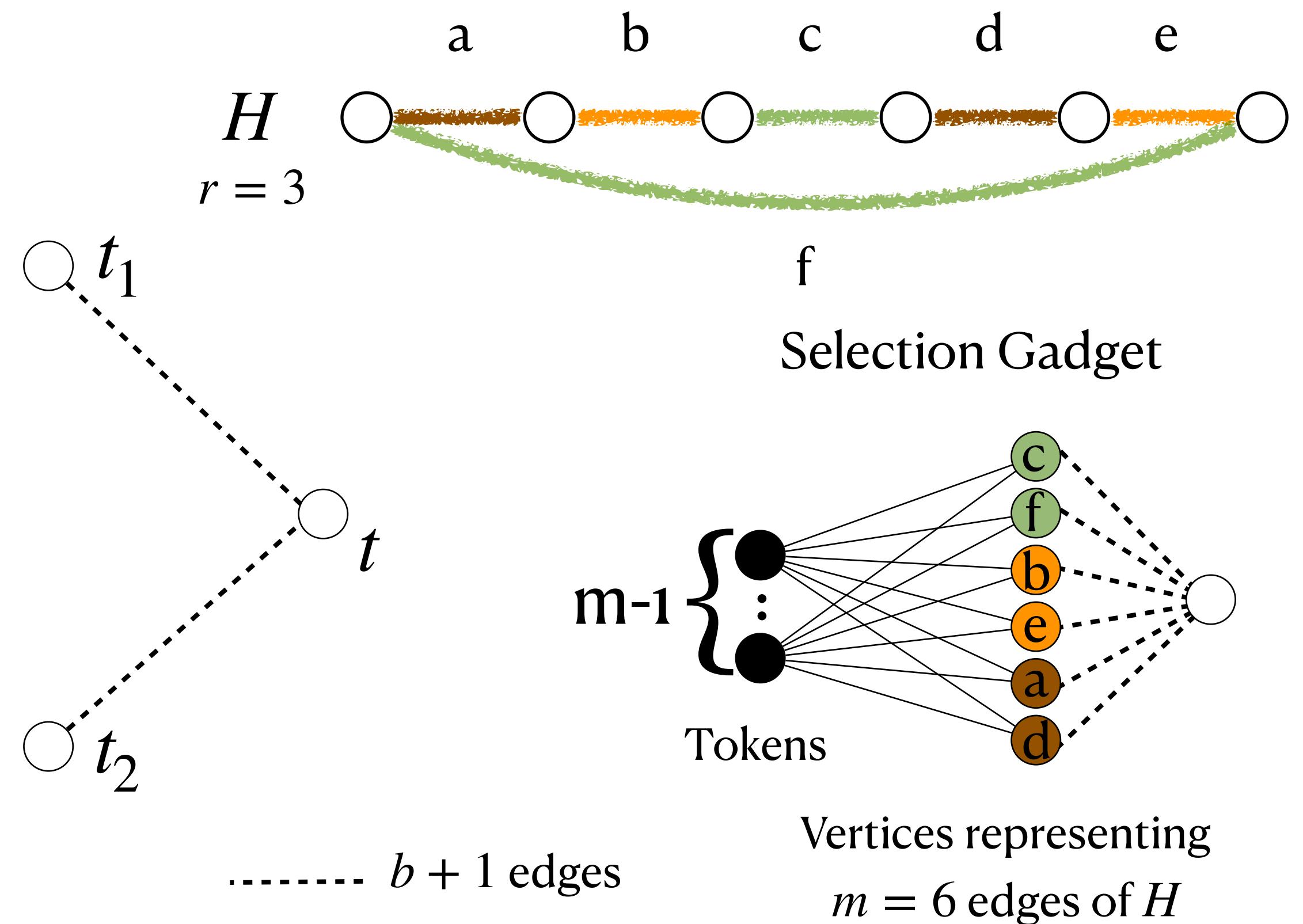
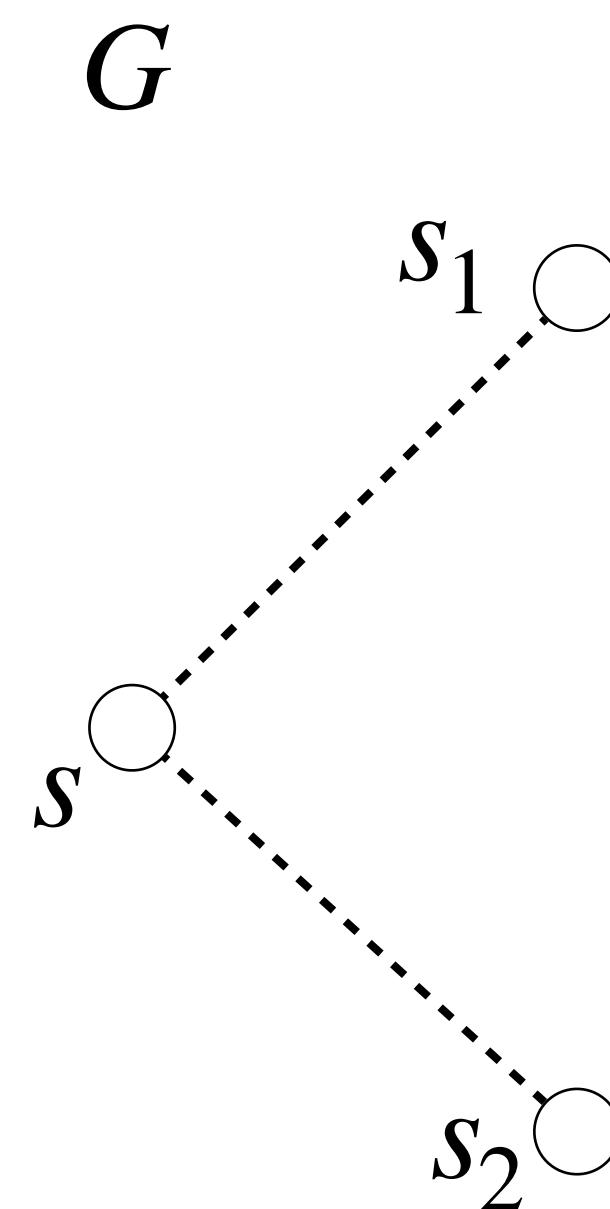
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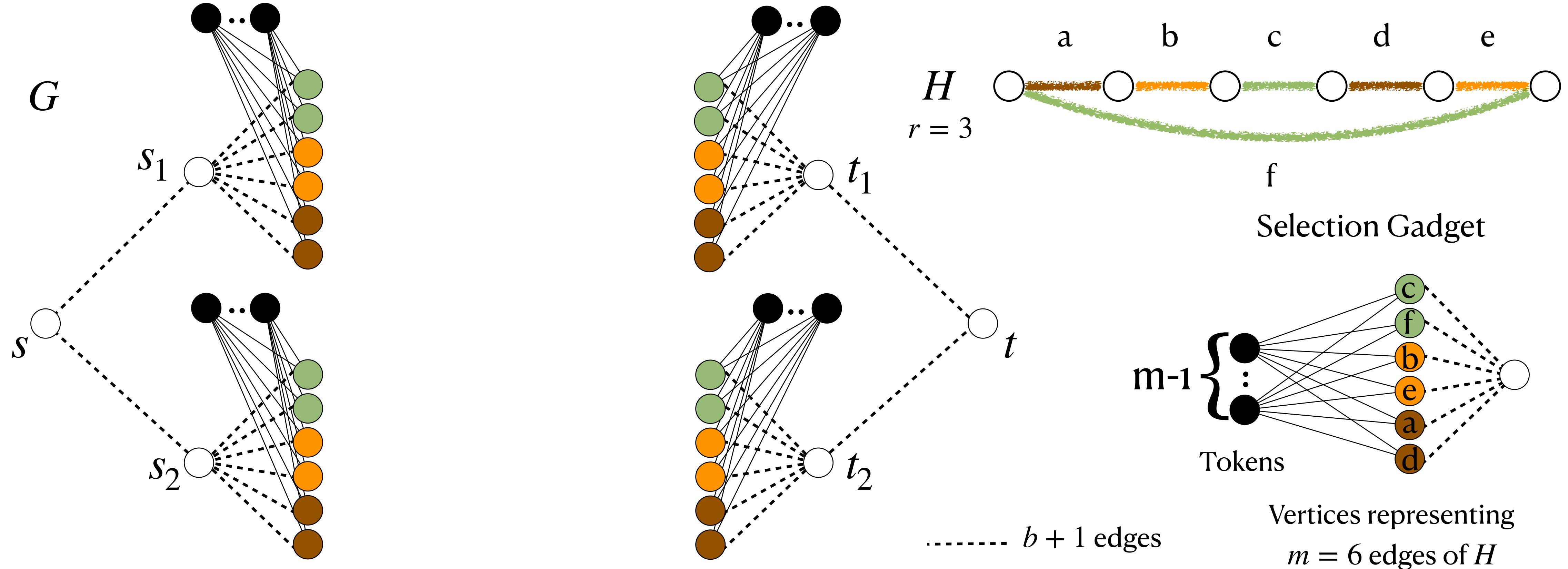
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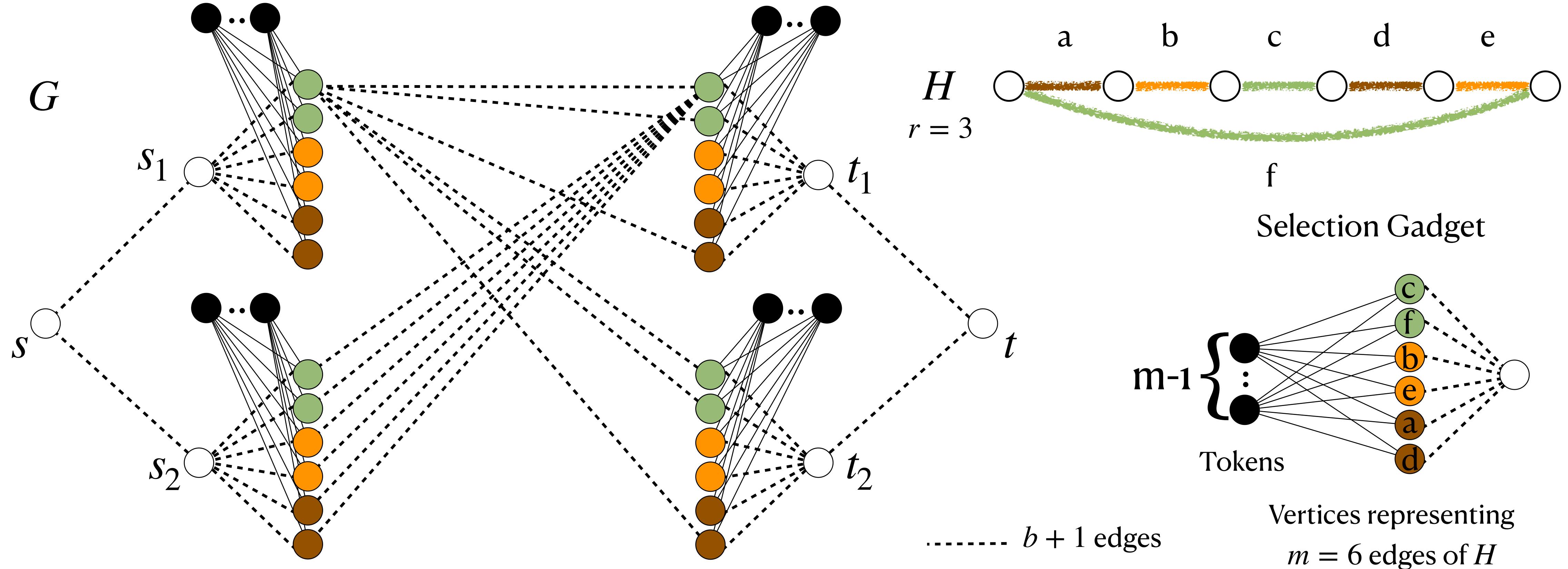
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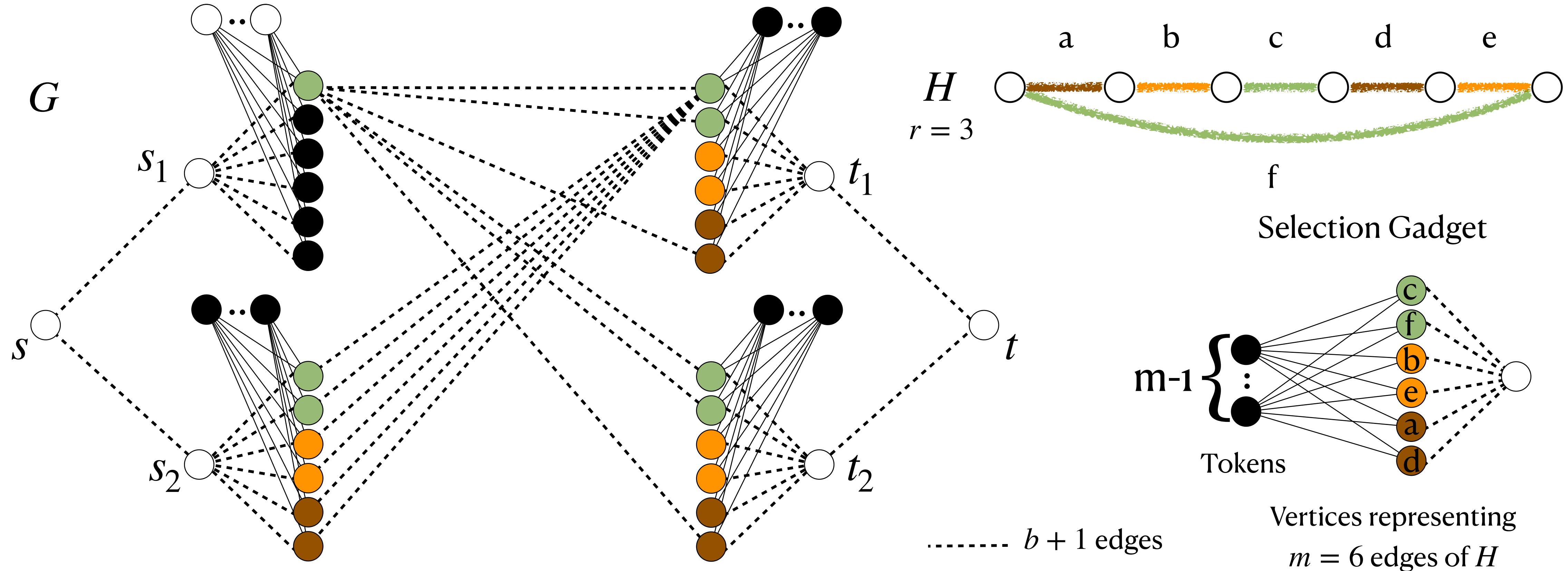
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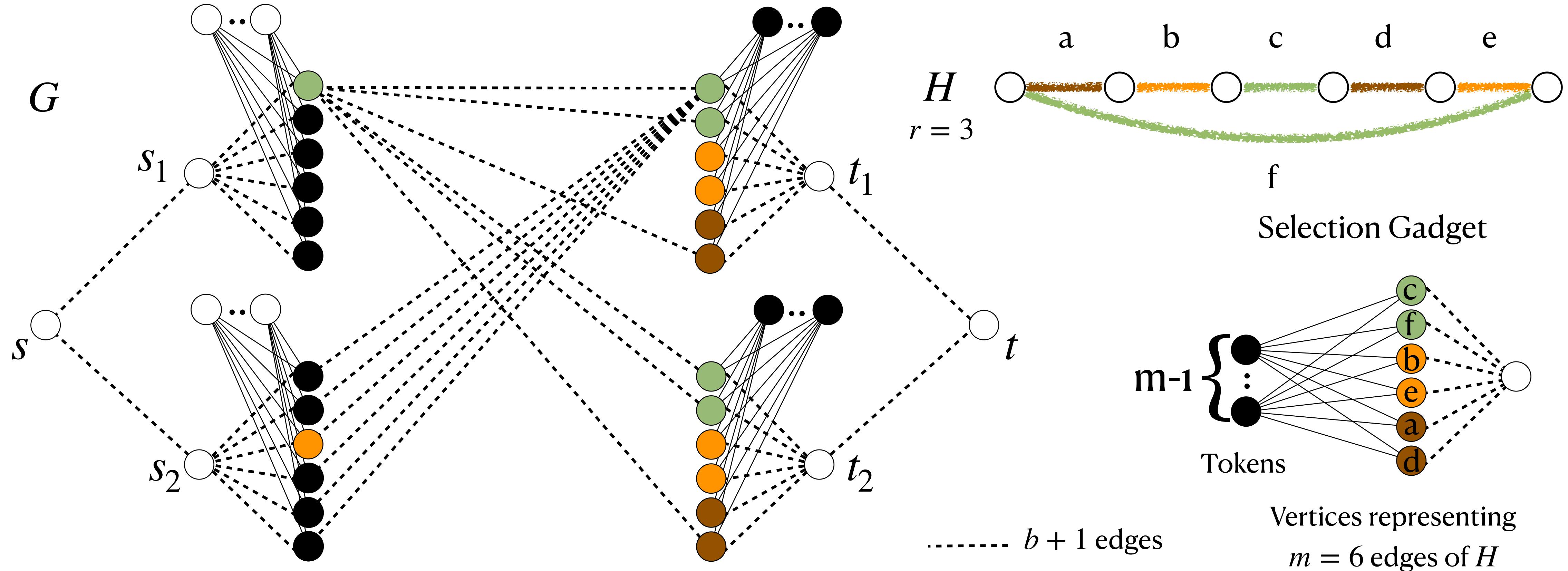
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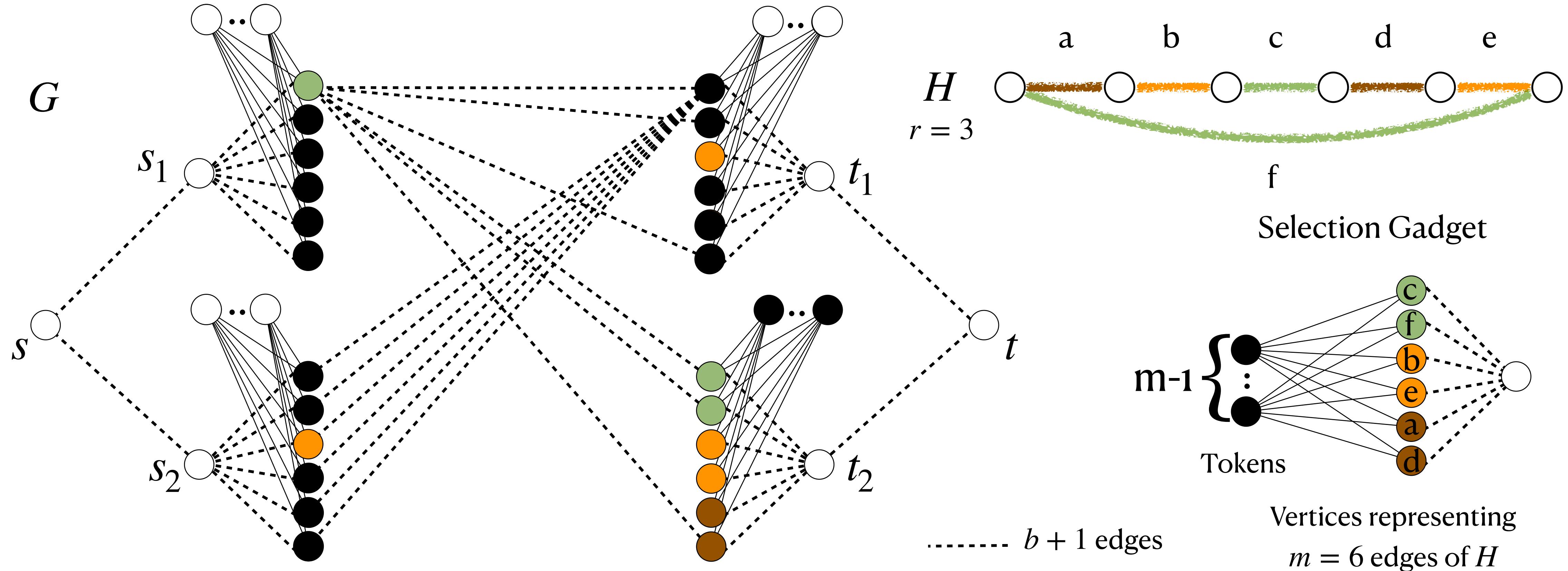
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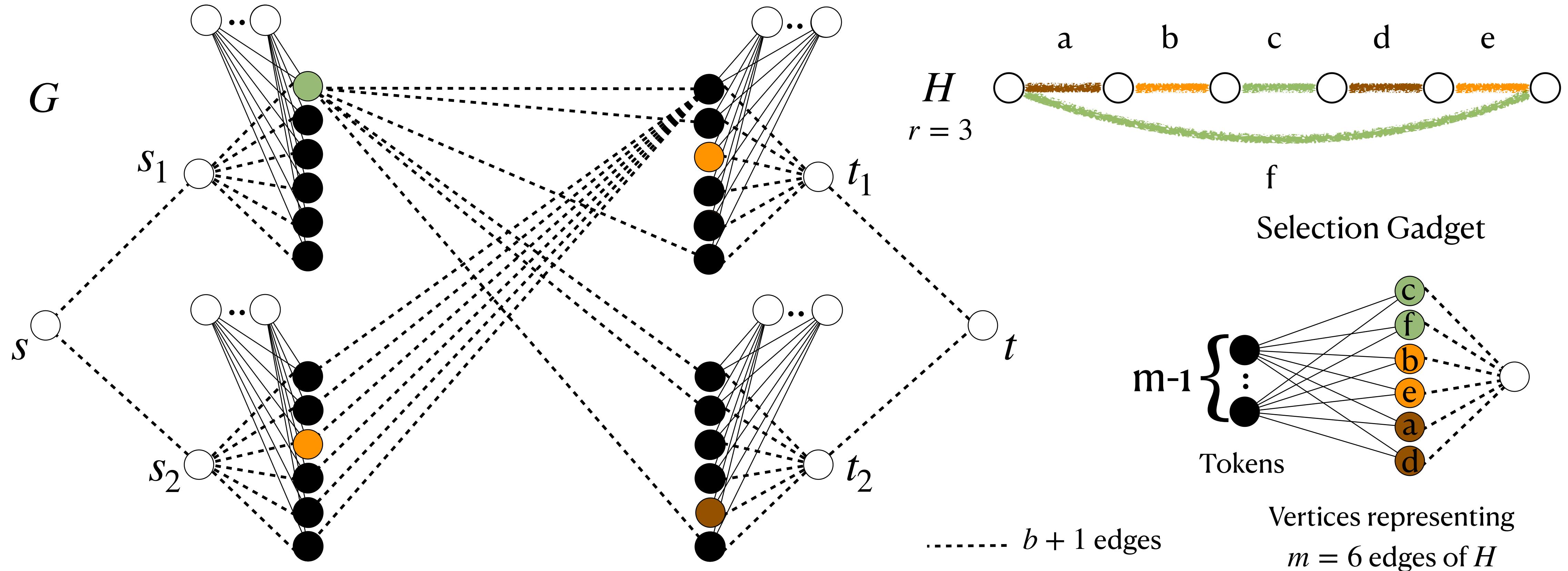
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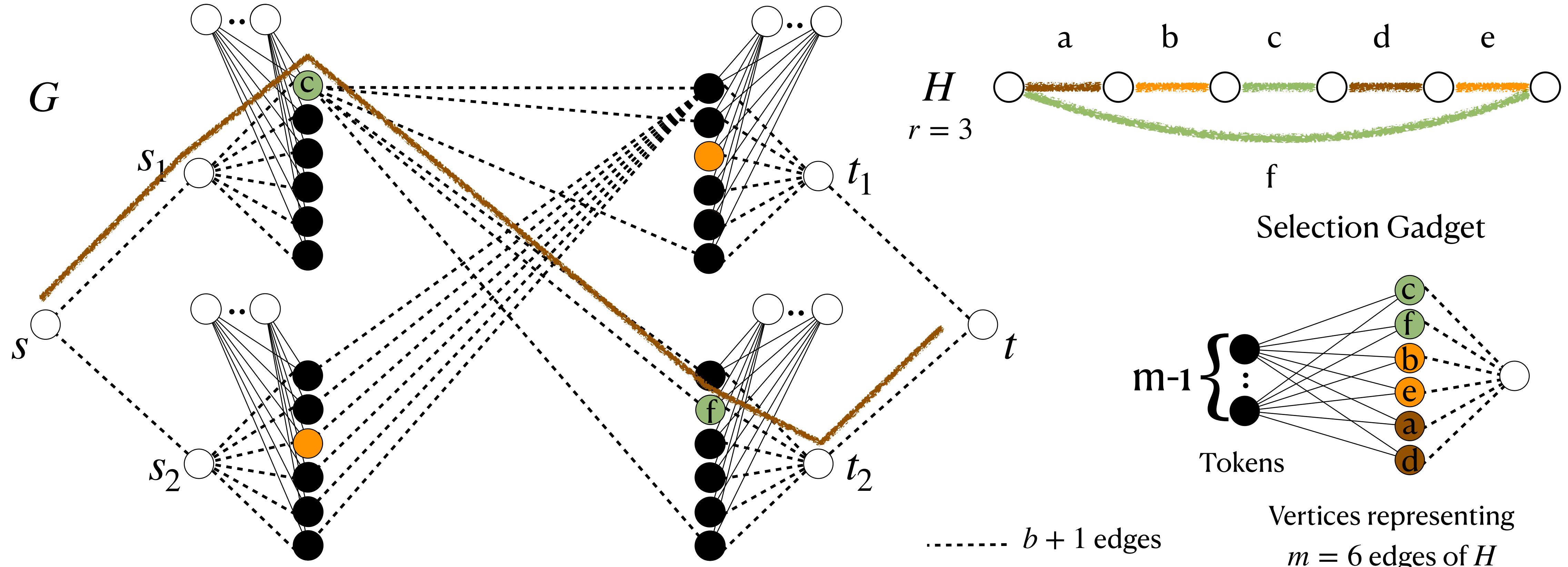
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- If a cut can be reached in fewer than b token slides, the vertices that remain free in the gadgets represent the edges of the rainbow matching (and vice versa).

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Naomi Nishimura



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Thank you.

Mario Grobler



Amer E. Mouawad



Sebastian Siebertz

